

# The reduction method for approximative solution of systems of Singular Integro-Differential Equations in Lebesgue spaces(case $\gamma \neq 0$ )

Feras M. Al Faqih  
Al-Hussein Bin Talal University  
Department of Mathematics  
Jordan  
falfaqih@ahu.edu.jo  
oxfer@yahoo.com

Iurie Caraus  
University of Quebec  
of Montreal  
Department of Informatics  
Canada  
caraus.iurie@courrier.uqam.ca

Nikos E. Mastorakis  
WSEAS  
A.I. Theologou 17-23  
15773 Zographou, Athens  
Greece  
mastor@wseas.org

*Abstract:* In this article we have elaborated the numerical schemes of reduction methods for approximate solution of system of singular integro-differential equations when the kernel has a weak singularity. The equations are defined on the arbitrary smooth closed contour of complex plane. We suggest the numerical schemes of the reduction method over the system of Faber-Laurent polynomials for the approximate solution of weakly singular integro- differential equations defined on smooth closed contours in the complex plane. We use the cut-off technique kernel to reduce the weakly singular integro- differential equation to the continuous one. Our approach is based on the Krykunov theory and Zolotarevski results. We have obtained the theoretical background for these methods in classical Lebesgue spaces.

*Key-Words:* Faber- Laurent Polynomials, systems of singular integro-differential equations, reduction methods

## 1 Introduction

Singular integro-differential equations (SIDE) model many problems in physics, elasticity theory, aerodynamics, mechanics, etc. [1]-[9].

The problem of approximate solution of systems of SIDE was studied in many scientific articles [10]-[18].

At the same time the reduction method applied to the approximative solution of systems of SIDE is not studied enough, particularly the case when the equations are defined on a close contour of the complex plain different from the standard one(unit circle: $\Gamma_0$ ).

It is known that the exact solution for SIDE can only be found in particular cases and even in these cases the exact solution is expressed by multiple singular integrals, their calculation presents many theoretical and practical difficul-

ties. That is why the necessity exists to elaborate approximate methods for solving SIDE with the corresponding theoretical background. The first results in this direction have been obtained for SIDE on a standard contour: segment or unity circle. [10]-[18] Transition to another contour, different from the standard one, implies many difficulties. It should be noted that the conformal mapping of SIDE from the arbitrary contour to the standard one using some reflection function does not solve the problem, but only it makes more difficult: a nucleus with a weak singularity appears, so the method of mechanical quadratures cannot be applied.

We would like to mention only the scientific articles [24]-[25] which study the reduction method applied to the Singular Integral Equations(SIE), defined on the smooth closed contour (different from a standard one), where the

theoretical background of reduction method has been obtained in Hölder spaces. In case when the SIE are defined on the unit circle the reduction method was studied in monograph [26] and scientific papers [27]-[28] where the theoretical background of SIE has been obtained in Lebesgue spaces  $L_p(\Gamma_0)$  and Holder spaces  $H_\beta(\Gamma_0)$  ( $\Gamma_0$  is unit circle). The case of SIDE of reduction methods has been studied in [29]. Theoretical background has been obtained in Holder spaces.

Theoretical background of the collocation for approximate solution of SIDE in Hölder spaces and Lebesgue spaces was proved in [22]-[23]. The equations are given on a closed contour satisfying some conditions of smoothness. The stability of collocation methods was obtained in [20]. The numerical results can be found in [21].

In the present work the numerical schemes of reduction methods for approximative solution of systems of weakly SIDE have been obtained on the Faber-Laurent polynomial system, generated by an arbitrary smooth closed contour. The theoretical background has been obtained in Lebesgue spaces.

## 2 Definitions of Function Spaces and Notations

Let  $\Gamma$  be a smooth closed contour bounding a simply connected domain  $D^+$  that contains the point  $z = 0$ , and let  $D^- = C \setminus D^+ \cup \Gamma$ .

Let function  $w = \Phi(z)$  apply conformably  $D^-$  in the domain  $|w| > 1$  so that  $\Phi(\infty) = \infty, \lim_{z \rightarrow \infty} z^{-1}\Phi(z) = \alpha > 0$ , and  $z = \phi(w)$  is the inverse function of function  $\Phi(z)$ .

And let  $w = F(z)$  apply conformably  $D^+$  in the domain  $|w| > 1$ , so that  $F(0) = \infty, \lim_{z \rightarrow 0} zF(z) = \beta > 0$ , and  $z = \varphi(w)$  is the inverse function.

In the area of the infinite point the function

$\Phi(z)$  will have the decomposition:

$$\Phi(z) = \alpha z + \alpha_0 + \frac{\alpha_1}{z} + \frac{\alpha_2}{z^2} + \dots,$$

and the inverse function  $z = \phi(w) = \gamma w + \gamma_0 + \frac{\gamma_1}{w} + \frac{\gamma_2}{w^2} + \dots, |w| > 1$ , where  $\gamma = \frac{1}{\alpha} > 0$ .

The function  $F(z)$  in the area of the point zero will have the decomposing:

$$F(z) = \beta z^{-1} + \beta_0 + \beta_1 z + \beta_2 z^2 + \dots,$$

and the inverse function will have a decomposing that is obtained in the same way.

Suppose in the future that  $\alpha = 1, \beta = 1$ . As is proved in the monograph [30], this supposition doesn't limit the general case.

With  $\Phi_k(z) (k = 0, 1, 2, \dots)$  mark the polynomial that represents the totality of members with non-negative power of  $z$  in the Laurent decomposition of the function  $[\Phi(z)]^k$ , and with  $F_k(1/z) (k = 1, 2, \dots)$  – the polynomial that represents the totality of members with negative power of  $z$  in Laurent expansion of the function  $[F(z)]^k$ . Polynomials  $\Phi_k(z) (k = 0, 1, 2, \dots)$  and  $F_k(1/z) (k = 1, 2, \dots)$  are called Faber polynomials for the contour  $\Gamma$  for the powers of  $z$  and  $1/z, z \in \Gamma$ , respectively. Let  $S_n$  be the operator that takes each continuous function  $g(t)$  on  $\Gamma$  to the  $n$ th partial sum of its Faber-Laurent polynomials (see [30]):

$$g(t) = \sum_{k=0}^{\infty} g_k \Phi_k(t) + \sum_{k=1}^{\infty} g_{-k} F_k(1/t), \quad (1)$$

where  $g_k (k = 0, \pm 1, \dots)$  is calculated from:

$$g_k = \frac{1}{2\pi i} \int_{|\tau|=\rho} g(\phi(\tau)) \tau^{-k-1} d\tau, (k = 0, 1, 2, \dots), \quad (2)$$

$$g_{-k} = \frac{1}{2\pi i} \int_{|\tau|=\rho} g(\varphi(\tau)) \tau^{-k-1} d\tau, (k = 1, 2, \dots). \quad (3)$$

Mark with  $S_n$  the operator that puts in correspondence to each function  $g(t)$  defined on  $\Gamma$  partial sum of order  $n$  of Faber-Laurent series:

$$(S_n g)(t) = \sum_{k=0}^n g_k \Phi_k(t) + \sum_{k=1}^n g_{-k} F_k(1/t). \quad (4)$$

We assume that the function  $z = \psi(w)$  has a second derivative, satisfying on unit circle the Hölder condition with some parameter  $q$  ( $0 < \nu < 1$ ); the class of such contours is denoted by  $C(2; \nu)$ . [19]

In the complex space  $[L_p(\Gamma)]_m$  ( $1 < p < \infty$ ) of vector functions (v.f.)

$$g(t) = (g_1(t), \dots, g_m(t));$$

$g_j(t) \in L_p(\Gamma)$ ,  $j = \overline{1, m}$  summarized on  $\Gamma$  on power  $p$ ,  $1 < p < \infty$  and with the norm

$$\|g\| = \sum_{k=1}^m \|g_k\|_p; \quad \|g_k\|_p = \left( \frac{1}{l} \int_{\Gamma} |g_k|^p(\tau) |d\tau| \right)^{\frac{1}{p}},$$

where  $l$  is the length of  $\Gamma$ ,

We denote by  $[H_\beta^{(q)}]_m$ ,  $0 < \beta \leq 1$ , the Banach space of  $m$ -dimensional vector functions, satisfying on  $\Gamma$  the Holder condition with degree  $\beta$ .

The norm is defined as  $\forall g(t) = \{g_1(t), \dots, g_m(t)\}$

$$\|g\|_\beta = \sum_1^m (\|g\|_C + H(g_k, \beta)),$$

$$\|g\|_C = \max_C |g(t)|,$$

$$H(g, \beta) = \sup_{t' \neq t''} \{|t' - t''|^{-\beta} |g(t') - g(t'')|\}, \quad t', t'' \in \Gamma.$$

**Definition 1** A factorization of non-singular matrix  $G(t)$  relative to the contour  $\Gamma$  is a representation of  $G(t)$  in the form

$$G(t) = G^+ \Delta(t) G^-$$

where  $G^\pm$  are matrix functions analytic and non-singular in  $D^\pm$ , satisfying  $\det G^\pm \neq 0$ , respectively,  $\Delta(t) = \text{diag}\{t^{\kappa_1}, t^{\kappa_2}, \dots, t^{\kappa_m}\}$ , and  $\kappa_1, \kappa_2, \dots, \kappa_m$  are integer. The numbers  $\kappa_1, \kappa_2, \dots, \kappa_m$  are called left partial indexes [36]

### 3 Problem formulation

In the complex space  $[L_p(\Gamma)]_m$  we consider the singular integro-differential equations (SIDE)

$$(Mx \equiv) \sum_{r=0}^q [\tilde{A}_r(t)x^{(r)}(t) + \tilde{B}_r(t) \frac{1}{\pi i} \int_{\Gamma} \frac{x^{(r)}(\tau)}{\tau - t} d\tau + \frac{1}{2\pi i} \int_{\Gamma} \frac{K_r(t, \tau)}{|t - \tau|^{\gamma_r}} \cdot x^{(r)}(\tau) d\tau] = f(t), \quad t \in \Gamma, \quad (5)$$

where  $0 < \gamma_r < 1$ ,  $\tilde{A}_r(t), \tilde{B}_r(t)$  are given matrix functions(m.f.),  $f(t)$  is given v.f. which belong to  $[H_\beta(\Gamma)]_m$ ; and  $K_r(t, \tau)$  ( $r = \overline{0, q}$ ) is m.f. which belong to  $[H_\beta(\Gamma)]_m$  by both variables.  $x^{(0)}(t) = x(t)$  is the required v.f.;  $x^{(r)}(t) = \frac{d^r x(t)}{dt^r}$  ( $r = \overline{1, q}$ ); ( $q$  is a natural number) which belong to  $[H_\beta(\Gamma)]_m$ .

Using the Riesz operators  $P = \frac{1}{2}(I + S)$ ,  $Q = I - P$ , (where  $I$  is the identity operator, and  $S$  is the singular operator (with Cauchy kernel)), we rewrite the system of Eq. (5) in the following form convenient for consideration:

$$(Mx \equiv) \sum_{r=0}^q [A_r(t)(Px^{(r)})(t) + B_r(t)(Qx^{(r)})(t) + \frac{1}{2\pi i} \int_{\Gamma} \frac{K_r(t, \tau)}{|t - \tau|^\gamma} \cdot x^{(r)}(\tau) d\tau] = f(t), \quad t \in \Gamma, \quad (6)$$

where  $A_r(t) = \tilde{A}_r(t) + \tilde{B}_r(t)$ ,  $B_r(t) = \tilde{A}_r(t) - \tilde{B}_r(t)$ ,  $r = 0, \dots, q$ .

We need that the function  $x^{(q)}(t)$  belongs to  $[H_\beta(\Gamma)]_m$ . From this condition follows that

$$x^{(k)} \in [H_\beta(\Gamma)]_m, \quad k = 0, \dots, q - 1.$$

We search for the solution of equation (5) in the class of functions, satisfying the condition

$$\frac{1}{2\pi i} \int_{\Gamma} x(\tau) \tau^{-k-1} d\tau = 0, \quad k = \overline{0, q-1}. \quad (7)$$

We introduce the denotation "the problem (5)-(7)" for the SIDE (5) together with the conditions (7).

In order to reduce the schemes of reduction methods we introduce a new integro- differential equation from the initial equation. The kernel with the weak singular peculiarities is substituted by continue kernel. Consequently we solve the approximative equation:

$$(M_\rho x) \equiv (M_0 x)(t) + \frac{1}{2\pi i} \sum_{r=0}^q \int_{\Gamma} K_{r,\rho}(t, \tau) x^{(r)}(\tau) d\tau = f(t), \quad t \in \Gamma. \tag{8}$$

$$\text{where } K_{r,\rho}(t, \tau) = \begin{cases} \frac{K_r(t, \tau)}{|t - \tau|^{\gamma r}} & \text{when } |t - \tau| \geq \rho; \\ \frac{K_r(t, \tau)}{\rho^{\gamma r}} & \text{when } |t - \tau| < \rho; \end{cases} \tag{9}$$

$\rho$  is a arbitrary positive number,  $M_0$  is a characteristic part of S which corresponds system (5). And so the equation (5) is changed on the new equation (8).

### 4 Auxiliary results

We formulate one result from [31],[32] establishing the equivalence (in sense of solvability) of problem (5)-(7) and system of SIE. We use this result for proving Theorem 7. V.F.  $\frac{d^q(Px)(t)}{dt^q}$  and  $\frac{d^q(Qx)(t)}{dt^q}$  can be represented by integrals of Cauchy type with the same density  $v(t)$  :

$$\left. \begin{aligned} \frac{d^q(Px)(t)}{dt^q} &= \frac{1}{2\pi i} \int_{\Gamma} \frac{v(\tau)}{\tau - t} d\tau, \quad t \in F^+, \\ \frac{d^q(Qx)(t)}{dt^q} &= \frac{t^{-q}}{2\pi i} \int_{\Gamma} \frac{v(\tau)}{\tau - t} d\tau, \quad t \in F^-. \end{aligned} \right\} \tag{10}$$

Using the integral representation (10) we reduce the problem (5)-(7) to the equivalent (in sense of solvability) system of SIE

$$(\Upsilon v \equiv) C(t)v(t) + \frac{D(t)}{\pi i} \int_{\Gamma} \frac{v(\tau)}{\tau - t} d\tau +$$

$$\frac{1}{2\pi i} \int_{\Gamma} \frac{h(t, \tau)}{|\tau - t|^\gamma} v(\tau) d\tau = f(t), \quad t \in \Gamma, \tag{11}$$

for unknown v.f.  $v(t)$  where

$$\begin{aligned} C(t) &= \frac{1}{2} [A_q(t) + t^{-q} B_q(t)], \\ D(t) &= \frac{1}{2} [A_q(t) - t^{-q} B_q(t)], \end{aligned} \tag{12}$$

$$h(t, \tau) = \frac{1}{2} [K_q(t, \tau) +$$

$$K_q(t, \tau)\tau^{-n}] - \frac{1}{2\pi i} \int_{\Gamma}$$

$$[K_q(t, t_1) - K_q(t, t_1)t_1^{-n}] \frac{dt_1}{t_1 - \tau}$$

$$+ \sum_{j=0}^{q-1} [A_j(t)\tilde{M}_j(t, \tau) +$$

$$\int_{\Gamma} K_j(t, t_1)\tilde{M}_j(t_1, \tau) dt_1]$$

$$- \sum_{j=0}^{q-1} [B_j(t)\tilde{N}_j(t, \tau) +$$

$$\int_{\Gamma} K_j(t, t_1)\tilde{N}_j(t_1, \tau) dt_1], \tag{13}$$

where  $\tilde{M}_j(t, \tau), \tilde{N}_j(t, \tau) \quad j = 0, \dots,$  are Hölder m.f. An obvious form for these functions is given in [32]. By virtue of the proprieties of the M.F.  $\tilde{M}_j(t, \tau), \tilde{N}_j(t, \tau), K_j(t, \tau), A_j(t), B_j(t), \quad j = 0, \dots, q$  the function  $h(t, \tau)$  is a continuous function in both variables.

**Lemma 2** *The system of SIE (11) and problem (5)-(7) are equivalent in the sense of solvability. That is, for each solution v.f.  $v(t)$  of system of SIE (11) there is a solution of problem (5)-(7), determined by formulae*

$$\begin{aligned} (Px)(t) &= \frac{(-1)^q}{2\pi i(q-1)!} \int_{\Gamma} v(\tau)[(\tau - t)^{q-1} \times \\ &\log\left(1 - \frac{t}{\tau}\right) + \sum_{k=1}^{q-1} \tilde{\alpha}_k \tau^{q-k-1} t^k] d\tau, \end{aligned}$$

$$(Qx)(t) = \frac{(-1)^q}{2\pi i(q-1)!} \int_{\Gamma} v(\tau) \tau^{-q} [(\tau-t)^{q-1} \times \log\left(1 - \frac{\tau}{t}\right) + \sum_{k=1}^{q-2} \tilde{\beta}_k \tau^{q-k-1} t^k] d\tau, \quad (14)$$

where  $(\tilde{\alpha}_k = \sum_{j=0}^{k-1} \frac{(-1)^j C_{q-1}^j}{k-j}, k = 1, \dots, q-1,$   
 $\tilde{\beta}_k = \sum_{j=k+1}^{q-1} \frac{(-1)^j C_{q-1}^j}{j-k}, k = 1, \dots, q-2$  and  $C_{q-1}^j$  are the binomial coefficients.) On the other hand, for each solution v.f.  $x(t)$  of the problem (5)-(7) there is a solution v.f.  $v(t)$

$$v(t) = \frac{d^q(Px)(t)}{dt^q} + t^q \frac{d^q(Qx)(t)}{dt^q},$$

to the system of SIE (11). Furthermore, for linearly-independent solutions of (11), there are corresponding linearly-independent solutions of the problem (5)-(7) from (14) and vice versa.

In formulas (14) by  $\log(1 - t/\tau)$  we understand the branch which vanishes as  $t = 0$  and by  $\log(1 - \tau/t)$  the branch which vanishes as  $t = \infty$ .

Define  $[\overset{\circ}{W}_p^{(q)}]_m$  as

$$[\overset{\circ}{W}_p^{(q)}]_m = \left\{ g \in [L_p(\Gamma)]_m : g^{(q)} \in [L_p(\Gamma)]_m, \right.$$

$$\left. \frac{1}{2\pi i} \int_{\Gamma} g(\tau) \tau^{-k-1} d\tau = 0, \right.$$

$$\left. k = 0, \dots, q-1 \right\}.$$

The norm in  $[\overset{\circ}{W}_p^{(q)}]_m$  is determined by the equality

$$[\|g\|_{p,q}]_m = [\|g^{(q)}\|_{L_p}]_m.$$

We denote by  $[L_{p,q}]_m$  the image of the space  $[L_p]_m$  with respect to the map  $P + t^{-q}Q$  equipped with the norm of  $[L_p]_m$ . We formulate Lemma 3 and Lemma 4 from [33]. We use these lemmas to prove the convergence theorems.

**Lemma 3** The differential operator  $D^q : [\overset{\circ}{W}_p^{(q)}]_m \rightarrow [L_{p,q}]_m, (D^q g)(t) = g^{(q)}(t)$  is continuously invertible and its inverse operator  $D^{-q} : [L_{p,q}]_m \rightarrow [\overset{\circ}{W}_p^{(q)}]_m$  is determined by the equality

$$(D^{-q}g)(t) = (N^+g)(t) + (N^-g)(t),$$

$$(N^+g)(t) = \frac{(-1)^q}{2\pi i(q-1)!} \times$$

$$\int_{\Gamma} (Pg)(\tau) (\tau-t)^{q-1} \log\left(1 - \frac{t}{\tau}\right) d\tau,$$

$$(N^-g)(t) = \frac{(-1)^{q-1}}{2\pi i(q-1)!} \times$$

$$\int_{\Gamma} (Qg)(\tau) (\tau-t)^{q-1} \log\left(1 - \frac{\tau}{t}\right) d\tau.$$

From Lemma 3 it follows

**Lemma 4** The operator  $B : [\overset{\circ}{W}_p^{(q)}]_m \rightarrow [L_p]_m, B = (P + t^qQ)D^q$  is invertible and

$$B^{-1} = D^{-q}(P + t^{-q}Q).$$

### 4.1 Estimates for weakly singular integral operators

**Lemma 5** Let  $h(t, \tau) \in C(\Gamma \times \Gamma)$ , and  $\psi(t) \in L_p(\Gamma), 1 < p < \infty$ . Then the function  $H(t) = \frac{1}{2\pi i} \int_{\Gamma} \frac{h(t, \tau)}{|\tau - t|^\gamma} \psi(\tau) d\tau$ , satisfies the inequality

$$\|H\|_p \leq d_1^1 \|\psi\|_p, \frac{1}{p} + \frac{1}{q} = 1,$$

$$\|(\cdot)\|_p = \left| \frac{1}{l} \int_{\Gamma} |(\cdot)(\tau)|^p d\tau \right|^{1/p}. \quad (15)$$

The proof can be found in [34].

**Lemma 6** Let the assumptions of Lemma 5 be satisfied; then  $\|\chi_\rho\|_p \leq d_2 \rho^{(1-\gamma)/q} \|\psi\|_p$ , where

$$\chi_\rho = \frac{1}{2\pi i} \int_{\Gamma} \left[ \frac{h(t, \tau)}{|\tau - t|^\gamma} - h_\rho(t, \tau) \right] \psi(\tau) d\tau, \frac{1}{p} +$$

$$\frac{1}{q} = 1.$$

The proof of this lemma can be found in [34].

<sup>1</sup>By  $d_1, d_2, \dots$ , we denote the constants.

### 5 Convergence Theorem

We seek an approximate solution of problem (5)-(7) in the form of a polynomial

$$x_{n,\rho}(t) = t^q \sum_{k=0}^n \alpha_{k,\rho} \Phi_k(t) + \sum_{k=1}^n \alpha_{-k,\rho} F_k\left(\frac{1}{t}\right), t \in \Gamma, \quad (16)$$

with unknown numerical v.f.  $\alpha_{k,\rho} = k = -n, \dots, n$ . The numerical v.f.  $\alpha_{k,\rho}$  are found from the condition:

$$S_n[Mx_{n,\rho} - f] = 0, \\ S_n[Mx_{n,\rho}] = S_n f, \quad (17)$$

for the unknown v.f.  $x_{n,\rho}(t)$  of the form (16). Note that Eq. (17) is a system of  $m(2n + 1)$  linear algebraic equations(SLAE) with  $m(2n + 1)$  unknowns  $\alpha_{k,\rho} k = -n, \dots, n$ .

Note that the functions of this system is determined by the Faber- Laurent coefficients of the M.f  $A_r(t)$  and  $B_r(t)$  :

$$\frac{1}{2\pi i} \int_{\Gamma} K_{r,\rho}(t, \tau) \Phi_k(\tau) d\tau, k = 0, \dots, n, \\ \frac{1}{2\pi i} \int_{\Gamma} K_{r,\rho}(t, \tau) F_k\left(\frac{1}{\tau}\right) d\tau, \\ k = 1, \dots, n, r = 0, \dots, q$$

In what follows, we give a theoretical background of the reduction method, i.e., derive conditions providing the solvability (starting from some indices  $n$ ) of (5) and the convergence of the approximate solutions ('16) to the exact solution

**Theorem 7** *Let the following conditions be satisfied:*

1. m.f.  $A_r(t), B_r(t)$  and  $K_r(t, \tau), r = 0, \dots, q$ , belong to the space  $[H(\alpha)]_m$ ;
2.  $\det[A_q(t)] \det[B_q(t)] \neq 0$ ;

3. the left partial indexes  $A_q(t)t^q B_q(t)$  of m.f. are equal to zero;

5) m.f.  $[K_r(t, \tau)] (r = 0, \dots, q) \in [H_\beta]_m(\Gamma \times \Gamma), 0 < \beta \leq 1$ , function  $f(t) \in [C(\Gamma)]_m, \Gamma \in C(2; \nu)$ ;

6) the operator  $M : [W_p^{(q)}]_m \rightarrow [L_p(\Gamma)]_m$  is linear and invertible;

Then starting from indices  $n \geq n_1$  and  $\rho$  small enough the SLAE (17) of reduction method is uniquely solvable. The approximate solutions  $x_{n,\rho}(t)$  given by formula (16) converge in the norm of space  $[W_p^{(q)}]_m$  to the exact solution  $(x(t))$  of problem (5)-(7) in sense of:

$$\lim_{n \rightarrow \infty \rho \rightarrow 0} \|x - x_{n,\rho}\|_{p,q}^m = 0. \quad (18)$$

**Proof** Using the conditions of Theorem 7 we have that the operator  $M : [W_{p,q}^{(q)}] \rightarrow [L_p(\Gamma)]_m$  is invertible. We estimate the perturbation of  $M$  depending on  $\rho$ . Using Lemma 6 and the relation  $M_\rho = M_0 + K_\rho$  we obtain

$$\|M - M_\rho\| = O(\rho^{(1-\gamma)/q}), \quad (19)$$

Let us show that the operator  $M_\rho$  is invertible for sufficiently small values  $\rho$ . Using the representation  $M_\rho = M[I - M^{-1}(M - M_\rho)]$  and (19), we obtain from Banach Theorem that the inverse operator  $M_\rho^{-1} = [I - M^{-1}(M - M_\rho)]^{-1} M^{-1}$  exists. The following inequalities hold:

$$\|M_\rho^{-1}\| \leq \frac{\|M^{-1}\|}{1 - q},$$

$$\|M^{-1} - M_\rho^{-1}\| \leq d_{11} \rho^{(1-\gamma)/q} \|M^{-1}\|. \quad (20)$$

The SLAE (17) of the reduction method for SIDE (5) for  $\gamma \in (0; 1)$  is equivalent to the operator equation

$$S_n M_\rho S_n x_{n,\rho} \equiv S_n M_0 S_n x_{n,\rho} + S_n \sum_{r=0}^q \left\{ \frac{1}{2\pi i} \int_{\Gamma} K_{r,\rho}(t, \tau) x_{n,\rho}^{(r)}(\tau) d\tau \right\}$$

$$= S_n f, \tag{21}$$

where  $K_{r,\rho}(t, \tau)$ , ( $r = 0, \dots, q$ ) is defined by formula (9). Using the integral presentation (10), the equation (21) is equivalent to the operator equation

$$U_n \Upsilon_\rho U_n v_{n,\rho} = U_n f, \tag{22}$$

where operator  $\Upsilon_\rho$  is defined in (11), substituting  $\Upsilon$  by  $\Upsilon_\rho$  and  $\frac{h(t, \tau)}{|\tau - t|^\gamma}$  by  $h_\rho(t, \tau)$  (where  $h_\rho(t, \tau)$  is calculated by formula (13)). The equation (22), represents the reduction method for the system of SIE

$$\Upsilon_\rho v_\rho = f, v_\rho(t) \in L_p(\Gamma). \tag{23}$$

We should show that if  $n (\geq n_1)$  is large enough and  $\rho$  small enough the operator  $U_n M_\rho U_n$  is invertible. The operator acts from the subspace  $[X_n]_m = \left\{ t^q \sum_{k=0}^n \xi_{k,\rho} t^k + \sum_{k=-n}^{-1} \xi_{k,\rho} t^k \right\}$  (the norm as in  $[W_p^{(q)}]_m$ ) to the subspace

$$[X_n]_m = \sum_{k=-n}^n r_k t^k, \quad t \in \Gamma.$$

(the norm as in  $[L_p(\Gamma)]_m$ .)

Using formulas (10) the  $\frac{d^q(Px_{n,\rho})(t)}{dt^q}$  and  $\frac{d^q(Qx_{n,\rho})(t)}{dt^q}$  can be represented by Cauchy type integrals with the same density  $v_{n,\rho}(t)$  :

$$\left. \begin{aligned} \frac{d^q(Px_{n,\rho})(t)}{dt^q} &= \frac{1}{2\pi i} \int_\Gamma \frac{v_{n,\rho}(\tau)}{\tau - t} d\tau, & t \in F^+ \\ \frac{d^q(Qx_{n,\rho})(t)}{dt^q} &= \frac{t^{-q}}{2\pi i} \int_\Gamma \frac{v_{n,\rho}(\tau)}{\tau - t} d\tau, & t \in F^- \end{aligned} \right\} \tag{24}$$

Using the formulas

$$(Px)^{(r)}(t) = P(x^{(r)})(t), (Qx)^{(r)}(t) = Q(x^{(r)})(t),$$

and relations (10) we obtain from (24)

$$v_{n,\rho}(t) = \sum_{k=0}^n \frac{(k+q)!}{k!} t^k \xi_{k,\rho} + (-1)^q \sum_{k=1}^n \frac{(k+q-1)!}{(k-1)!} t^{-k} \xi_{-k,\rho}.$$

We obtain from previous relation that  $v_{n,\rho}(t) \in X_n, t \in \Gamma$ . The reduction method for system of SIE was considered in [35] where sufficient conditions for solvability and convergence of this method were obtained. From (24), Lemma 2 and  $v_{n,\rho}(t) \in X_n$  we conclude that if function  $v_{n,\rho}(t)$  is the solution of the equation (22) then the function  $x_{n,\rho}(t)$  is the discrete solution for the system  $U_n M U_n x_{n,\rho} = U_n f$  and vice versa. We can determine the function  $v_{n,\rho}(t)$  from relations (14):

$$\begin{aligned} (Px_{n,\rho})(t) &= \frac{(-1)^q}{2\pi i (q-1)!} \int_\Gamma v_{n,\rho}(\tau) [(\tau - t)^{q-1} \times \\ &\quad \log(1 - \frac{t}{\tau}) + \sum_{k=1}^{q-1} \tilde{\alpha}_k \tau^{q-k-1} t^k] d\tau; \\ (Qx_{n,\rho})(t) &= \frac{(-1)^q}{2\pi i (q-1)!} \times \\ &\quad \int_\Gamma v_{n,\rho}(\tau) \tau^{-q} [(\tau - t)^{q-1} \log(1 - \frac{\tau}{t}) + \\ &\quad \sum_{k=1}^{q-1} \tilde{\beta}_k \tau^{q-k-1} t^k] d\tau; \end{aligned} \tag{25}$$

From the conditions 3),4),6) of Theorem 7, Lemma 3 and Lemma 4, the invertibility of operator  $\Upsilon : [L_p(\Gamma)]_m \rightarrow [L_p(\Gamma)]_m$  follows. From Banach Theorem and Lemma 6 for small numbers  $\rho$ , we have that the operator  $\Upsilon_\rho : [L_p(\Gamma)]_m \rightarrow [L_p(\Gamma)]_m$  is invertible. We should show that for (22) all conditions of the Theorem 1 are satisfied from [35]. Theorem 1[35] gives the convergence of the reduction method for system of SIE in spaces  $[L_p(\Gamma)]_m$ . From condition 3 of Theorem 1[35] and from (12) we obtain the condition 3 of Theorem 7. From the equality

$$[C(t) - D(t)]^{-1} [C(t) + D(t)] = t^q B_q^{-1} A_q(t),$$

we conclude that the index of the function  $[C(t) - D(t)]^{-1} [C(t) + D(t)]$  are equal to zero, which coincides with condition 4 of Theorem 7. Other conditions of Theorem 7 coincide with conditions of Theorem 1[35]. Conditions 1)- 6) in Theorem 7 provide the validity of all conditions of

Theorem 1[35]. Therefore beginning with numbers  $n \geq n_1$  (22) is uniquely solvable and for numbers  $\rho$  small enough. The approximate solutions  $v_{n,\rho}(t)$  of (22) converge to the exact solution of equation (11) in the norm of the space  $[L_p(\Gamma)]_m$  as  $n \rightarrow \infty$ . Therefore the equations (21) and the SLAE (17) have the unique solutions for  $(n \geq n_1)$ . From Theorem 1[35] the following estimation holds:

$$\|v_\rho - v_{n,\rho}\|_p^m \leq O\left(\frac{1}{n^\alpha}\right) + O\left(\omega\left(f; \frac{1}{n}\right)\right) + O\left(\omega^t\left(h; \frac{1}{n}\right)\right), \quad (26)$$

where  $O(\omega^t(h; \frac{1}{n}))$  and  $O(\omega(f; \frac{1}{n}))$  are modulus of continuity. From (10) and (25) we obtain

$$(Px_\rho)^{(q)}(t) = (Pv_\rho)(t), \quad (Qx_\rho)^{(q)}(t) = t^{-q}(Qv_\rho)(t).$$

Therefore we have

$$(Px_{n,\rho})^{(q)}(t) = (Pv_{n,\rho})(t), \\ (Qx_{n,\rho})^{(q)}(t) = t^{-q}(Qv_{n,\rho})(t).$$

We proceed to get an error estimate

$$\|x_\rho - x_{n,\rho}\|_{p,q} = \|x_\rho^{(q)} - x_{n,\rho}^{(q)}\|_{[L_p]} \leq \|P(v_\rho - v_{n,\rho})\|_{[L_p]} + \|t^{-q}Q(v_\rho - v_{n,\rho})\|_{[L_p]} \leq \|P\| \cdot \|v_\rho - v_{n,\rho}\|_{[L_p]} + \|t^{-q}\| \|Q\| \cdot \|v_\rho - v_{n,\rho}\|_{[L_p]} \leq (\|P\| + \|t^{-q}\| \|Q\|) \|v_\rho - v_{n,\rho}\|_{[L_p]}. \quad (27)$$

Using the inequality

$$\|t^{-q}\|_{L_p} = \left(\frac{1}{l} \int_\Gamma |t^{-q}|^p dt\right)^{\frac{1}{p}} = \left(\frac{1}{l} \int_\Gamma |t^{-qp}| dt\right)^{\frac{1}{p}} \leq \left(\frac{1}{l} \frac{1}{\min_{t \in \Gamma} |t|^{pq}} l\right)^{\frac{1}{p}} = \left(\frac{1}{\min_{t \in \Gamma} |t|^{pq}}\right)^{\frac{1}{p}} = c_1,$$

From (26),(27), (20) and from the inequality

$$\|x - x_{n,\rho}\|_{p,q}^m \leq \|M^{-1}f - M_\rho^{-1}\|_{p,q}^m + \|x_\rho - x_{n,\rho}\|_{p,q}^m. \quad (28)$$

we obtain the relation (18). Thus Theorem 7 is proved.

## 6 Conclusion

In this article we studied more general case when the kernel in SIDE (5) contains a weak singularity ( $\gamma \neq 0$ .) Theoretical background was proved in classical Lebesgue spaces. In future we are going to prove theoretical background in for the others functional spaces.

**Acknowledgements:** The research of Iurie Caraus was supported by Fulbright Grant.

### References:

- [1] Beloterkovski S. and Lifanov I., Numerical methods in singular integral equations. Moscow, Nauka: 1985, 256 p. (in Russian)
- [2] Linkov A. and Boundary Integral Equations in Elasticity. Theory Kluwer Academic: Dordrecht ; Boston, 2002, 268 p. Kalandia A., Mathematical methods of two- dimensional elasticity. Mir Publishers: 1975, 351 p.
- [3] J. Cohen and O. Boxma, Boundary value problems in Queueing system analysis, *North- Holland*, Amsterdam (1983),405 p.
- [4] A. Kalandia, Mathematical methods of two- dimensional elasticity, *Mir*, Moscow (1975), 351 p.
- [5] N. Muskhelishvili, Singular integral equations. Boundary problems of function theory and their application to mathematical physics. Translated from the second (1946) Russian edition and with a preface by J. R. M. Radok. Corrected reprint of the 1953 English translation. Dover Publications, Inc., New York, 1992. 447 pp. ISBN: 0-486-66893-2
- [6] N. Muskhelishvili, Some basic problems of the mathematical theory of elasticity. Fundamental equations, plane theory of elasticity, torsion and bending. Translated from



- the fourth, corrected and augmented Russian edition by J. R. M. Radok. Reprint of the second English edition. Noordhoff International Publishing, Leiden, 1977. xxxi+732 pp.
- [7] E. Ladopoulos, Singular Integral Equations: Linear and non-linear theory and its applications in science and engineering, 551p. *Springer*, Berlin, Heidelberg, New York (2000)
- [8] S. Samko, Hypersingular Integrals and Their Applications, *Taylor and Francis*, Series: Analytical Methods and Special Functions, Volume 5, 2002.
- [9] Bardzokas D. and Filshinsky M., Investigation of the direct and inverse piezoeffect in the dynamic problem of electroelasticity for an unbounded medium with a tunnel opening. *ACTA MECHANICA* 2002, 155(1): pp. 17-25.
- [10] Ivanov V., The theory of approximate methods and their application to the numerical solution of singular integral equations. Noordhoff International Publishing, 1976; 330 p.
- [11] Prössdorf S., Some classes of singular equations, Amsterdam; New York: North-Holland Pub. Co; Elsevier, 1978, 417 p.
- [12] F. Gakhov, Boundary value problems, In: Sneddon, I.N. (ed. ) *Pergamon, Oxford; Addison-Wesley*, Reading, MA (1966), 561 p.
- [13] N. Vekua, Systems of singular integral equations. Translated from the Russian by Gibbs, A. G. and Simmons, G.M., Noordhoff, *Groningen Material*. 1967, 216 p.
- [14] I. Gohberg and I. Krupnik, Introduction to the theory of one-dimensional singular integral operators. *Stiintsa*, Kishinev (1973) (in Russian) (German translation: Birkhäuser Verlag, Basel 1979)
- [15] S. Mikhlin and S. Prössdorf, Singular integral operators, *Springer-Verlag*, Berlin, (1986), 528 p.
- [16] Boikov I. and Zhechev I., Approximate solution of singular integrodifferential equations on closed contours of integration. *Journal of Mathematical Sciences*, 41(3).
- [17] Gabdulhaev B., Dzjadik's polynomial approximations for solutions of singular integral and integro-differential equations. *Izv. Vyssh. Uchebn. Zaved. Mat.* 1978, no. 6(193), 51-62. (in Russian)
- [18] Prössdorf S. and Sillbermann B., Numerical analysis for integral and related equations. Akademie-Verlag, Berlin, 1991. 542 pp. ISBN: 3-05-5000696-8.
- [19] Zolotarevskii A., Finite-dimensional methods for solving singular integral equations on closed contours, "Stiintsa", Kishinev, 1991. 136 pp. ISBN: 5-376-01000-7 (in Russian)
- [20] Iurie Caraus and Nikos E. Mastorakis, The Stability of Collocation Methods for Approximate Solution of Singular Integro-Differential Equations. Issue 4, Volume 7, April 2008 WSEAS TRANSACTIONS on MATHEMATICS
- [21] Iurie Caraus and Nikos E. Mastorakis, The Test Examples for Approximate Solution of Singular Integro-Differential Equations by Mechanical Quadrature Methods in Classical Hölder Spaces, 90 STUDIES in MECHANICS, ENVIRONMENT and GEOSCIENCE Proceedings of the 2nd IASME/WSEAS International Conference on CONTINUUM MECHANICS (CM '07) 2nd IASME/WSEAS International Conference on WATER RESOURCES, HYDRAULICS and HYDROLOGY (WHH

- '07), Portorose, Slovenia, May 15-17, 2007  
ISBN: 978-960-8457-70-6 pp. 90-95
- [22] Iurie Caraus and Nikos E. Mastorakis, Convergence of collocation methods for singular integro- differential equations in Lebesgue spaces, Issue 11, Volume 6, 2007, pp. 859-864 WSEAS TRANSACTIONS on MATHEMATICS
- [23] Iurie Caraus and Nikos E. Mastorakis, The Numerical Solution for Singular Integro- Differential Equations in Generalized Holder Spaces Journal title WSEAS TRANSACTIONS ON MATHEMATICS 2006, VOL 5; ISSUE 5, pp. 439-444
- [24] L. Tabara, V.Zolotarevskii, Function approximation by Faber-Laurent Polynomials in classical Holder spaces// Anale stiintifice ale USM. Seria "Sciences of Physics and Mathematics". Chisinau: USM, 1997, pp. 11-15
- [25] Igor Tarata and Vladimir Zolotarevskii, The reduction method in Approximative Solving of Singular Integral Equations in Generalized Holder spaces, Studii in Analiza Numerica si Optimizare, vol. 3, nr.1(5), 2001,pp.102-118.
- [26] Gohberg I, I. A. Feldman, Equations in convolutions and projection methods of their solution.- M.: Nauka, 1971,(in Russian).
- [27] V. Zolotarevski, About the approximate solution of systems of singular integral equations in  $L_p$  spaces// Izv. AN SSRM. Mathematics, 1990, N3. pp.22-26
- [28] V. Seichuk, Direct methods of the solution of singular equations on Lyapunov's contour. PhD thesis in mathematics, Chisinau: Moldova, 1987(in Russian)
- [29] Al-Faqih Feras, Iurie Caraus and Nikos E. Mastorakis, Approximate Solution of Singular Integro-differential Equations by Reduction Methods in Generalized Holder Spaces Journal title WSEAS TRANSACTIONS ON MATHEMATICS 2007, VOL 6; ISSU 4, pp. 595-600 ISSN 1109-2769
- [30] Suetin, P.K., Ryady po mnogochlenam Fabera (Series in Faber Polynomials), Moscow, 1984.
- [31] Yu. Krikunov, Solution of the generalized Riemann boundary problem and linear singular integrodifferential equation. *The scientific notes of the Kazani university*, Kazani, 116(4), (1956) pp.3-29.
- [32] Yu. Krikunov, The general boundary Riemann problem and linear singular integrodifferential equation, *The scientific notes of the Kazani university*, 112(10), 1952, pp.191-199.
- [33] Saks, R.: Boundary- value problems for elliptic systems of differential equations. University of Novosibirsk. Novosibirsk,(1975). (in Russian)
- [34] Seichuk, V. Estimates for weakly singular integral operators defined on closed integration contours and their applications to the approximate solution of singular integral equations. *Differ. Equ.* 41 (2005), no. 9, pp. 1311-1322.
- [35] V. Zolotarevskii, The reduction method for the solution of singular integral equations on the Lyapunove contours.- *Differential Equations*, v.23, N8.-1987.- pp.1416-1422.
- [36] G. Litvinciuk, Solvability of Boundary Value Problem and Singular Integral Equations with Shift, in: *Mathematics and its Applications*, Kluwer Academic Publisher, 2000.