

Positive Periodic Solutions in Shifts δ_{\pm} for a Neutral Delay Logistic Equation on Time Scales

LILI WANG

Anyang Normal University
School of mathematics and statistics
Xian'gedadao Road 436, 455000 Anyang
CHINA
ay_wanglili@126.com

MENG HU

Anyang Normal University
School of mathematics and statistics
Xian'gedadao Road 436, 455000 Anyang
CHINA
humeng2001@126.com

Abstract: Let $\mathbb{T} \subset \mathbb{R}$ be a periodic time scale in shifts δ_{\pm} with period $P \in (t_0, \infty)_{\mathbb{T}}$ and $t_0 \in \mathbb{T}$ is nonnegative and fixed. By using a fixed point theorem of strict-set-contraction, some criteria are established for the existence of positive periodic solutions in shifts δ_{\pm} for a neutral delay logistic equation on time scales of the form

$$x^{\Delta}(t) = x(t) \left[r(t) - a(t)x(t) - \sum_{j=1}^n b_j(t)x(\delta_{-}(\tau_j, t)) - \sum_{j=1}^n c_j(t)x^{\Delta}(\delta_{-}(\xi_j, t)) \right], t \in \mathbb{T}.$$

Finally, two numerical examples are presented to illustrate the feasibility and effectiveness of the results.

Key-Words: Positive periodic solution; Neutral delay logistic equation; Strict-set-contraction; Shift operator; Time scale.

1 Introduction

In 1993, Kuang [1] proposed an open problem (open problem 9.2) to obtain sufficient conditions for the existence of positive periodic solutions to

$$x'(t) = x(t) [a(t) - \beta(t)x(t) - b(t)x(t - \tau(t)) - c(t)x'(t - \tau(t))],$$

where a, β, b, c, τ are nonnegative continuous periodic functions. Since then, different classes of neutral functional differential and difference equations have been extensively studied; see, for example, [2-5].

However, in the natural world, there are many species whose developing processes are both continuous and discrete. Hence, using the only differential equation or difference equation can't accurately describe the law of their developments, see, for example, [6,7]. Therefore, there is a need to establish correspondent dynamic models on new time scales.

The theory of calculus on time scales (see [8] and references cited therein) was initiated by Stefan Hilger [9] in order to unify continuous and discrete analysis. Therefore, the study of dynamic equations on time scales, which unifies differential, difference, h -difference, and q -differences equations and more, has received much attention; see [10-14].

The existence problem of periodic solutions is an important topic in qualitative analysis of functional

dynamic equations. Up to now, there are only a few results concerning periodic solutions of neutral dynamic equations on time scales; see, for example, [15,16]. In these papers, authors considered the existence of periodic solutions for dynamic equations on time scales satisfying the condition "there exists a $\omega > 0$ such that $t \pm \omega \in \mathbb{T}, \forall t \in \mathbb{T}$." Under this condition all periodic time scales are unbounded above and below. However, there are many time scales such as $\overline{q^{\mathbb{Z}}} = \{q^n : n \in \mathbb{Z}\} \cup \{0\}$ and $\sqrt{\mathbb{N}} = \{\sqrt{n} : n \in \mathbb{N}\}$ which do not satisfy the condition. Adivar and Raf-foul introduced a new periodicity concept on time scales which does not oblige the time scale to be closed under the operation $t \pm \omega$ for a fixed $\omega > 0$. They defined a new periodicity concept with the aid of shift operators δ_{\pm} which are first defined in [17] and then generalized in [18].

Recently, by using the cone theory techniques, many researchers studied the existence of positive periodic solutions in shifts δ_{\pm} for some nonlinear first-order functional dynamic equations on time scales; see [19-22]. However, to the best of our knowledge, there are few papers published on the existence of positive periodic solutions in shifts δ_{\pm} for a neutral functional differential equation on time scales.

The main purpose of this paper is by using a fixed point theorem of strict-set-contraction to establish some criteria to guarantee the existence of pos-

itive periodic solutions in shifts δ_{\pm} of the following neutral delay logistic equation on time scales

$$x^{\Delta}(t) = x(t) \left[r(t) - a(t)x(t) - \sum_{j=1}^n b_j(t)x(\delta_-(\tau_j, t)) - \sum_{j=1}^n c_j(t)x^{\Delta}(\delta_-(\xi_j, t)) \right], \quad (1)$$

where $t \in \mathbb{T}$, $\mathbb{T} \subset \mathbb{R}$ be a periodic time scale in shifts δ_{\pm} with period $P \in [t_0, \infty)_{\mathbb{T}}$ and $t_0 \in \mathbb{T}$ is non-negative and fixed; $r, a, b_j, c_j \in C(\mathbb{T}, (0, \infty))$ ($j = 1, 2, \dots, n$) are Δ -periodic in shifts δ_{\pm} with period ω ; τ_j, ξ_j ($j = 1, 2, \dots, n$) are fixed if $\mathbb{T} = \mathbb{R}$ and $\tau_j, \xi_j \in [P, \infty)_{\mathbb{T}}$ if \mathbb{T} is periodic in shifts δ_{\pm} with period P .

For convenience, we introduce the notation

$$\Theta := e_r(t_0, \delta_+^{\omega}(t_0)),$$

$$\Gamma := \int_{t_0}^{\delta_+^{\omega}(t_0)} \left[\Theta a(s) + \sum_{j=1}^n \Theta b_j(s) - \sum_{j=1}^n c_j(s) \right] \Delta s,$$

$$\Pi := \int_{t_0}^{\delta_+^{\omega}(t_0)} \left[a(s) + \sum_{j=1}^n b_j(s) + \sum_{j=1}^n c_j(s) \right] \Delta s,$$

and

$$f^M = \sup_{t \in [t_0, \delta_+^{\omega}(t_0)]_{\mathbb{T}}} f(t), \quad f^m = \inf_{t \in [t_0, \delta_+^{\omega}(t_0)]_{\mathbb{T}}} f(t),$$

where f is a continuous ω -periodic function in shifts δ_{\pm} .

Throughout this paper, we assume that

$$(H_1) \quad \Theta := e_r(t_0, \delta_+^{\omega}(t_0)) < 1;$$

$$(H_2) \quad \Theta a(t) + \sum_{j=1}^n \Theta b_j(t) - \sum_{j=1}^n c_j(t) \geq 0;$$

$$(H_3) \quad (1 + r^m) \frac{\Theta^2 \Gamma}{1 - \Theta} \geq \sup_{t \in [t_0, \delta_+^{\omega}(t_0)]_{\mathbb{T}}} \left\{ a(t) + \sum_{j=1}^n b_j(t) + \sum_{j=1}^n c_j(t) \right\};$$

$$(H_4) \quad \frac{\Pi(r^M - 1)}{\Theta(1 - \Theta)} \leq \inf_{t \in [t_0, \delta_+^{\omega}(t_0)]_{\mathbb{T}}} \left\{ \Theta a(t) + \sum_{j=1}^n \Theta b_j(t) - \sum_{j=1}^n c_j(t) \right\};$$

$$(H_5) \quad \frac{1 - \Theta}{\Theta^2 \Gamma} \sum_{j=1}^n c_j^M < 1.$$

2 Preliminaries

Let \mathbb{T} be a nonempty closed subset (time scale) of \mathbb{R} . The forward and backward jump operators $\sigma, \rho : \mathbb{T} \rightarrow \mathbb{T}$ and the graininess $\mu : \mathbb{T} \rightarrow \mathbb{R}^+$ are defined, respectively, by

$$\sigma(t) = \inf\{s \in \mathbb{T} : s > t\},$$

$$\rho(t) = \sup\{s \in \mathbb{T} : s < t\}$$

$$\mu(t) = \sigma(t) - t.$$

A point $t \in \mathbb{T}$ is called left-dense if $t > \inf \mathbb{T}$ and $\rho(t) = t$, left-scattered if $\rho(t) < t$, right-dense if $t < \sup \mathbb{T}$ and $\sigma(t) = t$, and right-scattered if $\sigma(t) > t$. If \mathbb{T} has a left-scattered maximum m , then $\mathbb{T}^k = \mathbb{T} \setminus \{m\}$; otherwise $\mathbb{T}^k = \mathbb{T}$. If \mathbb{T} has a right-scattered minimum m , then $\mathbb{T}_k = \mathbb{T} \setminus \{m\}$; otherwise $\mathbb{T}_k = \mathbb{T}$.

A function $f : \mathbb{T} \rightarrow \mathbb{R}$ is right-dense continuous provided it is continuous at right-dense point in \mathbb{T} and its left-side limits exist at left-dense points in \mathbb{T} . If f is continuous at each right-dense point and each left-dense point, then f is said to be a continuous function on \mathbb{T} . The set of continuous functions $f : \mathbb{T} \rightarrow \mathbb{R}$ is denoted by $C(\mathbb{T}) = C(\mathbb{T}, \mathbb{R})$. The set of functions $f : \mathbb{T} \rightarrow \mathbb{R}$ that are differentiable and whose derivative is continuous is denoted by $C^1(\mathbb{T}) = C^1(\mathbb{T}, \mathbb{R})$.

For the basic theories of calculus on time scales, see [8].

A function $p : \mathbb{T} \rightarrow \mathbb{R}$ is called regressive provided $1 + \mu(t)p(t) \neq 0$ for all $t \in \mathbb{T}^k$. The set of all regressive and rd-continuous functions $p : \mathbb{T} \rightarrow \mathbb{R}$ is denoted by $\mathcal{R} = \mathcal{R}(\mathbb{T}, \mathbb{R})$. If r is a regressive function, then the generalized exponential function e_r is defined by

$$e_r(t, s) = \exp \left\{ \int_s^t \xi_{\mu(\tau)}(r(\tau)) \Delta \tau \right\}$$

for all $s, t \in \mathbb{T}$, with the cylinder transformation

$$\xi_h(z) = \begin{cases} \frac{\text{Log}(1+hz)}{h} & \text{if } h \neq 0, \\ z & \text{if } h = 0. \end{cases}$$

Let $p, q : \mathbb{T} \rightarrow \mathbb{R}$ be two regressive functions, define

$$p \oplus q = p + q + \mu p q, \quad \ominus p = -\frac{p}{1 + \mu p}, \quad p \ominus q = p \oplus (\ominus q).$$

Lemma 1. [8] Assume that $p, q : \mathbb{T} \rightarrow \mathbb{R}$ be two regressive functions, then

- (i) $e_0(t, s) \equiv 1$ and $e_p(t, t) \equiv 1$;
- (ii) $e_p(\sigma(t), s) = (1 + \mu(t)p(t))e_p(t, s)$;
- (iii) $e_p(t, s) = \frac{1}{e_p(s, t)} = e_{\ominus p}(s, t)$;
- (iv) $e_p(t, s)e_p(s, r) = e_p(t, r)$;
- (v) $(e_{\ominus p}(t, s))^{\Delta} = (\ominus p)(t)e_{\ominus p}(t, s)$.

The following definitions, lemmas about the shift operators and the new periodicity concept for time scales which can be found in [20,23].

Let \mathbb{T}^* be a non-empty subset of the time scale \mathbb{T} and $t_0 \in \mathbb{T}^*$ be a fixed number, define operators $\delta_{\pm} : [t_0, \infty) \times \mathbb{T}^* \rightarrow \mathbb{T}^*$. The operators δ_+ and δ_- associated with $t_0 \in \mathbb{T}^*$ (called the initial point) are said to be forward and backward shift operators on the set \mathbb{T}^* , respectively. The variable $s \in [t_0, \infty)_{\mathbb{T}}$ in $\delta_{\pm}(s, t)$ is called the shift size. The value $\delta_+(s, t)$ and $\delta_-(s, t)$ in \mathbb{T}^* indicate s units translation of the term $t \in \mathbb{T}^*$ to the right and left, respectively. The sets

$$\mathbb{D}_{\pm} := \{(s, t) \in [t_0, \infty)_{\mathbb{T}} \times \mathbb{T}^* : \delta_{\mp}(s, t) \in \mathbb{T}^*\}$$

are the domains of the shift operator δ_{\pm} , respectively. Hereafter, \mathbb{T}^* is the largest subset of the time scale \mathbb{T} such that the shift operators $\delta_{\pm} : [t_0, \infty) \times \mathbb{T}^* \rightarrow \mathbb{T}^*$ exist.

Definition 2. [23] (Periodicity in shifts δ_{\pm}) Let \mathbb{T} be a time scale with the shift operators δ_{\pm} associated with the initial point $t_0 \in \mathbb{T}^*$. The time scale \mathbb{T} is said to be periodic in shifts δ_{\pm} if there exists $p \in (t_0, \infty)_{\mathbb{T}^*}$ such that $(p, t) \in \mathbb{D}_{\pm}$ for all $t \in \mathbb{T}^*$. Furthermore, if

$$P := \inf\{p \in (t_0, \infty)_{\mathbb{T}^*} : (p, t) \in \mathbb{D}_{\pm}, \forall t \in \mathbb{T}^*\} \neq t_0,$$

then P is called the period of the time scale \mathbb{T} .

Definition 3. [23] (Periodic function in shifts δ_{\pm}) Let \mathbb{T} be a time scale that is periodic in shifts δ_{\pm} with the period P . We say that a real-valued function f defined on \mathbb{T}^* is periodic in shifts δ_{\pm} if there exists $\omega \in [P, \infty)_{\mathbb{T}^*}$ such that $(\omega, t) \in \mathbb{D}_{\pm}$ and $f(\delta_{\pm}^{\omega}(t)) = f(t)$ for all $t \in \mathbb{T}^*$, where $\delta_{\pm}^{\omega} := \delta_{\pm}(\omega, t)$. The smallest number $\omega \in [P, \infty)_{\mathbb{T}^*}$ is called the period of f .

Definition 4. [23] (Δ -periodic function in shifts δ_{\pm}) Let \mathbb{T} be a time scale that is periodic in shifts δ_{\pm} with the period P . We say that a real-valued function f defined on \mathbb{T}^* is Δ -periodic in shifts δ_{\pm} if there exists $\omega \in [P, \infty)_{\mathbb{T}^*}$ such that $(\omega, t) \in \mathbb{D}_{\pm}$ for all $t \in \mathbb{T}^*$, the shifts δ_{\pm}^{ω} are Δ -differentiable with rd-continuous derivatives and $f(\delta_{\pm}^{\omega}(t))\delta_{\pm}^{\Delta\omega}(t) = f(t)$ for all $t \in \mathbb{T}^*$, where $\delta_{\pm}^{\omega} := \delta_{\pm}(\omega, t)$. The smallest number $\omega \in [P, \infty)_{\mathbb{T}^*}$ is called the period of f .

Lemma 5. [23] $\delta_+^{\omega}(\sigma(t)) = \sigma(\delta_+^{\omega}(t))$ and $\delta_-^{\omega}(\sigma(t)) = \sigma(\delta_-^{\omega}(t))$ for all $t \in \mathbb{T}^*$.

Lemma 6. [20] Let \mathbb{T} be a time scale that is periodic in shifts δ_{\pm} with the period P . Suppose that the shifts δ_{\pm}^{ω} are Δ -differentiable on $t \in \mathbb{T}^*$ where $\omega \in [P, \infty)_{\mathbb{T}^*}$ and $p \in \mathcal{R}$ is Δ -periodic in shifts δ_{\pm} with the period ω . Then

$$(i) e_p(\delta_{\pm}^{\omega}(t), \delta_{\pm}^{\omega}(t_0)) = e_p(t, t_0) \text{ for } t, t_0 \in \mathbb{T}^*;$$

$$(ii) e_p(\delta_{\pm}^{\omega}(t), \sigma(\delta_{\pm}^{\omega}(s))) = e_p(t, \sigma(s)) = \frac{e_p(t, s)}{1 + \mu(t)p(t)} \text{ for } t, s \in \mathbb{T}^*.$$

Lemma 7. [23] Let \mathbb{T} be a time scale that is periodic in shifts δ_{\pm} with the period P , and let f be a Δ -periodic function in shifts δ_{\pm} with the period $\omega \in [P, \infty)_{\mathbb{T}^*}$. Suppose that $f \in C_{rd}(\mathbb{T})$, then

$$\int_{t_0}^t f(s)\Delta s = \int_{\delta_{\pm}^{\omega}(t_0)}^{\delta_{\pm}^{\omega}(t)} f(s)\Delta s.$$

Lemma 8. [8] Suppose that r is regressive and $f : \mathbb{T} \rightarrow \mathbb{R}$ is rd-continuous. Let $t_0 \in \mathbb{T}$, $y_0 \in \mathbb{R}$, then the unique solution of the initial value problem

$$y^{\Delta} = r(t)y + f(t), y(t_0) = y_0$$

is given by

$$y(t) = e_r(t, t_0)y_0 + \int_{t_0}^t e_r(t, \sigma(\tau))f(\tau)\Delta\tau.$$

Set

$$C_{\omega}^0 = \{x : x \in C(\mathbb{T}, \mathbb{R}), x(\delta_+^{\omega}(t)) = x(t)\}$$

with the norm defined by $|x|_0 = \sup_{t \in [t_0, \delta_+^{\omega}(t_0)]_{\mathbb{T}}} |x(t)|$,

and

$$C_{\omega}^1 = \{x : x \in C^1(\mathbb{T}, \mathbb{R}), x(\delta_+^{\omega}(t)) = x(t)\}$$

with the norm defined by $|x|_1 = \max\{|x|_0, |x^{\Delta}|_0\}$. Then C_{ω}^0 and C_{ω}^1 are all Banach spaces.

By using Lemmas 1, 5 and 8, we can obtain the following lemma.

Lemma 9. $x(t) \in C_{\omega}^1$ is an ω -periodic solution in shifts δ_{\pm} of system (1) if and only if $x(t)$ is an ω -periodic solution in shifts δ_{\pm} of

$$x(t) = \int_t^{\delta_+^{\omega}(t)} G(t, s)x(s) \left[a(s)x(s) + \sum_{j=1}^n b_j(s)x(\delta_-(\tau_j, s)) + \sum_{j=1}^n c_j(s)x^{\Delta}(\delta_-(\xi_j, s)) \right] \Delta s, \quad (2)$$

where

$$G(t, s) = \frac{e_r(t, \sigma(s))}{1 - e_r(t_0, \delta_+^{\omega}(t_0))}.$$

It is easy to verify that the Green's function $G(t, s)$ satisfies the property

$$\frac{\Theta}{1 - \Theta} \leq G(t, s) \leq \frac{1}{1 - \Theta}, \forall s \in [t, \delta_+^\omega(t)]_{\mathbb{T}}, \quad (3)$$

where $\Theta := e_r(t_0, \delta_+^\omega(t_0))$. By Lemma 6, we have

$$G(\delta_+^\omega(t), \delta_+^\omega(s)) = G(t, s), \quad (4)$$

where $t \in \mathbb{T}^*, s \in [t, \delta_+^\omega(t)]_{\mathbb{T}}$.

In order to obtain the existence of periodic solutions in shifts δ_\pm of system (1), we first make the following preparations:

Let E be a Banach space and K be a cone in E . The semi-order induced by the cone K is denoted by " \leq ", that is, $x \leq y$ if and only if $y - x \in K$. In addition, for a bounded subset $A \subset E$, let $\alpha_E(A)$ denote the (Kuratowski) measure of non-compactness defined by

$$\alpha_E(A) = \inf \{d > 0 : \text{there is a finite number of subsets } A_i \subset A, \text{ such that } A = \bigcup_i A_i \text{ and } \text{diam}(A_i) \leq d\},$$

where $\text{diam}(A_i)$ denotes the diameter of the set A_i .

Let E, F be two Banach spaces and $D \subset E$, a continuous and bounded map $\Phi : \Omega \rightarrow F$ is called k -set contractive if for any bounded set $S \subset D$ we have

$$\alpha_F(\Phi(S)) \leq k\alpha_E(S).$$

Φ is called strict-set-contractive if it is k -set-contractive for some $0 \leq k < 1$.

Lemma 10. [24, 25] *Let K be a cone of the real Banach space X and $K_{r,R} = \{x \in K | r \leq x \leq R\}$ with $R > r > 0$. Suppose that $\Phi : K_{r,R} \rightarrow K$ is strict-set-contractive such that one of the following two conditions is satisfied:*

- (i) $\Phi x \not\leq x, \forall x \in K, \|x\| = r$ and $\Phi x \not\geq x, \forall x \in K, \|x\| = R$.
- (ii) $\Phi x \not\geq x, \forall x \in K, \|x\| = r$ and $\Phi x \not\leq x, \forall x \in K, \|x\| = R$.

Then Φ has at least one fixed point in $K_{r,R}$.

Define K , a cone in C_ω^1 , by

$$K = \{x \in C_\omega^1 : x(t) \geq \Theta|x|_1, t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}\}, \quad (5)$$

and an operator $\Phi : K \rightarrow C_\omega^1$ by

$$\begin{aligned} (\Phi x)(t) &= \int_t^{\delta_+^\omega(t)} G(t, s)x(s) \left[a(s)x(s) \right. \\ &\quad \left. + \sum_{j=1}^n b_j(s)x(\delta_-(\tau_j, s)) \right] \Delta s \end{aligned}$$

$$+ \sum_{j=1}^n c_j(s)x^\Delta(\delta_-(\xi_j, s)) \Big] \Delta s. \quad (6)$$

In the following, we will give some lemmas concerning K and Φ defined by (5) and (6), respectively.

Lemma 11. *Assume that $(H_1) - (H_3)$ hold.*

- (i) *If $r^M \leq 1$, then $\Phi : K \rightarrow K$ is well defined.*
- (ii) *If (H_4) holds and $r^M > 1$, then $\Phi : K \rightarrow K$ is well defined.*

Proof. For any $x \in K$, it is clear that $\Phi x \in C^1(\mathbb{T}, \mathbb{R})$. In view of (6), for $t \in \mathbb{T}$, we obtain

$$\begin{aligned} &(\Phi x)(\delta_+^\omega(t)) \\ &= \int_{\delta_+^\omega(t)}^{\delta_+^\omega(\delta_+^\omega(t))} G(\delta_+^\omega(t), s)x(s) \left[a(s)x(s) \right. \\ &\quad \left. + \sum_{j=1}^n b_j(s)x(\delta_-(\tau_j, s)) \right. \\ &\quad \left. + \sum_{j=1}^n c_j(s)x^\Delta(\delta_-(\xi_j, s)) \right] \Delta s \\ &= \int_t^{\delta_+^\omega(t)} G(\delta_+^\omega(t), \delta_+^\omega(u))x(\delta_+^\omega(u)) \\ &\quad \times \left[a(\delta_+^\omega(u))\delta_+^{\Delta\omega}(u)x(\delta_+^\omega(u)) \right. \\ &\quad \left. + \sum_{j=1}^n b_j(\delta_+^\omega(u))\delta_+^{\Delta\omega}(u)x(\delta_-(\tau_j, \delta_+^\omega(u))) \right. \\ &\quad \left. + \sum_{j=1}^n c_j(\delta_+^\omega(u))\delta_+^{\Delta\omega}(u)x^\Delta(\delta_-(\xi_j, \delta_+^\omega(u))) \right] \Delta u \\ &= \int_t^{\delta_+^\omega(t)} G(t, u)x(u) \left[a(u)x(u) \right. \\ &\quad \left. + \sum_{j=1}^n b_j(u)x(\delta_-(\tau_j, u)) \right. \\ &\quad \left. + \sum_{j=1}^n c_j(u)x^\Delta(\delta_-(\xi_j, u)) \right] \Delta u \\ &= (\Phi x)(t), \end{aligned}$$

that is, $(\Phi x)(\delta_+^\omega(t)) = (\Phi x)(t), t \in \mathbb{T}$. So $\Phi x \in C_\omega^1$. In view of (H_2) , for $x \in K, t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$, we have

$$\begin{aligned} &a(t)x(t) + \sum_{j=1}^n b_j(t)x(\delta_-(\tau_j, t)) \\ &+ \sum_{j=1}^n c_j(t)x^\Delta(\delta_-(\xi_j, t)) \end{aligned}$$

$$\begin{aligned}
 &\geq a(t)x(t) + \sum_{j=1}^n b_j(t)x(\delta_-(\tau_j, t)) \\
 &\quad - \sum_{j=1}^n c_j(t)|x^\Delta(\delta_-(\xi_j, t))| \\
 &\geq \Theta a(t)|x^\Delta|_1 + \sum_{j=1}^n \Theta b_j(t)|x^\Delta|_1 \\
 &\quad - \sum_{j=1}^n c_j(t)|x^\Delta|_1 \\
 &= \left[\Theta a(t) + \sum_{j=1}^n \Theta b_j(t) - \sum_{j=1}^n c_j(t) \right] |x^\Delta|_1 \\
 &\geq 0. \tag{7}
 \end{aligned}$$

Therefore, for $x \in K, t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$, we find

$$\begin{aligned}
 |\Phi x|_0 &\leq \frac{1}{1-\Theta} \int_{t_0}^{\delta_+^\omega(t_0)} x(s) \left[a(s)x(s) \right. \\
 &\quad + \sum_{j=1}^n b_j(s)x(\delta_-(\tau_j, s)) \\
 &\quad \left. + \sum_{j=1}^n c_j(s)x^\Delta(\delta_-(\xi_j, s)) \right] \Delta s
 \end{aligned}$$

and

$$\begin{aligned}
 (\Phi x)(t) &\geq \frac{\Theta}{1-\Theta} \int_t^{\delta_+^\omega(t)} x(s) \left[a(s)x(s) \right. \\
 &\quad + \sum_{j=1}^n b_j(s)x(\delta_-(\tau_j, s)) \\
 &\quad \left. + \sum_{j=1}^n c_j(s)x^\Delta(\delta_-(\xi_j, s)) \right] \Delta s \\
 &= \frac{\Theta}{1-\Theta} \int_{t_0}^{\delta_+^\omega(t_0)} x(s) \left[a(s)x(s) \right. \\
 &\quad + \sum_{j=1}^n b_j(s)x(\delta_-(\tau_j, s)) \\
 &\quad \left. + \sum_{j=1}^n c_j(s)x^\Delta(\delta_-(\xi_j, s)) \right] \Delta s \\
 &\geq \Theta |\Phi x|_0. \tag{8}
 \end{aligned}$$

Now, we show that $(\Phi x)^\Delta(t) \geq \Theta |\Phi x|_1, t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$. From (6), we have

$$\begin{aligned}
 &(\Phi x)^\Delta(t) \\
 &= G(t, \delta_+^\omega(t))x(\delta_+^\omega(t)) \left[a(\delta_+^\omega(t))\delta_+^{\Delta\omega}(t)x(\delta_+^\omega(t)) \right.
 \end{aligned}$$

$$\begin{aligned}
 &\quad + \sum_{j=1}^n b_j(\delta_+^\omega(t))\delta_+^{\Delta\omega}(t)x(\delta_-(\tau_j, \delta_+^\omega(t))) \\
 &\quad \left. + \sum_{j=1}^n c_j(\delta_+^\omega(t))\delta_+^{\Delta\omega}(t)x^\Delta(\delta_-(\xi_j, \delta_+^\omega(t))) \right] \\
 &\quad - G(t, t)x(t) \left[a(t)x(t) + \sum_{j=1}^n b_j(t)x(\delta_-(\tau_j, t)) \right. \\
 &\quad \left. + \sum_{j=1}^n c_j(t)x^\Delta(\delta_-(\xi_j, t)) \right] + r(t)(\Phi x)(t) \\
 &= r(t)(\Phi x)(t) - x(t) \left[a(t)x(t) \right. \\
 &\quad + \sum_{j=1}^n b_j(t)x(\delta_-(\tau_j, t)) \\
 &\quad \left. + \sum_{j=1}^n c_j(t)x^\Delta(\delta_-(\xi_j, t)) \right]. \tag{9}
 \end{aligned}$$

It follows from (7) and (9) that if $(\Phi x)^\Delta(t) \geq 0$, then

$$(\Phi x)^\Delta(t) \leq r(t)(\Phi x)(t) \leq r^M(\Phi x)(t) \leq (\Phi x)(t). \tag{10}$$

On the other hand, from (8), (9) and (H_3) , if $(\Phi x)^\Delta(t) < 0$, then

$$\begin{aligned}
 &-(\Phi x)^\Delta(t) \\
 &= x(t) \left[a(t)x(t) + \sum_{j=1}^n b_j(t)x(\delta_-(\tau_j, t)) \right. \\
 &\quad \left. + \sum_{j=1}^n c_j(t)x^\Delta(\delta_-(\xi_j, t)) \right] - r(t)(\Phi x)(t) \\
 &\leq |x|_1^2 \left[a(t) + \sum_{j=1}^n b_j(t) + \sum_{j=1}^n c_j(t) \right] - r^m(\Phi x)(t) \\
 &\leq (1+r^m) \frac{\Theta^2}{1-\Theta} |x|_1^2 \int_{t_0}^{\delta_+^\omega(t_0)} \left[\Theta a(s) \right. \\
 &\quad \left. + \sum_{j=1}^n \Theta b_j(s) - \sum_{j=1}^n c_j(s) \right] \Delta s - r^m(\Phi x)(t) \\
 &= (1+r^m) \int_{t_0}^{\delta_+^\omega(t_0)} \frac{\Theta}{1-\Theta} \Theta |x|_1 \left[\Theta |x|_1 a(s) \right. \\
 &\quad \left. + \sum_{j=1}^n \Theta |x|_1 b_j(s) - \sum_{j=1}^n |x|_1 c_j(s) \right] \Delta s \\
 &\quad - r^m(\Phi x)(t) \\
 &\leq (1+r^m) \int_t^{\delta_+^\omega(t)} G(t, s)x(s) \left[a(s)x(s) \right.
 \end{aligned}$$

$$\begin{aligned}
 & + \sum_{j=1}^n b_j(s)x(\delta_-(\tau_j, s)) \\
 & - \sum_{j=1}^n c_j(s)|x^\Delta(\delta_-(\xi_j, s))| \Big] \Delta s - r^m(\Phi x)(t) \\
 \leq & (1 + r^m) \int_t^{\delta_+^{\omega}(t)} G(t, s)x(s) \Big[a(s)x(s) \\
 & + \sum_{j=1}^n b_j(s)x(\delta_-(\tau_j, s)) \\
 & + \sum_{j=1}^n c_j(s)x^\Delta(\delta_-(\xi_j, s)) \Big] \Delta s - r^m(\Phi x)(t) \\
 = & (1 + r^m)(\Phi x)(t) - r^m(\Phi x)(t) \\
 = & (\Phi x)(t). \tag{11}
 \end{aligned}$$

It follows from (10) and (11) that $|(\Phi x)^\Delta|_0 \leq |\Phi x|_0$. So $|\Phi x|_1 = |\Phi x|_0$. By (8), we have $(\Phi x)(t) \geq \Theta|\Phi x|_1$. Hence, $\Phi x \in K$. The proof of (i) is complete.

(ii) In view of the proof of (i), we only need to prove that $(\Phi x)^\Delta(t) \geq 0$ implies

$$(\Phi x)^\Delta(t) \leq (\Phi x)(t).$$

From (7), (9), (H_2) and (H_4) , we obtain

$$\begin{aligned}
 & (\Phi x)^\Delta(t) \\
 \leq & r(t)(\Phi x)(t) - \Theta|x|_1 \Big[a(t)x(t) \\
 & + \sum_{j=1}^n b_j(t)x(\delta_-(\tau_j, t)) \\
 & - \sum_{j=1}^n c_j(t)|x^\Delta(\delta_-(\xi_j, t))| \Big] \\
 \leq & r(t)(\Phi x)(t) \\
 & - \Theta|x|_1^2 \Big[a(t) + \sum_{j=1}^n b_j(t) - \sum_{j=1}^n c_j(t) \Big] \\
 \leq & r^M(\Phi x)(t) - \Theta|x|_1^2 \frac{r^M - 1}{\Theta(1 - \Theta)} \int_{t_0}^{\delta_+^{\omega}(t_0)} \Big[a(s) \\
 & + \sum_{j=1}^n b_j(s) + \sum_{j=1}^n c_j(s) \Big] \Delta s \\
 \leq & r^M(\Phi x)(t) \\
 & - (r^M - 1) \int_t^{\delta_+^{\omega}(t)} \frac{1}{1 - \Theta}|x|_1 \Big[a(s)|x|_1 \\
 & + \sum_{j=1}^n b_j(s)|x|_1 + \sum_{j=1}^n c_j(s)|x|_1 \Big] \Delta s
 \end{aligned}$$

$$\begin{aligned}
 & \leq r^M(\Phi x)(t) \\
 & - (r^M - 1) \int_t^{\delta_+^{\omega}(t)} G(t, s)x(s) \Big[a(s)x(s) \\
 & + \sum_{j=1}^n b_j(s)x(\delta_-(\tau_j, s)) \\
 & + \sum_{j=1}^n c_j(s)|x^\Delta(\delta_-(\xi_j, s))| \Big] \Delta s \\
 \leq & r^M(\Phi x)(t) \\
 & - (r^M - 1) \int_t^{\delta_+^{\omega}(t)} G(t, s)x(s) \Big[a(s)x(s) \\
 & + \sum_{j=1}^n b_j(s)x(\delta_-(\tau_j, s)) \\
 & + \sum_{j=1}^n c_j(s)x^\Delta(\delta_-(\xi_j, s)) \Big] \Delta s \\
 = & r^M(\Phi x)(t) - (r^M - 1)(\Phi x)(t) \\
 = & (\Phi x)(t).
 \end{aligned}$$

The proof of (ii) is complete. □

Lemma 12. Assume that $(H_1) - (H_3)$ hold and $R \sum_{j=1}^n c_j^M < 1$.

- (i) If $r^M \leq 1$, then $\Phi : K \cap \bar{\Omega}_R \rightarrow K$ is strict-set-contractive,
- (ii) If (H_4) holds and $r^M > 1$, then $\Phi : K \cap \bar{\Omega}_R \rightarrow K$ is strict-set-contractive,

where $\Omega_R = \{x \in C_\omega^1 : |x|_1 < R\}$.

Proof. We only need to prove (i), since the proof of (ii) is similar. It is easy to see that Φ is continuous and bounded. Now we prove that $\alpha_{C_\omega^1}(\Phi(S)) \leq \left(R \sum_{j=1}^n c_j^M\right) \alpha_{C_\omega^1}(S)$ for any bounded set $S \subset \bar{\Omega}_R$. Let $\eta = \alpha_{C_\omega^1}(S)$. Then, for any positive number $\varepsilon < \left(R \sum_{j=1}^n c_j^M\right) \eta$, there is a finite family of subsets $\{S_i\}$ satisfying $S = \bigcup_i S_i$ with $\text{diam}(S_i) \leq \eta + \varepsilon$. Therefore

$$|x - y|_1 \leq \eta + \varepsilon \quad \text{for any } x, y \in S_i. \tag{12}$$

As S and S_i are precompact in C_ω^0 , it follows that there is a finite family of subsets $\{S_{ij}\}$ of S_i such that $S_i = \bigcup_j S_{ij}$ and

$$|x - y|_0 \leq \varepsilon \quad \text{for any } x, y \in S_{ij}. \tag{13}$$

In addition, for any $x \in S$ and $t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$, we have

$$\begin{aligned} |(\Phi x)(t)| &= \int_t^{\delta_+^\omega(t)} G(t, s)x(s) \left[a(s)x(s) \right. \\ &\quad + \sum_{j=1}^n b_j(s)x(\delta_-(\tau_j, s)) \\ &\quad \left. + \sum_{j=1}^n c_j(s)x^\Delta(\delta_-(\xi_j, s)) \right] \Delta s \\ &\leq \frac{R^2}{1-\Theta} \int_{t_0}^{\delta_+^\omega(t_0)} \left[a(s) + \sum_{j=1}^n b_j(s) \right. \\ &\quad \left. + \sum_{j=1}^n c_j(s) \right] \Delta s := H \end{aligned}$$

and

$$\begin{aligned} |(\Phi x)^\Delta(t)| &= \left| r(t)(\Phi x)(t) - x(t) \left[a(t)x(t) \right. \right. \\ &\quad + \sum_{j=1}^n b_j(t)x(\delta_-(\tau_j, t)) \\ &\quad \left. \left. + \sum_{j=1}^n c_j(t)x^\Delta(\delta_-(\xi_j, t)) \right] \right| \\ &\leq r^M H + R^2 a^M + R^2 \sum_{j=1}^n (b_j^M + c_j^M). \end{aligned}$$

Applying the Arzela-Ascoli Theorem, we know that $\Phi(S)$ is precompact in C_ω^0 . Then, there is a finite family of subsets $\{S_{ijk}\}$ of S_{ij} such that $S_{ij} = \bigcup_k S_{ijk}$ and

$$|\Phi x - \Phi y|_0 \leq \varepsilon \quad \text{for any } x, y \in S_{ijk}. \quad (14)$$

From (7), (9) and (12)-(14) and (H_2) , for any $x, y \in S_{ijk}$, we obtain

$$\begin{aligned} &|(\Phi x)^\Delta - (\Phi y)^\Delta|_0 \\ &= \sup_{t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}} \left\{ \left| r(t)(\Phi x)(t) - r(t)(\Phi y)(t) \right. \right. \\ &\quad - x(t) \left[a(t)x(t) + \sum_{j=1}^n b_j(t)x(\delta_-(\tau_j, t)) \right. \\ &\quad \left. \left. + \sum_{j=1}^n c_j(t)x^\Delta(\delta_-(\xi_j, t)) \right] \right. \\ &\quad \left. + y(t) \left[a(t)y(t) + \sum_{j=1}^n b_j(t)y(\delta_-(\tau_j, t)) \right. \right. \\ &\quad \left. \left. + \sum_{j=1}^n c_j(t)y^\Delta(\delta_-(\xi_j, t)) \right] \right\} \end{aligned}$$

$$\begin{aligned} &\leq \sup_{t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}} \left\{ |r(t)[(\Phi x)(t) - (\Phi y)(t)]| \right. \\ &\quad + \sup_{t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}} \left\{ x(t) \left[a(t)x(t) \right. \right. \\ &\quad + \sum_{j=1}^n b_j(t)x(\delta_-(\tau_j, t)) \\ &\quad \left. \left. + \sum_{j=1}^n c_j(t)x^\Delta(\delta_-(\xi_j, t)) \right] \right. \\ &\quad \left. - y(t) \left[a(t)y(t) + \sum_{j=1}^n b_j(t)y(\delta_-(\tau_j, t)) \right. \right. \\ &\quad \left. \left. + \sum_{j=1}^n c_j(t)y^\Delta(\delta_-(\xi_j, t)) \right] \right\} \\ &\leq r^M |(\Phi x) - (\Phi y)|_0 \\ &\quad + \sup_{t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}} \left\{ x(t) \left[\left(a(t)x(t) \right. \right. \right. \\ &\quad + \sum_{j=1}^n b_j(t)x(\delta_-(\tau_j, t)) \\ &\quad + \sum_{j=1}^n c_j(t)x^\Delta(\delta_-(\xi_j, t)) \left. \left. \right) \right. \\ &\quad \left. - \left(a(t)y(t) + \sum_{j=1}^n b_j(t)y(\delta_-(\tau_j, t)) \right. \right. \\ &\quad \left. \left. + \sum_{j=1}^n c_j(t)y^\Delta(\delta_-(\xi_j, t)) \right) \right\} \\ &\quad + \sup_{t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}} \left\{ y(t) \left[a(t)y(t) \right. \right. \\ &\quad + \sum_{j=1}^n b_j(t)y(\delta_-(\tau_j, t)) \\ &\quad \left. \left. + \sum_{j=1}^n c_j(t)y^\Delta(\delta_-(\xi_j, t)) \right] [x(t) - y(t)] \right\} \\ &\leq r^M \varepsilon + R \sup_{t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}} \left\{ a(t)|x(t) - y(t)| \right. \\ &\quad + \sum_{j=1}^n b_j(t)|x(\delta_-(\tau_j, t)) - y(\delta_-(\tau_j, t))| \\ &\quad \left. + \sum_{j=1}^n c_j(t)|x^\Delta(\delta_-(\xi_j, t)) - y^\Delta(\delta_-(\xi_j, t))| \right\} \\ &\quad + \varepsilon \sup_{t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}} \left\{ a(t)y(t) + \sum_{j=1}^n b_j(t)y(\delta_-(\tau_j, t)) \right\} \end{aligned}$$

$$\begin{aligned}
 & + \sum_{j=1}^n c_j(t) |y^\Delta(\delta_-(\xi_j, t))| \} \\
 & \leq r^M \varepsilon + R\varepsilon \left(a^M + \sum_{j=1}^n b_j^M \right) \\
 & + R(\eta + \varepsilon) \left(\sum_{j=1}^n c_j^M \right) \\
 & + R\varepsilon \left(a^M + \sum_{j=1}^n b_j^M + \sum_{j=1}^n c_j^M \right) \\
 & = \left(R\eta \sum_{j=1}^n c_j^M \right) + \hat{H}\varepsilon, \tag{15}
 \end{aligned}$$

where $\hat{H} = r^M + 2Ra^M + 2R \sum_{j=1}^n b_j^M + 2R \sum_{j=1}^n c_j^M$.

From (14) and (15) we have

$$|\Phi x - \Phi y|_1 \leq \left(R \sum_{j=1}^n c_j^M \right) \eta + \hat{H}\varepsilon,$$

for any $x, y \in S_{ijk}$. As ε is arbitrary small, it follows that

$$\alpha_{C_\omega^1}(\Phi(S)) \leq \left(R \sum_{j=1}^n c_j^M \right) \alpha_{C_\omega^1}(S).$$

Therefore, Φ is strict-set-contractive. The proof is complete. \square

3 Main Result

Our main result of this paper is as follows:

Theorem 13. Assume that $(H_1) - (H_3)$, (H_5) hold.

- (i) If $r^M \leq 1$, then system (1) has at least one positive ω -periodic solution in shifts δ_\pm .
- (ii) If (H_4) holds and $r^M > 1$, then system (1) has at least one positive ω -periodic solution in shifts δ_\pm .

Proof. We only need to prove (i), since the proof of (ii) is similar. Let $R = \frac{1-\Theta}{\Theta^2 \Gamma}$ and $0 < r < \frac{\Theta(1-\Theta)}{\Pi}$, then we have $0 < r < R$. From Lemmas 11 and 12, we know that Φ is strict-set-contractive on $K_{r,R}$. In view of (9), we see that if there exists $x^* \in K$ such that $\Phi x^* = x^*$, then x^* is one positive ω -periodic solution in shifts δ_\pm of system (1). Now, we shall prove that condition (ii) of Lemma 10 holds.

First, we prove that $\Phi x \not\leq x, \forall x \in K, |x|_1 = r$. Otherwise, there exists $x \in K, |x|_1 = r$ such that

$\Phi x \geq x$. So $|x| > 0$ and $\Phi x - x \in K$, which implies that

$$(\Phi x)(t) - x(t) \geq \Theta |\Phi x - x|_1 \geq 0, \tag{16}$$

for any $t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$.

Moreover, for $t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$, we have

$$\begin{aligned}
 (\Phi x)(t) & = \int_t^{\delta_+^\omega(t)} G(t, s)x(s) \left[a(s)x(s) \right. \\
 & + \sum_{j=1}^n b_j(s)x(\delta_-(\tau_j, s)) \\
 & + \left. \sum_{j=1}^n c_j(s)x^\Delta(\delta_-(\xi_j, s)) \right] \Delta s \\
 & \leq \frac{1}{1-\Theta} r |x|_0 \int_{t_0}^{\delta_+^\omega(t_0)} \left[a(s) + \sum_{j=1}^n b_j(s) \right. \\
 & + \left. \sum_{j=1}^n c_j(s) \right] \Delta s \\
 & = \frac{r}{1-\Theta} \Pi |x|_0 \\
 & < \Theta |x|_0. \tag{17}
 \end{aligned}$$

In view of (16) and (17), we have

$$|x|_0 \leq |\Phi x| < \Theta |x|_0 < |x|_0,$$

which is a contradiction. Finally, we prove that $\Phi x \not\leq x, \forall x \in K, |x|_1 = R$ also holds. For this case, we only need to prove that

$$\Phi x \not\leq x \quad x \in K, |x|_1 = R.$$

Suppose, for the sake of contradiction, that there exists $x \in K$ and $|x|_1 = R$ such that $\Phi x < x$. Thus $x - \Phi x \in K \setminus \{0\}$. Furthermore, for any $t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$, we have

$$x(t) - (\Phi x)(t) \geq \Theta |x - \Phi x|_1 > 0. \tag{18}$$

In addition, for any $t \in [t_0, \delta_+^\omega(t_0)]_{\mathbb{T}}$, we find

$$\begin{aligned}
 (\Phi x)(t) & = \int_t^{\delta_+^\omega(t)} G(t, s)x(s) \left[a(s)x(s) \right. \\
 & + \sum_{j=1}^n b_j(s)x(\delta_-(\tau_j, s)) \\
 & + \left. \sum_{j=1}^n c_j(s)x^\Delta(\delta_-(\xi_j, s)) \right] \Delta s \\
 & \geq \frac{\Theta}{1-\Theta} \Theta |x|_1^2 \int_{t_0}^{\delta_+^\omega(t_0)} \left[\Theta a(s) \right. \\
 & + \left. \sum_{j=1}^n \Theta b_j(s) - \sum_{j=1}^n c_j(s) \right] \Delta s
 \end{aligned}$$

$$\begin{aligned} &= \frac{\Theta^2}{1 - \Theta} \Gamma R^2 \\ &= R. \end{aligned} \tag{19}$$

From (18) and (19), we obtain

$$|x| > |\Phi x|_0 \geq R,$$

which is a contradiction. Therefore, conditions (i) and (ii) hold. By Lemma 10, we see that Φ has at least one nonzero fixed point in K . Therefore, system (1) has at least one positive ω -periodic solution in shifts δ_{\pm} . The proof is complete. \square

4 Numerical examples

Example 1. Consider the following system on time scales

$$\begin{aligned} x^\Delta(t) = & x(t) \left[\frac{2 + \cos \pi t}{8} - (5 - 2 \sin \pi t)x(t) \right. \\ & - (2 + \sin \pi t)x(\delta_-(2, t)) \\ & \left. - \frac{1 - \cos \pi t}{20} x^\Delta(\delta_-(2, t)) \right]. \end{aligned} \tag{20}$$

Obviously,

$$\begin{aligned} r = \frac{2 + \cos \pi t}{8}, \quad a = 5 - 2 \sin \pi t, \\ b_1 = 2 + \sin \pi t, \quad c_1 = \frac{1 - \cos \pi t}{20}. \end{aligned}$$

Let $\mathbb{T} = \mathbb{R}$, $t_0 = 0$, then $\delta_{\pm}^\omega(t) = t + 2$. It is easy to verify $r(t), a(t), b_1(t), c_1(t)$ are Δ -periodic in shifts δ_{\pm} with period $\omega = 2$. By a direct calculation, we can get

$$\Theta = e^{-\frac{1}{2}}, \Gamma = 8.3914,$$

$$\inf_{t \in [0, 2]_{\mathbb{T}}} \{\Theta a(t) + \Theta b_1(t) - c_1(t)\} = 2.3261,$$

$$\sup_{t \in [0, 2]_{\mathbb{T}}} \{a(t) + b_1(t) + c_1(t)\} = 8.0512,$$

$$(1 + r^m) \frac{\Theta^2}{1 - \Theta} \Gamma = 8.8264,$$

and

$$\frac{1 - \Theta}{\Theta^2 \Gamma} c_1^M = 0.0128.$$

Hence, $(H_1) - (H_3), (H_5)$ hold and $r^M \leq 1$. According to Theorem 13, when $\mathbb{T} = \mathbb{R}$, system (20) has at least one positive 2-periodic solution in shifts δ_{\pm} .

Example 2. Consider the following system on time scales

$$\begin{aligned} x^\Delta(t) = & x(t) \left[\frac{1}{5t} - \frac{2}{t} x(t) - \frac{3}{t} x(\delta_-(4, t)) \right. \\ & \left. - \frac{1}{20t} x^\Delta(\delta_-(4, t)) \right]. \end{aligned} \tag{21}$$

Obviously,

$$r = \frac{1}{5t}, \quad a = \frac{2}{t}, \quad b_1 = \frac{3}{t}, \quad c_1 = \frac{1}{20t}.$$

Let $\mathbb{T} = 2^{\mathbb{N}_0}$, $t_0 = 1$, then $\delta_{\pm}^\omega(t) = 4t$. It is easy to verify $r(t), a(t), b_1(t), c_1(t)$ are Δ -periodic in shifts δ_{\pm} with period $\omega = 4$. By a direct calculation, we can get

$$\Theta = 0.6818, \Gamma = 4.6566,$$

$$\inf_{t \in [1, 4]_{\mathbb{T}}} \{\Theta a(t) + \Theta b_1(t) - c_1(t)\} = 0.8022,$$

$$\sup_{t \in [1, 4]_{\mathbb{T}}} \{a(t) + b_1(t) + c_1(t)\} = 5.0500,$$

$$(1 + r^m) \frac{\Theta^2}{1 - \Theta} \Gamma = 7.1429,$$

and

$$\frac{1 - \Theta}{\Theta^2 \Gamma} c_1^M = 0.0073.$$

Hence, $(H_1) - (H_3), (H_5)$ hold and $r^M \leq 1$. According to Theorem 13, when $\mathbb{T} = 2^{\mathbb{N}_0}$, system (21) has at least one positive 4-periodic solution in shifts δ_{\pm} .

5 Conclusion

This paper is concerned with the existence of positive periodic solutions in shifts δ_{\pm} for a neutral delay logistic equation on time scales. Based on the theory of calculus on time scales, by using a fixed point theorem of strict-set-contraction, some existence results are established for the system.

The method used in this paper is the same in [3], but the results obtained in this paper extend and unify periodic differential, difference, h -difference and q -difference equations and more by a new periodicity concept on time scales.

Acknowledgements: This work is supported by the Basic and Frontier Technology Research Project of Henan Province (Grant No. 142300410113).

References:

- [1] Y. Kuang, *Delay differential equations with applications in population dynamics*, New York: Academic Press; 1993.
- [2] Z. Yang, J. Cao, Existence of periodic solutions in neutral state-dependent delays equations and models, *J. Comput. Appl. Math.*, 174, (2005), pp.179-199.
- [3] Y. Li, Positive periodic solutions of periodic neutral Lotka-Volterra system with state dependent delays, *J. Math. Anal. Appl.*, 330, (2007), pp.1347-1362.
- [4] G. E. Chatzarakis, G. N. Miliaras, Convergence and divergence of the solutions of a neutral difference equation, *J. Appl. Math.*, Volume 2011, Article ID 262316.
- [5] Q. Feng, R. Yuan, Existence of almost periodic solutions for neutral delay difference systems, *Front. Math. China*, 4(3), (2009), pp.437-462.
- [6] V. Spedding, Taming nature's numbers, *New Scientist*, 2404, (2003), pp.28-31.
- [7] R. C. McKellar, K. Knight, A combined discrete-continuous model describing the lag phase of *Listeria monocytogenes*, *Int. J. Food Microbiol.*, 54(3), (2000), pp.171-180.
- [8] M. Bohner, A. Peterson, *Advances in dynamic equations on time scales*, Boston: Birkhäuser, 2003.
- [9] S. Hilger, *Ein Masskettenkalkl mit Anwendug auf Zentrumsmanngfaltigkeiten* [Ph.D. thesis], Universität Würzburg, 1988.
- [10] M. Hu, H. Lv, Almost periodic solutions of a single-species system with feedback control on time scales, *Adv. Differ. Equ.*, 2013, 2013:196.
- [11] M. Hu, L. Wang, Almost periodic solution of neutral-type neural networks with time delay in the leakage term on time scales, *WSEAS Trans. Syst.*, 13, (2014), pp.231-241.
- [12] L. Wang, M. Hu, Dynamic behaviors of an almost periodic Volterra integro dynamic equation on time scales, *WSEAS Trans. Math.*, 13, (2014), pp.182-191.
- [13] M. Hu, P. Xie, Positive periodic solutions of delayed dynamic equations with feedback control on time scales, *WSEAS Trans. Math.*, 7, (2013), pp.777-785.
- [14] M. Fazly, M. Hesaaraki, Periodic solutions for predator-prey systems with Beddington-DeAngelis functional response on time scales, *Nonlinear Anal. RWA.*, 9(3), (2008), pp. 1224-1235.
- [15] E. R. Kaufmann, Y. N. Raffoul, Periodic solutions for a neutral nonlinear dynamical equation on a time scale, *J. Math. Anal. Appl.*, 319, (2006), pp.315-325.
- [16] A. Ardjouni, A. Djoudi, Existence of periodic solutions for nonlinear neutral dynamic equations with variable delay on a time scale, *Commun. Nonlinear Sci. Numer. Simulat.*, 17(7), (2012), pp.3061-3069.
- [17] M. Adıvar, Function bounds for solutions of Volterra integro dynamic equations on the time scales, *Electron. J. Qual. Theo.*, 7, (2010), pp.1-22.
- [18] M. Adıvar, Y.N. Raffoul, Existence of resolvent for Volterra integral equations on time scales, *B. Aust. Math. Soc.*, 82(1), (2010), pp.139-155.
- [19] E. Çetin, Positive periodic solutions in shifts δ_{\pm} for a nonlinear first-order functional dynamic equation on time scales, *Adv. Differ. Equ.*, 2014, 2014:76.
- [20] E. Çetin, F.S. Topal, Periodic solutions in shifts δ_{\pm} for a nonlinear dynamic equation on time scales, *Abstr. Appl. Anal.*, Volume 2012, Article ID 707319.
- [21] M. Hu, L. Wang, Multiple periodic solutions in shifts δ_{\pm} for an impulsive functional dynamic equation on time scales, *Adv. Differ. Equ.*, 2014, 2014:152.
- [22] M. Hu, L. Wang, Positive periodic solutions in shifts δ_{\pm} for a class of higher-dimensional functional dynamic equations with impulses on time scales, *Abstr. Appl. Anal.*, Volume 2014, Article ID 509052.
- [23] M. Adıvar, A new periodicity concept for time scales, *Math. Slovaca*, 63(4), (2013), pp.817-828.
- [24] N.P. Cac, J.A. Gatica, Fixed point theorems for mappings in ordered Banach spaces, *J. Math. Anal. Appl.*, 71, (1979), pp.547-557.
- [25] D. Guo, Positive solutions of nonlinear operator equations and its applications to nonlinear integral equations, *Adv. Math.*, 13,(1984), pp.294-310 (in Chinese).