

# Planar Graph Characterization - Using $\gamma$ - Stable Graphs

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*Abstract:* A graph  $G$  is said to be  $\gamma$  - stable if  $\gamma(G_{xy}) = \gamma(G)$ , for all  $x, y \in V(G)$ ,  $x$  is not adjacent to  $y$ , where  $G_{xy}$  denotes the graph obtained by merging the vertices  $x, y$ . In this paper we have provided a necessary and sufficient condition for  $\bar{G}$  to be  $\gamma$  - stable, where  $\bar{G}$  denotes the complement of  $G$ . We have obtained a characterization of planar graphs when  $G$  and  $\bar{G}$  are  $\gamma$  - stable graphs.

*Key-Words:*  $\gamma$  - stable graph, planar, nonplanar, dominating set.

## 1 Introduction

In graph theory, a planar graph is a graph that can be embedded in the plane, that is it can be drawn on the plane in such a way that its edges intersect only at their endpoints. In other words, it can be drawn in such a way that no edges cross each other [13].

Planarity of graph is related with various properties. Tilings appears in many fields such as architecture, crystal structure etc. In [7], Hao Li has obtained some properties of planar normal tiling. In [6], Gurami Tsitsiashvili and Marina Osipova have discussed the asymptotic analysis of connectivity probability in random planar graphs. Pulley blank has proved that deciding whether a graph is supereulerian within planar graphs is NP-complete[9]. Hong-Jian Lai, Yehong Shao and Huiya Yan have provided a survey on supereulerian graph [9]. In[11], C. H. C. Little and G. Sanjith have provide a new characterization of planar graphs that concerns the structure of the cocycle space of a graph.

Characterizing planar graphs based on graph properties is a common problem discussed by various authors. In [2], By Joseph Battle, Frank Harary and Yukihiro Kodama have proved that every planar graph with nine points has a nonplanar complement. In[1], Jin Akiyama and Frank Harary have characterized all graphs for which  $G$  and  $\bar{G}$  are outerplanar.

In [4], Rosa I. Enciso and Ronald D. Dutton have classified planar graph based on the complement of  $G$ . They have proved the following result.

**R<sub>1</sub>.** If  $G$  is a planar graph,  $\gamma(\bar{G}) \leq 4$ .

In this paper we have characterized planar graphs based on the property of  $\bar{G}$ .

## 2 Terminology

We consider only simple connected undirected graphs  $G = (V, E)$ . The open neighborhood of vertex  $v \in V(G)$  is defined by  $N(v) = \{u \in V(G) | uv \in E(G)\}$ , while its closed neighborhood is the set  $N[v] = N(v) \cup \{v\}$ . We say that  $H$  is a subgraph of  $G$ , if  $V(H) \subseteq V(G)$  and  $uv \in E(H)$  implies  $uv \in E(G)$ . If a subgraph  $H$  satisfies the added property that for every pair  $u, v$  of vertices,  $uv \in E(H)$  if and only if  $uv \in E(G)$ , then  $H$  is called an induced subgraph of  $G$  and is denoted by  $\langle H \rangle$ . Two graphs are said to be homeomorphic if one graph can be obtained from the other by the creation of edges in series ( that is by insertion of vertices of degree two ) or by the merger of edges in series. In the literature of graph theory,  $K_5$  and  $K_{3,3}$  are called Kuratowski's graph.

An elementary contraction of a graph  $G$  is obtained by identifying two adjacent points  $u$  and  $v$ , that is by the removal of  $u$  and  $v$  and the addition of a new point  $w$  adjacent to those points to which  $u$  or  $v$  was adjacent. A graph  $G$  is contractible to a graph  $H$  if  $H$  can be obtained from  $G$  by a sequence of elementary contractions[5]. For properties related to graph theory we refer to F. Harary [5]. We indicate that  $u$  is adjacent to  $v$  by writing  $u \perp v$  [3].

A set of vertices  $D$  in a graph  $G = (V, E)$  is a dominating set if every vertex of  $V - D$  is adjacent to some vertex of  $D$ . If  $D$  has the smallest possible cardinality of any dominating set of  $G$ , then  $D$  is called a minimum dominating set - abbreviated MDS. The cardinality of any MDS for  $G$  is called the domination number of  $G$  and it is denoted by  $\gamma(G)$ . A  $\gamma$  - set denotes a dominating set for  $G$  with minimum cardinality. The private neighborhood of  $v \in D$  is defined by  $pn[v, D] = N(v) - N(D - \{v\})$ . For properties

related to domination we refer to T. W. Haynes, S. T. Hedetniemi, and P. J. Slater [8].

### 3 Results and Discussions

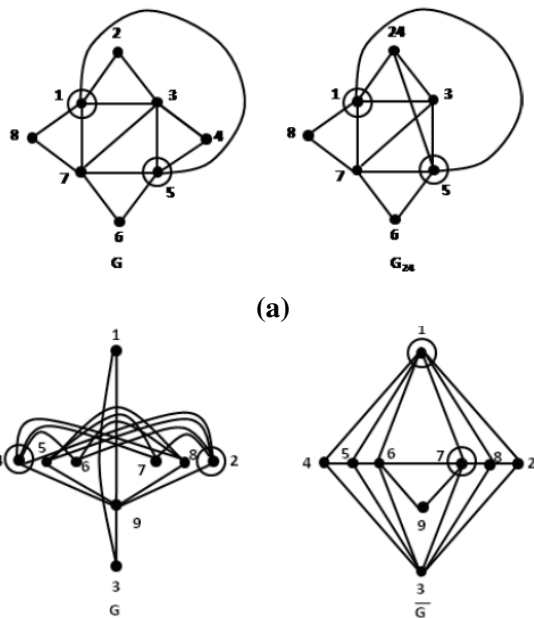
In [14], M. Yamuna and K. Karthika defined  $\gamma$  - stable graphs. A graph  $G$  is said to be  $\gamma$  - stable if  $\gamma(G_{xy}) = \gamma(G)$ , for all  $x, y \in V(G)$ ,  $x$  is not adjacent to  $y$ , where  $G_{xy}$  denotes the graph obtained by merging the vertices  $x, y$

They have proved the following results.

**R<sub>2</sub>.** A graph  $G$  is  $\gamma$  - stable if and only if every  $\gamma$  - set  $D$  of  $G$  is a clique.

**R<sub>3</sub>.** If  $G$  is  $\gamma$  - stable, then  $pn[u, D] \geq 2$ , for all  $u \in V(G)$ .

In all the figures encircled vertices denotes a  $\gamma$  - set.



(a)  
(b)  
**Fig.1**

In Fig. 1(a),  $G_{24}$  denote the graph obtained by merging the nonadjacent vertices 2 and 4,  $\gamma(G) = \gamma(G_{24})$ . This is true for all  $x, y \in V(G)$ ,  $x$  is not adjacent to  $y$ , which implies  $G$  is  $\gamma$  - stable.

The graph in Fig. 1 (a) is self complement, that is  $G, \bar{G}$  are  $\gamma$  - stable,  $G$  planar. In Fig.1 (b)  $G, \bar{G}$  are  $\gamma$  - stable,  $G$  nonplanar. We observe that when  $G$  and  $\bar{G}$  are  $\gamma$  - stable graphs  $G$  may or may not be planar.

In this paper we focus on obtaining conditions under which  $\bar{G}$  is  $\gamma$  - stable and hence use it for characterizing planarity of  $\gamma$  - stable graphs.

**Theorem 1** For any graph  $G$  such that  $\gamma(\bar{G}) = k, \bar{G}$  is  $\gamma$  - stable if and only if

1. there is at least one set of  $k$  - independent vertices  $S \subseteq V(G)$  such that there is no  $v \in V - S, v$  adjacent to all vertices in  $S$ .
2. for all  $k$  - non - independent vertices  $S$  in  $G$ , there is at least one  $v \in V - S, v$  adjacent to all vertices in  $S$ .

**Proof:** Assume that  $\bar{G}$  is a  $\gamma$  - stable graph such that  $\gamma(\bar{G}) = k$ . We know that any  $\gamma$  - set in  $\bar{G}$  is a clique. Let  $S = \{v_1, v_2, \dots, v_k\}$  be a  $\gamma$  - set in  $\bar{G}$ .  $\langle S \rangle$  is a clique in  $\bar{G}$ , which implies there is no adjacency between these vertices in  $G$ , that is  $S$  is independent with respect to  $G$ . Assume that there is a vertex  $v \in V(G) - S(G)$  such that  $v$  adjacent to all vertices in  $S$ . This means that, in  $\bar{G}$  vertex  $v$  is not adjacent to any vertex in  $S$ , a contradiction as  $S$  is a  $\gamma$  - set in  $\bar{G}$ . Hence condition 1 is true.

Let  $S = \{u_1, u_2, \dots, u_k\}$  be a set of non - independent vertices in  $G$ . Assume that there is no  $v \in V - S$  such that  $v$  adjacent to all vertices in  $S$ . This means that in  $\bar{G}$ , every  $v \in V - S$  is adjacent to at least one vertex in  $S$ , that is  $S$  is a  $\gamma$  - set with respect to  $\bar{G}$ . Since  $S$  is a non - independent set in  $G$ , there is at least one  $u_i, u_j \in S(G)$  such that  $u_i \perp u_j$ . This means that there is no edge between  $u_i$  and  $u_j$  in  $\bar{G}$ , a contradiction as  $\bar{G}$  is  $\gamma$  - stable and  $S$  is a  $\gamma$  - set with respect to  $\bar{G}$ . Hence condition 2 is satisfied.

Conversely, let  $G$  be a graph such that

- i.  $\gamma(\bar{G}) = k$
- ii. condition 1 and 2 of the theorem satisfied.

We have to prove that  $\bar{G}$  is  $\gamma$  - stable, that is we need to prove every  $\gamma$  - set of  $\bar{G}$  is a clique [ by  $R_2$  ]. Let  $S(G) = \{v_1, v_2, \dots, v_k\}$  be a set of vertices that satisfies condition 1. Since  $S$  is independent in  $G$ ,  $\langle S \rangle$  is a clique with respect to  $\bar{G}$ . Since there is no  $v \in V(G) - S(G), v$  adjacent to all vertices in  $S(G)$ , every  $v \in V(G) - S(G)$  is adjacent to at least one vertex in  $S$ , that is  $S$  is a  $\gamma$  - set in  $\bar{G}$ .

Let  $S = \{u_1, u_2, \dots, u_k\}$  be a set of vertices in  $G$ , that satisfies condition 2. Since  $S$  is non - independent in  $G$ ,  $\langle S \rangle$  cannot be a clique in  $\bar{G}$ . Since there is atleast one  $v \in V(G) - S(G), v$  adjacent to all vertices in  $S(G)$ ,  $v$  is not adjacent to any vertex in  $S(\bar{G})$ , that is  $S$  is not a  $\gamma$  - set with respect to  $\bar{G}$ . This is true for every set  $S(\bar{G})$  such that

- i.  $\langle S(\bar{G}) \rangle$  is not a clique,
- ii.  $|S(\bar{G})| = k$ ,

that is there is no  $\gamma$  - set that is not a clique in  $\bar{G}$ .

From the above discussion we conclude that every  $\gamma$  - set of  $\bar{G}$  is a clique. □

**Theorem 2** Let  $G$  and  $\bar{G}$  be  $\gamma$  - stable graphs such that  $\gamma(G) = k, \gamma(\bar{G}) = m, m > k$ . Then every  $m - 1, m - 2, \dots, 2$  independent vertices in  $G$  are collectively adjacent to atleast two vertices in  $G$ .

**Proof:** Let  $G$  and  $\bar{G}$  be  $\gamma$  - stable graphs. Let  $\gamma(\bar{G}) = D = \{x_1, x_2, \dots, x_m\}$  and let  $Z = \{v_1, v_2, \dots, v_p\}$  be a set of independent vertices in  $G$ , where  $p \in [m - 1, m - 2, \dots, 2]$ .

If possible assume that the vertices in  $Z$  are collectively adjacent to one vertex say  $x \in V(G)$ . In  $\bar{G}, \langle v_1, v_2, \dots, v_p \rangle$  is a clique. In  $\bar{G}, Z$  dominates  $V(\bar{G}) - \{x\}$ , which implies  $Z \cup \{x\}$  is a dominating set for  $\bar{G}, |Z \cup \{x\}| \leq m, x$  selfish.  $\langle Z \cup \{x\} \rangle$  is not a clique in  $\bar{G}$ .

If  $|Z \cup \{x\}| < m$ , then  $\{Z \cup \{x\}\}$  dominates  $\bar{G}$  such that  $|Z \cup \{x\}| < m$ , a contradiction as  $\gamma(\bar{G}) = m$ .

If  $|Z \cup \{x\}| = m$ , then since  $\langle Z \cup \{x\} \rangle$  is not a clique, we get a contradiction to our assumption that  $\bar{G}$  is a  $\gamma$  - stable graph.

So every  $m - 1, m - 2, \dots, 2$  independent vertices in  $G$  are collectively adjacent to atleast two vertices in  $G$ .  $\square$

### 4 Planar Characterization of $\gamma$ - Stable Graphs

We recollect the following famous theorem on planar graphs.

**R<sub>4</sub>.** A necessary and sufficient condition for a graph  $G$  to be planar is that  $G$  does not contain either of Kuratowski's two graphs or any graph homeomorphic to either of them.

**R<sub>5</sub>.** A graph is planar if and only if it does not have a subgraph contractible to  $K_5$  or  $K_{3,3}$ . [5]

We shall prove that a  $\gamma$  - stable graph is planar or nonplanar using  $R_4$  and  $R_5$ .

If  $\gamma(G) = 1$ , then  $\bar{G}$  is disconnected and hence  $\bar{G}$  is not a  $\gamma$  - stable graph. Also by  $R_1$ , if  $G$  is a planar graph,  $\gamma(G) \leq 4$ . So in the remaining part of this section we restrict our discussion to cases where  $1 < \gamma(G) \leq 4, 1 < \gamma(\bar{G}) \leq 4$ .

We shall use the following results of Theorem 1 and 2 frequently.

- i. If  $\gamma(\bar{G}) = k$ , then every  $k$  - non - independent vertices in  $G$  are collectively adjacent to atleast one vertex in  $G$ .
- ii. If  $G, \bar{G}$  are  $\gamma$  - stable,  $\gamma(G) = k, \gamma(\bar{G}) = m, m > k$ , then every  $m - 1, m - 2, \dots, 2$  independent vertices in  $G$  are collectively adjacent to atleast two vertices in  $G$ .

In all figures, in the remaining part of the discussion,

- i. --- represents the newly added edges in the current discussion.
- ii. When we use edge contraction, a vertex receives a label of the contracted vertices. For example  $y : bb_1x_1x_2$  means that the contracted edges are  $bb_1, b_1x_1, x_1x_2$  and is assigned the new label as  $b$ .
- iii. If  $a, b, c, \dots$  denote graphs in figures, then  $a', b', c', \dots$  denotes subgraphs of  $a, b, c, \dots$  respectively [  $a', b', c', \dots$  are either  $K_5$  or  $K_{3,3}$  ].

All cases and subcases are supported with graphs along with the discussion.

**Theorem 3** If  $G$  and  $\bar{G}$  are  $\gamma$  - stable graphs such that  $\gamma(G) \leq 4$  and  $\gamma(\bar{G}) = 4$ , then  $G$  is nonplanar.

**Proof: Case 1:**  $\gamma(G) = 2, \gamma(\bar{G}) = 4$ .

Let  $\gamma(G) = D = \{a, b\}$ . Since  $G$  is  $\gamma$  - stable,  $pn[u, D] \geq 2$ , for all  $u \in D$  [ by  $R_3$  ]. Let  $\{a_1, a_2\} \in pn[a, D], \{b_1, b_2\} \in pn[b, D]$ .  $\langle a_1, a, b, b_1 \rangle$  is non - independent in  $G, \gamma(\bar{G}) = 4$ . There is a vertex  $x \in V(G)$  such that  $x \perp (a_1, a, b, b_1)$  [ Since  $a_2 \in pn[a, D], b_2 \in pn[b, D], x \neq a_2, b_2$  ].

$\langle x, a, b, a_1 \rangle$  is non - independent in  $G$ . So, there is one  $y \in V(G)$  such that  $y \perp (x, a, b, a_1)$  [ Since  $a_2 \in pn[a, D], \{b_1, b_2\} \in pn[b, D], x \neq a_2, b_1, b_2$  ].

Similarly  $\langle x, a, b, y \rangle$  is non - independent, there is one  $z \in V(G)$  such that  $z \perp (x, a, b, y)$  [ Since  $\{a_1, a_2\} \in pn[a, D], \{b_1, b_2\} \in pn[b, D], x \neq a_1, a_2, b_1, b_2$  ].  $\langle a, b, x, y, z \rangle$  is  $K_5$ , which is a subgraph of  $G$  as seen in Fig. 2 implies  $G$  is nonplanar.

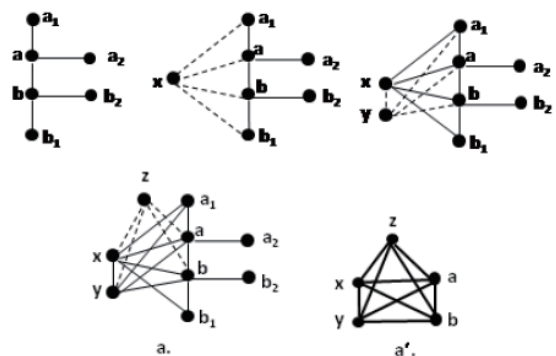


Fig. 2

**Case 2:**  $\gamma(G) = 3, \gamma(\bar{G}) = 4$ .

Let  $\gamma(G) = D = \{a, b, c\}$  be a  $\gamma$  - set for  $G$ . Since  $G$  is  $\gamma$  - stable,  $pn[u, D] \geq 2$ , for all  $u \in D$  [ by  $R_3$  ]. Let  $\{a_1, a_2\} \in pn[a, D], \{b_1, b_2\} \in pn[b, D]$  and  $\{c_1, c_2\} \in pn[c, D]$ .

$\langle a_1, a, b, c \rangle$  is non-independent in  $G, \gamma(\bar{G}) = 4$ , there is a vertex  $x \in V(G)$  such that  $x \perp (a_1, a, b, c)$  [ Since  $a_2 \in pn[a, D], \{b_1, b_2\} \in pn[b, D]$  and  $\{c_1, c_2\} \in pn[c, D], x \neq a_2, b_1, b_2, c_1, c_2$ ].

$\langle x, a, b, c \rangle$  is non-independent in  $G$ , there is a vertex  $y$  such that  $y \perp (x, a, b, c)$  [ Since  $\{a_1, a_2\} \in pn[a, D], \{b_1, b_2\} \in pn[b, D]$  and  $\{c_1, c_2\} \in pn[c, D], y \neq a_1, a_2, b_1, b_2, c_1, c_2$ ].

So,  $\langle x, y, a, b, c \rangle$  is  $K_5$ , which is a subgraph of  $G$  as seen in Fig. 3 implies  $G$  is nonplanar.

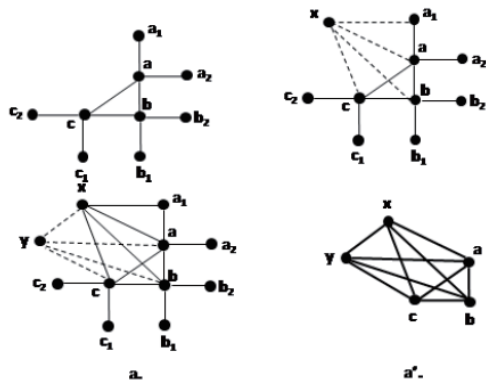


Fig.3

**Case 3:**  $\gamma(G) = 4$  and  $\gamma(\bar{G}) = 4$ .

Let  $\gamma(G) = \{a, b, c, d\}$ .  $\langle a, b, c, d \rangle$  is non-independent in  $G, \gamma(G) = 4$ . There is a vertex  $x \in V(G)$  such that  $x \perp (a, b, c, d)$ , that is  $\langle a, b, c, d, x \rangle$  is  $K_5$  as seen in Fig. 4 implies  $G$  is nonplanar.

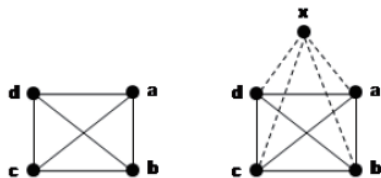


Fig.4

From case 1, 2 and 3 we conclude that, if  $G$  and  $\bar{G}$  are  $\gamma$ -stable graphs such that  $\gamma(G) \leq 4$  and  $\gamma(\bar{G}) = 4$ , then  $G$  is nonplanar.  $\square$

**Theorem 4** If  $G$  and  $\bar{G}$  are  $\gamma$ -stable graphs such that  $\gamma(G) \leq 4$  and  $\gamma(\bar{G}) = 3$ , then  $G$  is nonplanar.

**Proof:** We prove the following claims to prove the theorem.

**Claim 1:** If  $\gamma(G) = 2, \gamma(\bar{G}) = 3$ , then  $G$  is nonplanar.

**Proof:** Let  $\gamma(G) = D = \{a, b\}$ . Since  $G$  is  $\gamma$ -stable,  $pn[u, D] \geq 2$ , for all  $u \in D$  [ by R3 ]. Let  $\{a_1, a_2\} \in pn[a, D], \{b_1, b_2\} \in pn[b, D]$ .  $\langle a, b, a_1$

is non-independent in  $G, \gamma(\bar{G}) = 3$ , there is a vertex  $x_1 \in V(G)$  such that  $x_1 \perp (a, b, a_1)$ . [ Since  $a_2 \in pn[a, D], \{b_1, b_2\} \in pn[b, D], x_1 \neq a_2, b_1, b_2$ ].

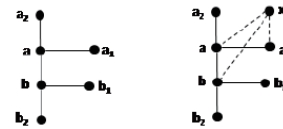


Fig.5

$\langle a, a_1, x_1 \rangle$  is non-independent, there is one vertex adjacent to these vertices. Note that this common vertex cannot be  $b, b_1, b_2$  [ Since  $a_1 \in pn[a, D], \{b_1, b_2\} \in pn[b, D]$ ]. So, the common vertex is either  $a_2$  or any other vertex ( say  $x_3$ ).

**Case 1 :**  $a, a_1, x_1 \perp a_2$

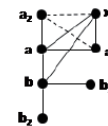


Fig.6

$\langle a_2, x_1, b_2 \rangle$  is non-independent. The common adjacent vertex can be  $a_1, b_1$ , or any vertex say  $x_2$ .

**Subcase 1:**  $a_2, x_1, b_2 \perp a_1$

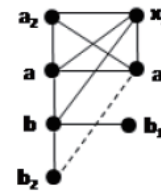


Fig.7

A. If  $a_2 \perp b_2$ , then contracting the edge  $bb_2, \langle a, b, a_1, a_2, x_1 \rangle$  is  $K_5$  as seen in Fig. 8 implies  $G$  is nonplanar.

B. If  $a_2$  is not adjacent to  $b_1, b_2$ , since  $a_2, b_1$  and  $a_2, b_2$  are independent in  $G$ , by Theorem 2, there is at least two vertices common to  $a_2, b_1$  and  $a_2, b_2$ . These two common vertices can be  $x_1, a_1$ .

a.  $a_2, b_1 \perp x_1, a_1$  and  $a_2, b_2 \perp x_1, a_1$ .  $a'$  is  $K_{3,3}$  as seen in Fig. 9 implies  $G$  is nonplanar.

b.  $a_2, b_1$  and  $a_2, b_2$  is not adjacent to  $a_1, x_1$ . This means that,  $a_2, b_1$  and  $a_2, b_2$  are adjacent to some vertex in  $G$ . Let  $a_2, b_1$  be adjacent to some  $y \in V(G)$ .

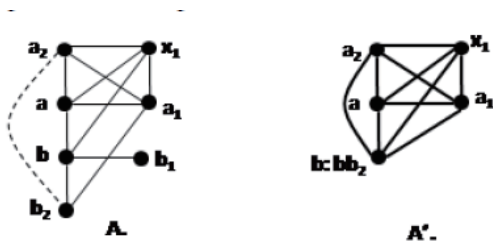


Fig.8

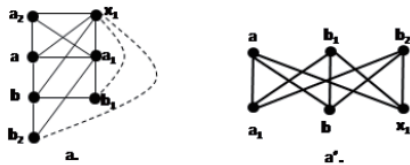


Fig.9

Contracting edges  $yb_1, b_1b$  and  $bb_2, \langle a, b, a_1, a_2, x_1 \rangle$  is  $K_5$  as seen in Fig. 10 implies  $G$  is nonplanar.

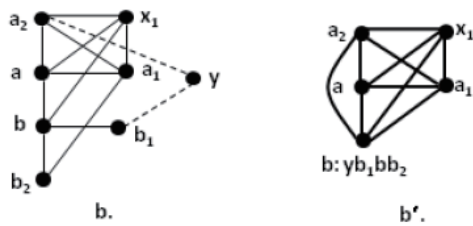


Fig.10

Similarly if there is any  $y \in V(G) \perp a_2, b_2, \langle a, b, a_1, a_2, x_1 \rangle$  is  $K_5$  implies  $G$  is nonplanar.

**Subcase 2:**  $a_2, x_1, b_2 \perp b_1$

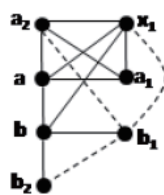


Fig.11

A. If  $a_1 \perp b_2$ , then contracting the edges  $b_1b$  and  $bb_2, \langle a, b, a_1, a_2, x_1 \rangle$  is  $K_5$  as seen in Fig. 12 implies  $G$  is non planar.

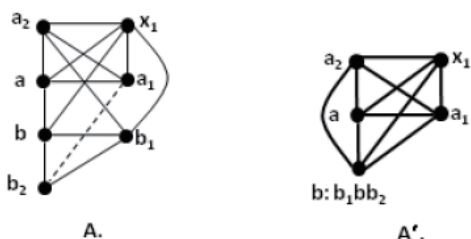


Fig.12

B. If  $a_1$  is not adjacent to  $b_2$ , then by Theorem 2  $a_1, b_2$  are adjacent to at least two vertices. The different possible cases is discussed in a to c.

a. If  $a_1, b_2 \perp a_2, x_1$ , then  $a'$  is  $K_{3,3}$  as seen in Fig. 13 implies  $G$  is nonplanar.

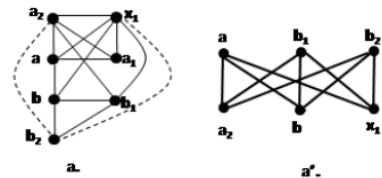


Fig.13

b. If  $a_1, b_2 \perp a_2, b_1$ , then contracting the edges  $b_1b$  and  $bb_2, \langle a, b, a_1, a_2, x_1 \rangle$  is  $K_5$  as seen in Fig. 14 implies  $G$  is nonplanar.

c. If  $a_1, b_2 \perp x_1, b_1$ , then contracting the edges  $b_1b$  and  $bb_2, \langle a, b, a_1, a_2, x_1 \rangle$  is  $K_5$  as seen in Fig. 14 implies  $G$  is nonplanar.

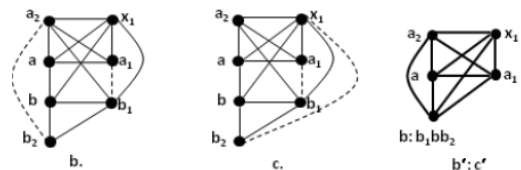


Fig.14

C. If  $a_1, b_2$  are adjacent to some  $y \in V(G)$ , then contracting the edges  $b_1b, bb_2, b_2y, \langle a, b, a_1, a_2, x_1 \rangle$  is  $K_5$  as seen in Fig. 15 implies  $G$  is nonplanar.

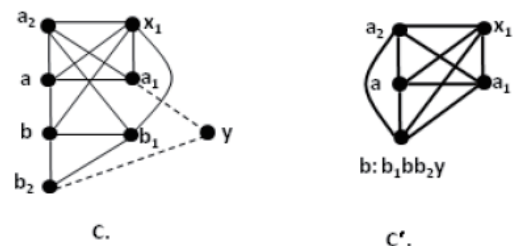


Fig.15

**Subcase 3:**  $a_2, x_1, b_2$  are adjacent to some  $x_2 \in V(G)$ .

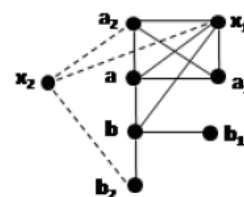


Fig.16

- A. If  $a_1 \perp b_2$ , then contracting the edges  $x_2b_2, b_2b$ ,  $\langle a, b, a_1, a_2, x_1 \rangle$  is  $K_5$  as seen in Fig. 17 implies  $G$  is nonplanar.

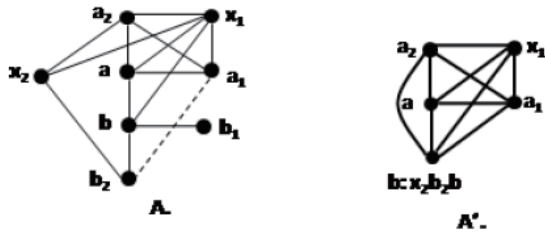


Fig.17

- B. If  $a_1$  is not adjacent to  $b_2$ , then by Theorem 2  $a_1, b_2$  are adjacent to at least two vertices. The different possible cases is discussed in a to g.

- a.  $a_1, b_2 \perp a_2, x_1$

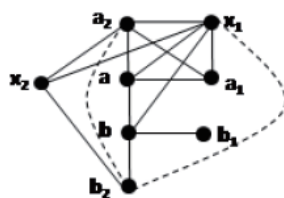


Fig.18

$x_2$  is dominated either by  $a$  or  $b$ .

- $a_1$ . If  $x_2 \perp a$ , then  $a_1'$  is  $K_{3,3}$  implies  $G$  is nonplanar.  
 $a_2$ . If  $x_2 \perp b$ , then contracting the edge  $ab$  we see that  $a_2'$  is  $K_{3,3}$  implies  $G$  is nonplanar.

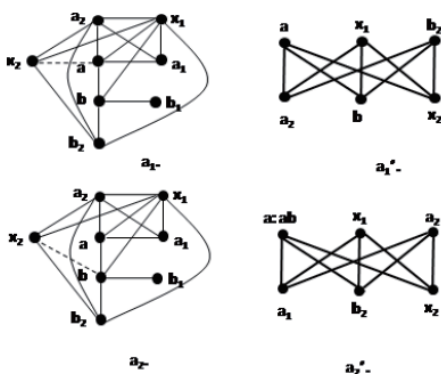


Fig.19

- b. If  $a_1, b_2 \perp a_2, b_1$ , then contract the edges  $b_1b_2, b_2b$ .  
 c. If  $a_1, b_2 \perp x_1, b_1$ , then contract the edges  $x_2b_2, b_2b, bb_1$ .  
 d. If  $a_1, b_2 \perp b_1, x_2$ , then contract the edges  $x_2b_2, b_2b$ .

- e. If  $a_1, b_2 \perp a_2, x_2$ , then contract the edges  $x_2b_2, b_2b$ .  
 f. If  $a_1, b_2 \perp x_1, x_2$ , then contract the edges  $x_2b_2, b_2b$ .  
 g. If  $a_1, b_2$  are adjacent to some vertex  $y \in V(G)$ , then contract edges  $x_2b_2, b_2b, b_2y$ .

In all cases from b to g,  $\langle a, b, a_1, a_2, x_1 \rangle$  is  $K_5$  as seen in Fig. 20 implies  $G$  is nonplanar.

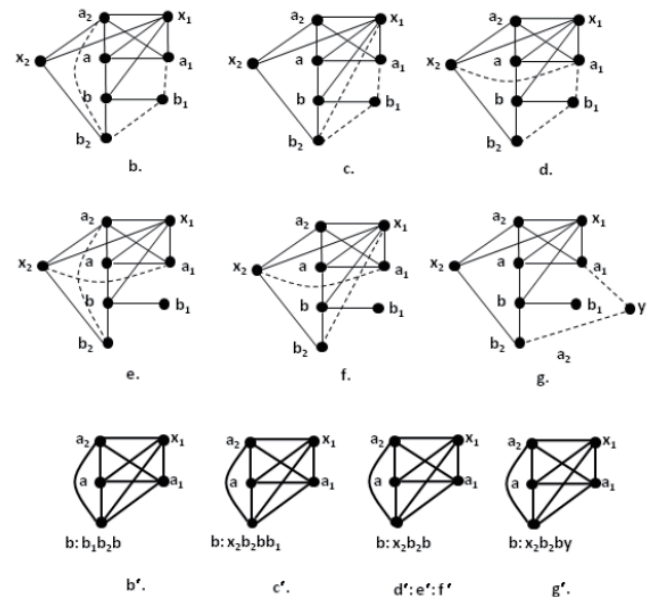


Fig.20

Case 2:  $a, a_1, x_1 \perp x_3$

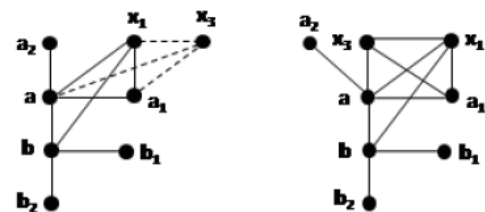


Fig.21

$\langle x_3, x_1, b_2 \rangle$  is non-independent. So,  $x_3, x_1, b_2$  are collectively adjacent to either  $a_1, a_2, b, b_1$  or some  $x_4 \in V(G)$ .

Subcase 1:  $x_3, x_1, b_2 \perp a_1$

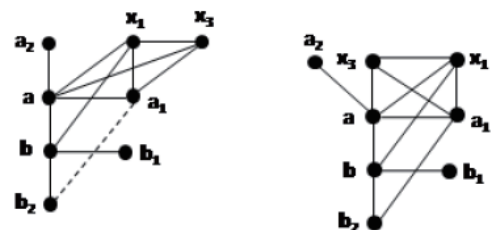
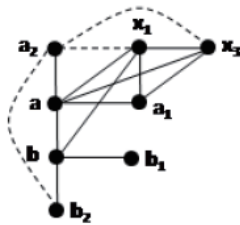


Fig.22

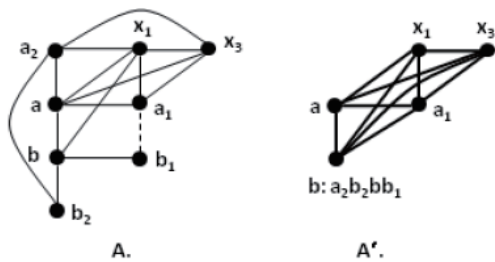
The graph in Fig. 22 is isomorphic to graph in Fig. 7 of subcase 1 of case 1. So, the discussion is analogues to subcase 1 of case 1.

**Subcase 2:**  $x_3, x_1, b_2 \perp a_2$



**Fig.23**

A. If  $a_1 \perp b_1$ , then contracting the edge  $a_2b_2, b_2b, bb_1, \langle a, b, a_1, x_1, x_3 \rangle$  is  $K_5$  as seen in Fig. 24 implies  $G$  is nonplanar.

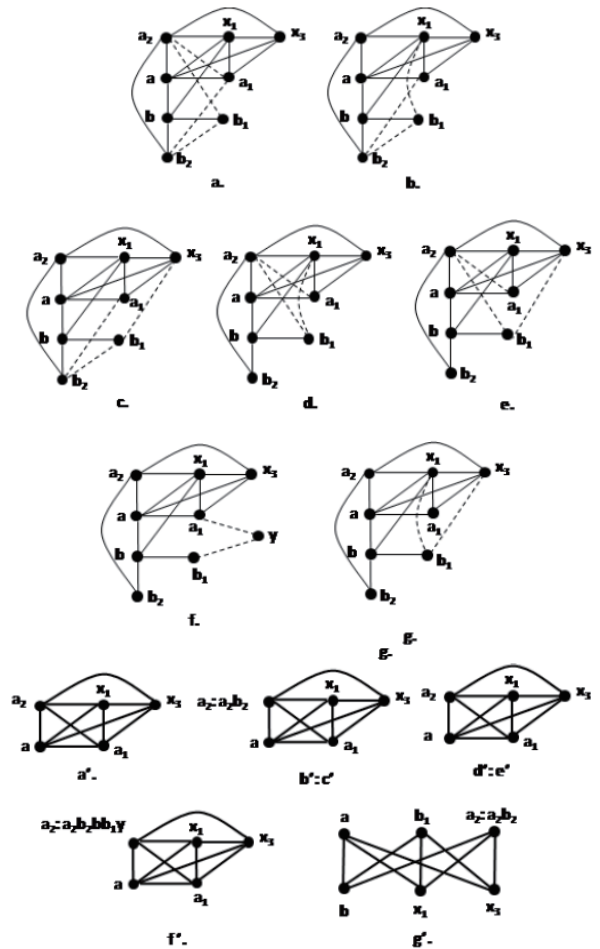


**Fig.24**

B. If  $a_1$  is not adjacent to  $b_1$ , then by Theorem 2  $a_1, b_1$  are adjacent to at least two vertices. The different possible cases is discussed in a to g.

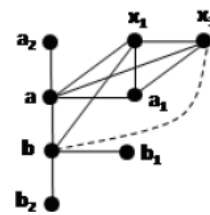
- a. If  $a_1, b_1 \perp b_2, a_2$ , then  $\langle a, a_1, a_2, x_1, x_3 \rangle$  is  $K_5$ .
- b. If  $a_1, b_1 \perp b_2, x_1$ , then contract the edge  $a_2b_2$ .
- c. If  $a_1, b_1 \perp b_2, x_3$ , then contract the edge  $a_2b_2$ .
- d. If  $a_1, b_1 \perp a_2, x_1$ , then  $\langle a, a_1, a_2, x_1, x_3 \rangle$  is  $K_5$ .
- e. If  $a_1, b_1 \perp a_2, x_3$ ,  $\langle a, a_1, a_2, x_1, x_3 \rangle$  is  $K_5$ .
- f. If  $a_1, b_1 \perp y$ , then contract the edges  $a_2b_2, b_2b, bb_1, b_1y$ .
- g. If  $a_1, b_1 \perp x_1, x_3$ , then contracting the edge  $a_2b_2$ , we see that  $g'$  is  $K_{3,3}$ .

In cases a to f,  $\langle a, a_1, a_2, x_1, x_3 \rangle$  is  $K_5$  and  $g'$  is  $K_{3,3}$  as seen in Fig. 25 implies  $G$  is nonplanar.



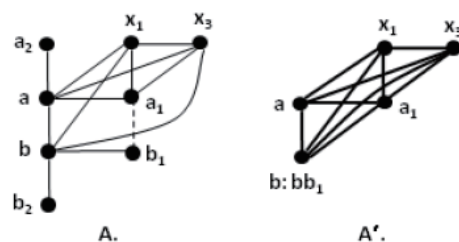
**Fig.25**

**Subcase 3:**  $x_3, x_1, b_2 \perp b$ .



**Fig.26**

A. If  $a_1 \perp b_1$ , then contracting the edge  $bb_1, \langle a, b, a_1, x_1, x_3 \rangle$  is  $K_5$  as seen in Fig. 27 implies  $G$  is nonplanar.



**Fig.27**

B. If  $a_1$  is not adjacent to  $b_1$ , then by Theorem 2,  $a_1, b_1$  are adjacent to at least two vertices. The different possible cases is discussed in  $a$  to  $g$ .

- a. If  $a_1, b_1 \perp b_2, a_2$ , then contract the edge  $bb_2$ .
- b. If  $a_1, b_1 \perp b_2, x_1$ , then contract the edge  $bb_2$ .
- c. If  $a_1, b_1 \perp b_2, x_3$ , then contract the edge  $bb_2$ .
- d. If  $a_1, b_1 \perp a_2, x_1$ , then contract the edges  $a_2b_1, b_1b$ .
- e. If  $a_1, b_1 \perp a_2, x_3$ , then contract the edges  $a_2b_1, b_1b$ .
- f. If  $a_1, b_1 \perp y$ , then contract the edges  $yb_1, b_1b$ .

In case  $a$  to  $f$ ,  $\langle a, b, a_1, x_1, x_3 \rangle$  is  $K_5$  implies  $G$  is nonplanar.

If  $a_1 \perp b_2$ , then contracting the edge  $b_2b$ ,  $\langle a, b, a_1, x_1, x_3 \rangle$  is  $K_5$  implies  $G$  is nonplanar. If  $a_1$  is not adjacent to  $b_2$ , then  $a_1, b_1$  and  $a_1, b_2$  are pair of independent vertices. By Theorem 2, these vertices are collectively adjacent to at least two vertices. In all possible combinations except the case when  $a_1, b_1, b_2$  are collectively adjacent to  $x_1, x_3$ ,  $\langle a, b, a_1, x_1, x_3 \rangle$  is  $K_5$  implies  $G$  is nonplanar as in cases  $a$  to  $f$ .

- g. If  $a_1, b_1, b_2 \perp x_1, x_3$ , then  $g'$  is  $K_{3,3}$  implies  $G$  is nonplanar.

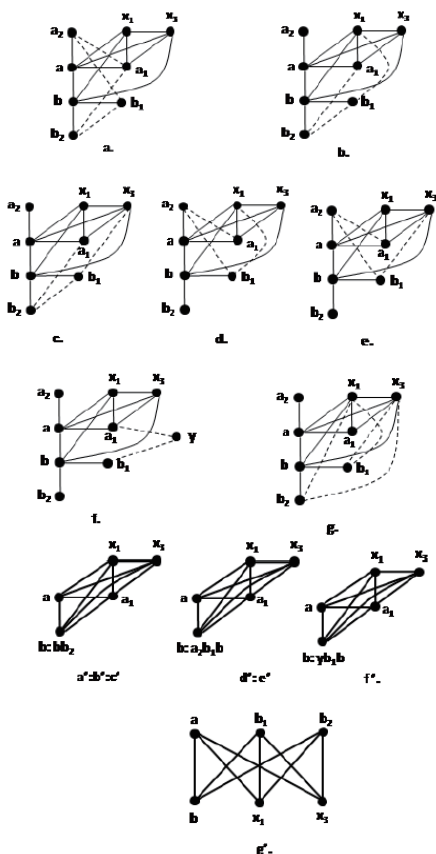


Fig.28

Subcase 4:  $x_3, x_1, b_2 \perp b_1$ .

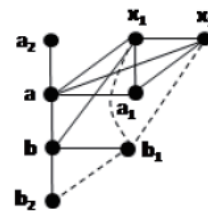


Fig.29

The graph in Fig. 29 is isomorphic to graph in Fig. 11 of subcase 2 of case 1. So, the discussion is analogues to subcase 2 of case 1.

Subcase 5:  $x_3, x_1, b_2 \perp x_4$ .

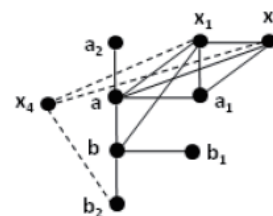


Fig.30

The graph in Fig. 30 is isomorphic to graph in Fig. 16 of subcase 3 of case 1. So, the discussion is analogues to subcase 3 of case 1.

By case 1 and case 2, we conclude that  $G$  is nonplanar.

**Claim 2** If  $G$  and  $\bar{G}$  are  $\gamma$ -stable graphs such that  $\gamma(G) = \gamma(\bar{G}) = 3$ , then  $G$  is nonplanar.

**Proof:** Let  $\gamma(G) = D = \{a, b, c\}$ . Since  $G$  is  $\gamma$ -stable,  $pn[u, D] \geq 2$ , for all  $u \in D$  [by  $R_3$ ]. Let  $\{a_1, a_2\} \in pn[a, D], \{b_1, b_2\} \in pn[b, D]$  and  $\{c_1, c_2\} \in pn[c, D]$ . Since  $\langle a, b, c \rangle$  is non-independent,  $\gamma(\bar{G}) = 3$ , there is a vertex  $x_1 \in V(G)$  such that  $x_1 \perp (a, b, c)$  [Since  $a_1 \in pn[a, D], b_1 \in pn[b, D]$  and  $c_1 \in pn[c, D], x_1 \neq a_1, b_1, c_1$ ]. Since  $\langle a_1, a, x_1 \rangle$  is non-independent, let  $x_2 \perp (a_1, a, x_1)$  [Since  $a_1 \in pn[a, D], b_1 \in pn[b, D]$  and  $c_1 \in pn[c, D], x_2 \neq b, b_1, c_1$ ].

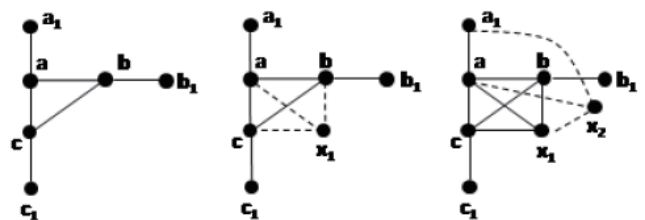


Fig.31



Since  $\langle x_1, x_2, b_1 \rangle$  is non-independent, there is atleast one vertex adjacent to them. The common vertex could be  $b, a_1, c_1$  or any  $x_j \in V(G)$ .

**Case 1:**  $x_1, x_2, b_1 \perp b$

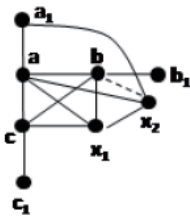


Fig.32

$\langle x_1, x_2, c_1 \rangle$  is non-independent.  $x_1, x_2, c_1$  are collectively adjacent to either  $c, a_1, b_1$  or some  $x_i \in V(G)$ .

- a. If  $x_1, x_2, c_1 \perp c$ , then  $\langle a, b, c, x_1, x_2 \rangle$  is  $K_5$ .
- b. If  $x_1, x_2, c_1 \perp a_1$ , then contract the edges  $cc_1$  and  $c_1a_1$ .
- c. If  $x_1, x_2, c_1 \perp b_1$ , then contract the edges  $b_1x_2$  and  $cc_1$ .
- d. If  $x_1, x_2, c_1 \perp$  some  $x_i \in V(G)$ , then contract the edges  $x_i c_1$  and  $c_1 c$ .

In all cases,  $\langle a, b, c, x_1, x_2 \rangle$  is  $K_5$  as seen in Fig. 33 implies  $G$  is nonplanar.

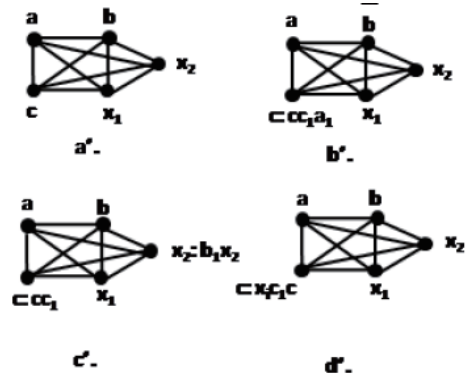


Fig.33

**Case 2:**  $x_1, x_2, b_1 \perp a_1$

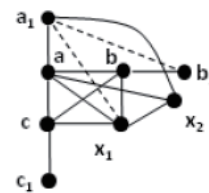
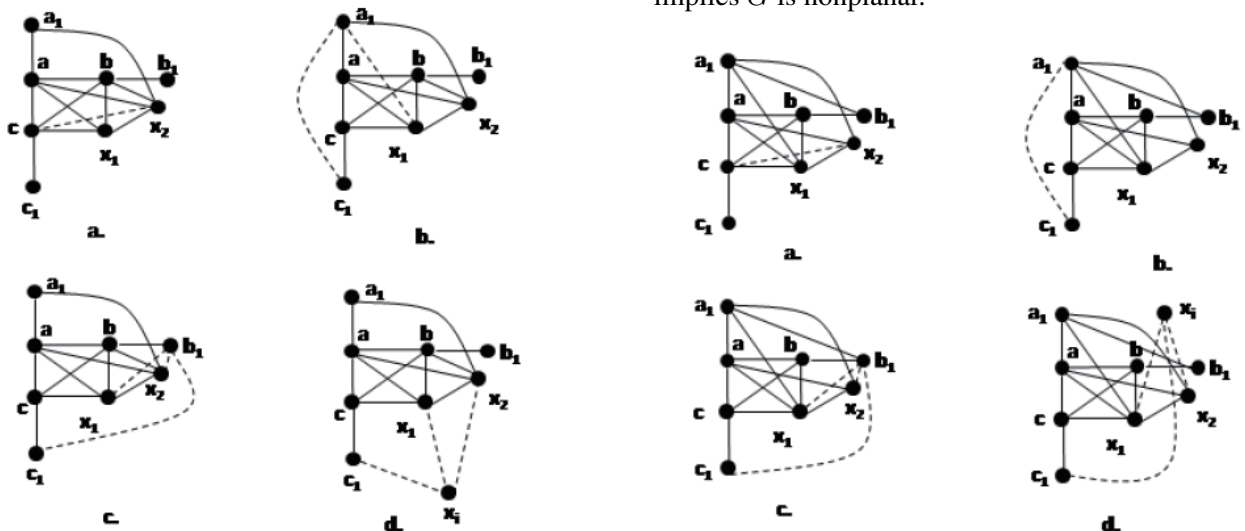


Fig.34

$\langle x_1, x_2, c_1 \rangle$  is non-independent.  $x_1, x_2, c_1$  are collectively adjacent to either  $c, a_1, b_1$  or some  $x_i \in V(G)$ .

- a. If  $x_1, x_2, c_1 \perp c$ , then contract the edges  $bb_1$  and  $b_1a_1$ .
- b. If  $x_1, x_2, c_1 \perp a_1$ , then contract the edges  $cc_1, x_2a_1$  and  $bb_1$ .
- c. If  $x_1, x_2, c_1 \perp b_1$ , then contract the edges  $b_1a_1, a_1x_2$  and  $cc_1$ .
- d. If  $x_1, x_2, c_1 \perp$  some  $x_i \in V(G)$ , then contract the edges  $a_1b_1, b_1b$  and  $x_i c_1, c_1 c$ .

In all cases  $\langle a, b, c, x_1, x_2 \rangle$  is  $K_5$  as seen in Fig. 35 implies  $G$  is nonplanar.



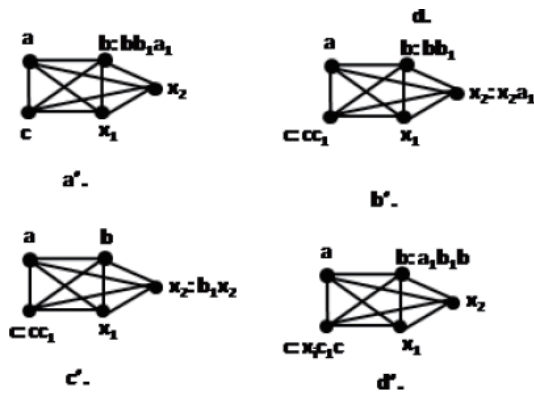


Fig.35

Case 3:  $x_1, x_2, b_1 \perp c_1$

Contracting the edges  $bb_1$  and  $a_1x_2$ ,  $a'$  is  $K_{3,3}$  as seen in Fig. 36 implies  $G$  is nonplanar.

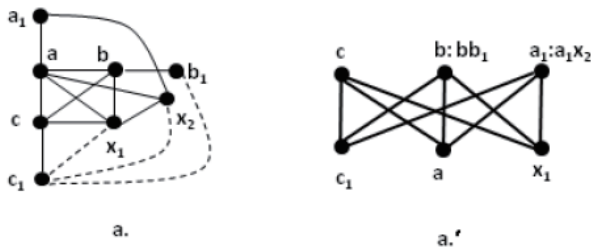


Fig.36

Case 4:  $x_1, x_2, b_1$  adjacent to some  $x_j \in V(G), x_j \neq b$ .

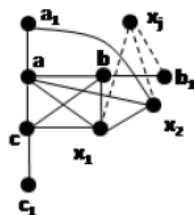


Fig.37

Subcase 1: Since  $\langle x_1, x_2, c_1 \rangle$  is non-independent,  $x_1, x_2, c_1$  adjacent to either  $c, a_1, b_1$  or  $x_j \in V(G)$ .

- a. If  $x_1, x_2, c_1 \perp c$ , then contract the edges  $x_jb_1, b_1b$ .
- b. If  $x_1, x_2, c_1 \perp a_1$ , then contract the edges  $x_jb_1, b_1b$  and  $a_1c_1, c_1c$ .
- c. If  $x_1, x_2, c_1 \perp b_1$ , then contract the edges  $b_1x_2$  and  $c_1c$ .
- d. If  $x_1, x_2, c_1 \perp x_j$ , then contract the edges  $bb_1, x_2x_j$  and  $c_1c$ .

In all cases,  $\langle a, b, c, x_1, x_2 \rangle$  is  $K_5$  as seen in Fig. 38 implies  $G$  is nonplanar.

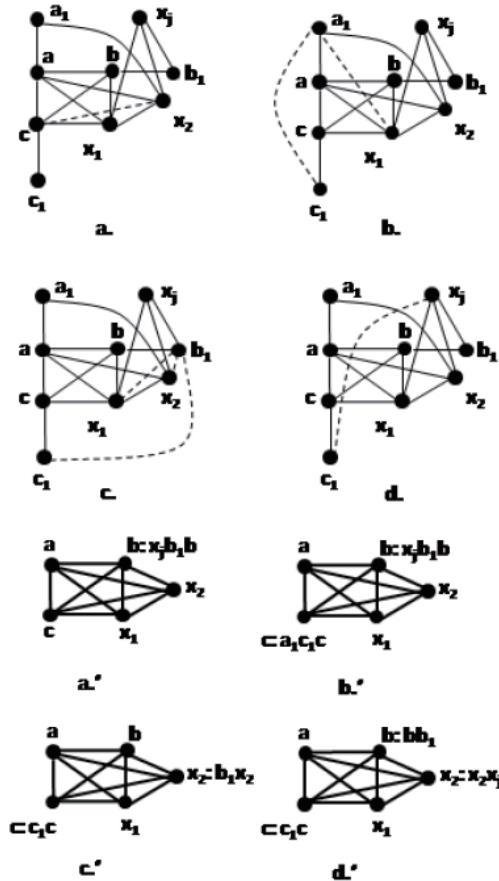


Fig.38

Subcase 2:  $x_1, x_2, c_1 \perp$  some  $x_k \in V(G), x_k \neq c$ .

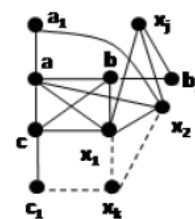


Fig.39

- a. If  $x_j = x_k$ , then  $x_j$  is adjacent to  $b_1, x_2, x_1, c_1$ . Contract the edges  $x_2x_j, bb_1, cc_1$ .
- b. If  $x_k$  and  $x_j$  are distinct, then contract the edges  $bb_1, b_1x_j$  and  $x_kc_1, c_1c$ .

In both the cases  $\langle a, b, c, x_1, x_2 \rangle$  is  $K_5$  as seen in Fig. 40 implies  $G$  is nonplanar.

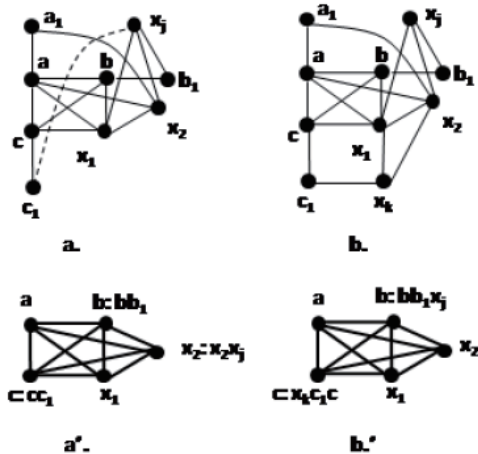


Fig.40

From case 1, 2, 3 and 4 we see that if  $G$  and  $\bar{G}$  are  $\gamma$  - stable graphs satisfying the conditions of the theorem, then  $G$  is nonplanar.

**Claim 3:** If  $\gamma(G) = 4, \gamma(\bar{G}) = 3$ , then  $G$  is nonplanar.

**Proof:** Let  $D = \gamma(G) = \{a, b, c, d\}$ . Since  $G$  is  $\gamma$  - stable, we know that  $pn[u, D] \geq 2$ , for all  $u \in D$ , [ by  $R_3$ ]. Let  $\{a_1, a_2\} \in pn[a, D]$ ,  $\{b_1, b_2\} \in pn[b, D]$ ,  $\{c_1, c_2\} \in pn[c, D]$ ,  $\{d_1, d_2\} \in pn[d, D]$ .  $\langle a_1, a, b \rangle$  is non - independent. Let  $x_1 \perp a_1, a, b$  [ Since  $a_1 \in pn[a, D], b_1 \in pn[b, D], c_1 \in pn[c, D], d_1 \in pn[d, D], x_1 \neq b_1, c_1, d_1, c, d$ .

$\langle c, c_1, x_1 \rangle$  is non - independent. Let  $x_2 \perp c, c_1, x_1$  [Since  $a_1 \in pn[a, D], b_1 \in pn[b, D], c_1 \in pn[c, D], d_1 \in pn[d, D], x_2 \neq a_1, b_1, d_1, a, b, d$ .

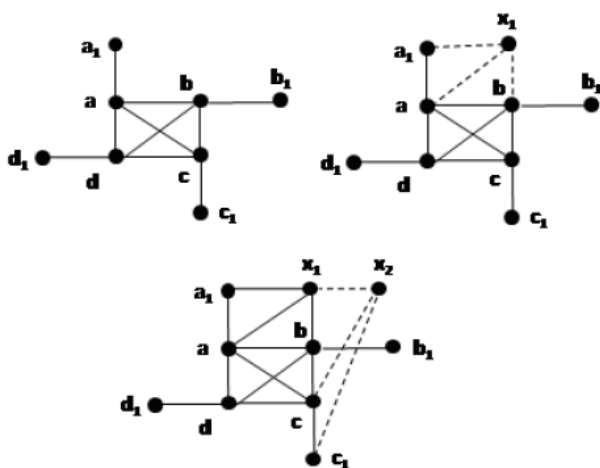


Fig.41

$\langle d, d_1, x_1 \rangle$  is non - independent. The common adjacent vertex is either  $x_2$  or any vertex  $x_3 \in V(G)$  [ Note that  $d, d_1, x_1$  cannot be collectively adjacent to  $a, b, c, a_1, b_1, c_1$ ].

- a. If  $d, d_1, x_1 \perp x_2$ , then contract the edge  $x_2x_1$ .
- b. If  $d, d_1, x_1 \perp x_3$ , then contract the edges  $x_3x_1$  and  $x_1x_2$ .

In both the cases,  $\langle a, b, c, d, x_1 \rangle$  is  $K_5$  as seen in the Fig. 42 implies  $G$  is nonplanar.

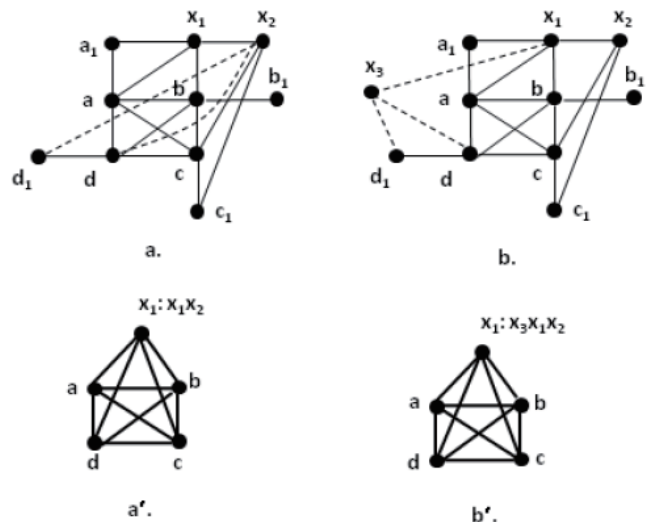


Fig.42

From the above discussion, we conclude that  $G$  is nonplanar.

**Remark 5** If  $G$  and  $\bar{G}$  are  $\gamma$ -stable graphs such that  $\gamma(G) \leq 4$  and  $\gamma(\bar{G}) = 2$ , then  $G$  need not be nonplanar.

**Example 6**

**Case 1:**  $\gamma(G) = 2$  and  $\gamma(\bar{G}) = 2$ .

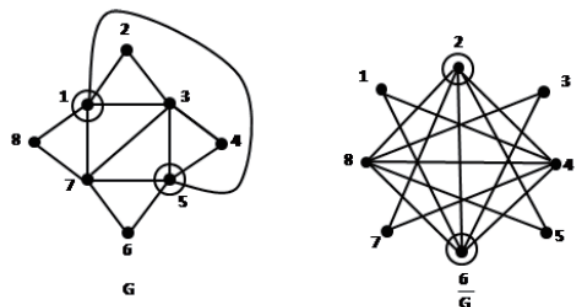


Fig.43

**Case 2:**  $\gamma(G) = 3$  and  $\gamma(\bar{G}) = 2$ .

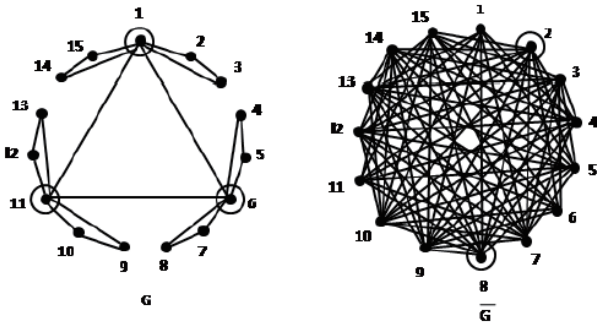


Fig.44

Case 3  $\gamma(G) = 4$  and  $\gamma(\bar{G}) = 2$ .

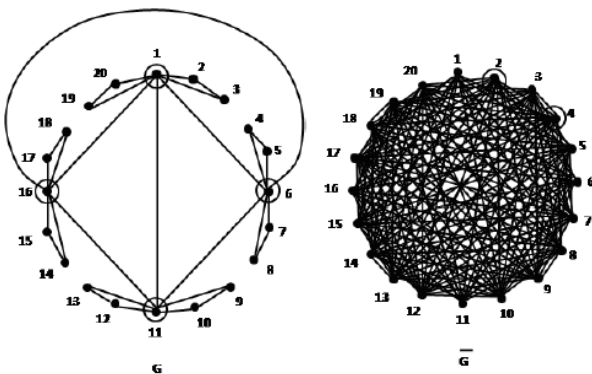


Fig.45

In Fig. 43, 44 and 45  $G$  and  $\bar{G}$  are  $\gamma$  - stable graphs,  $G$  planar.

### 5 Conclusion

From the above discussion we conclude that, if  $G, \bar{G}$  are  $\gamma$  - stable graphs, then

1.  $G$  is nonplanar, if  $2 < \gamma(\bar{G}) \leq 4$ .
2.  $G$  need not be nonplanar, if  $\gamma(\bar{G}) = 2$ .

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