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Objective oriented design of a CUBE cable - based parallel robot for arm rehabilitation tasks

with Authors: Fouad Inel, Mohammed Khadem ,Abd Ghafour Slimane Tich Tich I would like to thank all the reviewers for their thoughtful comments and efforts towards improving our manuscript. We revised the manuscript with special attention to the comments that we received from **Three** (3) reviewers that were experts, specialists in the area of my paper.

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