

# Parallel Flow of a Pressure-Dependent Viscosity Fluid through Composite Porous Layers

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*Abstract:* - Flow of a fluid with pressure-dependent viscosity through a composite of two porous layers is considered in this work in an attempt to validate velocity and shear stress continuity conditions at the interface, and are popular in the study of flow over porous layers and through composite layers when viscosity of the fluid is constant. For the current problem, conditions at the interface between the porous layers reflect continuity assumptions of velocity and shear stress, with additional continuity assumptions on pressure and viscosity. Viscosity is assumed to vary continuously and exponentially across the layers as a function of pressure. Analytical solutions are obtained to illustrate the effects of flow and media parameters (Darcy numbers, layer thicknesses, angle of inclination, and viscosity adjustment parameter) on the dynamic behaviour of pressure-dependent viscosity fluids in porous structures. All computations, simulations and graphs in this work have been carried out and obtained using *Maple 2020* software package.

*Key-Words:* - Composite porous layers; Pressure-Dependent Viscosity; Inclined Plane.

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## 1 Introduction

In this work, we initiate the study of flow of fluids with pressure-dependent viscosities through composite porous layers. Flow of fluids with constant viscosities through layered porous media have been extensively studied (*cf.* [1, 2, 3] and the references therein). Flow of fluids with pressure-dependent viscosities through free-space has also received considerable attention in the literature, (*cf.* [4, 5, 6, 7, 8] and the references therein). However, only recently models of flow of fluids with pressure-dependent viscosities through porous media have been derived [9, 10, 11, 12].

Fluid viscosity variations include changes in viscosity due to temperature, pressure and shear-thinning. Many fluids, such as paint and polymers exhibit behaviours in which a fluid becomes either thicker, or thinner when sheared, [13, 14, 15, 16, 17]. Nakshatrala & Rajagopal [17] provided an account of these variations. Studies of fluid viscosity variations

and viscosity dependence on pressure can be traced to back to the nineteenth century and the work of various authors, including Stokes [18], Barus [19, 20]. More recently, experimental studies confirm dependence of viscosity on pressure, [7, 8, 21].

Barus [19, 20] suggested two relationships for dependence of viscosity on pressure, an exponential and a linear relationship. The Barus relationships received considerable analysis in the literatr, (*cf.* [22] and the references therein). A model describing the dependence of viscosity on pressure, temperature and density has been reported in Szeri [5]. Other models of dependence have been discussed in the literature, [23, 24].

Interest in fluids with pressure-dependent viscosities in porous media stems from their industrial applications in the oil industry (enhanced oil recovery and geological carbon sequestration), food and polymer processing, in the pharmaceutical industry, in thin film lubrication and in filtration

problems [6, 15, 17, 22, 25, 26]. Fusi *et.al.* [25] provided elegant modelling of three important filtration problems involving pressure-dependent viscosity fluids in porous media, and Housiadas *et.al.* [26] initiated studies of compressible fluids with pressure-dependent viscosity, in their development of new analytic solutions of weakly compressible Newtonian Poiseuille flows. These and many other applications initiated the recent interest in the modelling and simulation of flow through porous media with a focus on fluids with variable or stratified viscosities, and fluids with pressure-dependent viscosities, [12, 11, 12, 17].

Models describing the flow of fluids with pressure-dependent viscosity through porous media have been derived, discussed or otherwise analyzed by various authors, including Srinivasan and Rajagopal [10], Nakshatrala and Rajagopal [17], Kannan and Rajagopal [13], Abu Zaytoon *et.al.* [11], Alharbi, *et.al.* [12], Of interest to the current work is the Brinkman-type model, [10, 13, 17], in which the flow through a rigid porous structure is described by the following equations of continuity and momentum, respectively, written here for steady flow:

$$\nabla \cdot \vec{u} = 0 \quad (1)$$

$$\rho \vec{u} \cdot \nabla \vec{u} = -\nabla p + \nabla \cdot \vec{T} - \lambda(p)\vec{u} + \rho \vec{G} \quad (2a)$$

$$\vec{T} = -p\vec{I} + 2\mu(p)\vec{A} \quad (2b)$$

is the Cauchy stress tensor in which

$$\vec{A} = \frac{1}{2}(\nabla \vec{u} + (\nabla \vec{u})^T) \quad (2c)$$

where  $\vec{u}$  is the velocity vector field,  $p$  is the pressure,  $\rho$  is the fluid density,  $\rho \vec{G} = (\rho G_1, \rho G_2, \rho G_3)$  is the body force,  $\mu = \mu(p)$  is the variable viscosity, and  $\lambda(p)$  is a drag function that has been given various forms as discussed by Kannan and Rajagopal [13], and include exponential and polynomial forms in terms of pressure. Governing equations for flow in the channel are the equation of continuity and the Navier-Stokes equations with pressure-dependent viscosity. These equations are similar in form to equations (1) and (2) with  $\lambda(p) = 0$  in (2a).

When the drag function is expressed as the ratio between viscosity of the fluid and permeability of the porous medium, namely,  $\lambda(p) = \mu/k$ , equation (2) reduces to a model derived using intrinsic volume averaging, [11, 12]. This form of drag function facilitates studies of flow through constant and

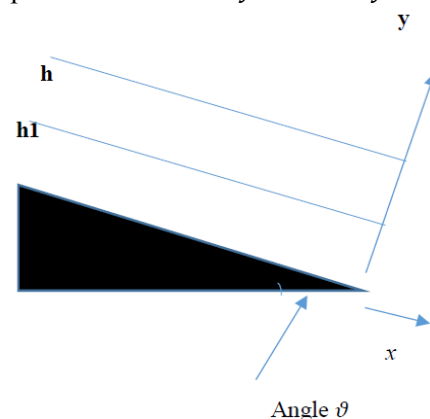
variable permeability porous media [27, 28]. We implement this form in the current study where we consider the parallel flow of a fluid with pressure-dependent viscosity through two porous layers inclined to the horizontal at an angle.

The flow domain of a porous channel inclined to the horizontal has been a model configuration for many problems, including thin film lubrication and wave, [29], and, we believe, it facilitates the introduction of a continuous pressure function on which viscosity depends. Conditions at the interface between the porous layer that emphasize continuity of pressure, viscosity, shear stress and velocity.

## 2 Problem Formulation

The steady flow of an incompressible fluid with pressure-dependent viscosity through a porous medium is governed by continuity and momentum equations (1) and (2), above, in which we take  $\lambda(p) = \mu/k$ .

Now, consider the flow through the configuration shown in **Fig.1**, where a fluid flows through two composite porous layers each with different permeability. We set layer 1 to  $0 \leq y \leq h_1$  and layer 2 to  $h_1 \leq y \leq h$ . Layers 1 and 2 are assumed to be parallel and meet at a sharp interface  $y = h_1$  with angle of inclination  $\vartheta$ . The layers are bounded by solid, impermeable walls at  $y = 0$  and  $y = h$ .



**Fig. 1. Representative sketch**

For the unidirectional flow at hand, the flow is in the  $x$ -direction, taken along the inclined wall, with  $\vec{u} = (u, 0)$ . Continuity equation (1) implies that  $u_x = 0$  or  $u = u(y)$ . Equation (2) reduces to  $-p_y + \rho G_2 = 0$ , where  $\rho G_2$  is the body force component in the  $y$ -direction, namely,  $-\rho g \cos \vartheta$ . Flow in the  $x$ -direction is under the effect of body force (gravity) whose component in the  $x$ -direction is  $\rho g \sin \vartheta$ .

Pressure gradient in the  $x$ -direction is zero,  $p_x = 0$ , which emphasizes that  $p = p(y)$ .

We now define the following dimensionless quantities and Darcy numbers with respect to total thickness of the flow domain and with respect to a characteristic velocity,  $U$ :

$$y^* = \frac{y}{h}; \quad u_i^* = \frac{u_i}{U} \quad \varepsilon = \frac{h_1}{h}; \quad Da_i = \frac{k_i}{h^2} \quad \text{for } i = 1,2; \quad (3)$$

Dropping the asterisk (\*), the governing equations for the  $i$ th layer, where  $i = 1,2$  refer to the lower and upper layer, respectively, take the following forms:

$$\mu_i \frac{d^2 u_i}{dy^2} + \frac{d\mu_i}{dy} \frac{du_i}{dy} + \frac{\rho g h^2 \sin \vartheta}{U} - \frac{\mu_i}{Da_i} u_i = 0 \quad (4)$$

$$\frac{dp_i}{dy} = -\rho g h \cos \vartheta \quad (5)$$

At the solid boundaries,  $y = 0$  and  $y = 1$ , the velocity vanishes. We also assume that the value of pressure at  $y=l$  is given as  $p_0$ . Boundary conditions are thus as follows:

$$u_1(0) = 0 \quad (6)$$

$$u_2(1) = 0 \quad (7)$$

$$p_2(1) = p_0 \quad (8)$$

$$u_1(\varepsilon) = u_2(\varepsilon) \quad (9)$$

$$\mu_1 \frac{du_1}{dy}(\varepsilon) = \mu_2 \frac{du_2}{dy}(\varepsilon) \quad (10)$$

$$\mu_1(\varepsilon) = \mu_2(\varepsilon) \quad (11)$$

$$p_1(\varepsilon) = p_2(\varepsilon) \quad (12)$$

In order to find the pressure distribution, we integrate equation (5) and use conditions (8) and (12) to obtain

$$p_1(y) = p_0 + (1 - y)\rho g h \cos \vartheta; \quad 0 \leq y \leq \varepsilon \quad (13)$$

$$p_2(y) = p_0 + (1 - y)\rho g h \cos \vartheta; \quad \varepsilon \leq y \leq 1 \quad (14)$$

At the interface between the two layers, the pressure is given by

$$p_1(\varepsilon) = p_2(\varepsilon) = p_0 + (1 - \varepsilon)\rho g h \cos \vartheta \quad (15)$$

In order to solve (16), we first need to specify viscosities  $\mu_i$  as functions of pressure distributions (13) and (14). In this work we assume that viscosities vary exponentially according to Barus' relationship of the form:

$$\mu_i(p_i) = A e^{\alpha p_i} \quad (16)$$

where  $A$  and  $\alpha$  are positive constants, referred to as viscosity control parameters. Their role is to keep values of viscosities within realistic limits. We note that  $\mu_1(p_1)$  and  $\mu_2(p_2)$  are equal at the interface,  $y = \varepsilon$ , hence condition (11) is satisfied. Equations (4) thus take the following form:

$$\frac{d^2 \bar{u}_i}{d\bar{y}^2} - \beta \frac{d\bar{u}_i}{d\bar{y}} - \frac{\bar{u}_i}{Da_i} = -\gamma e^{\beta \bar{y}} \quad (17)$$

where

$$\beta = \alpha \rho g h \cos \vartheta \quad (18)$$

$$\gamma = \frac{\rho g h^2 \sin \vartheta}{UA} e^{-\beta - \alpha p_0} \quad (19)$$

### 3 Problem Solution

#### 3.1. Velocity Profiles

General solutions to equations (17) are given by:

$$u_1 = c_1 e^{m_1 y} + c_2 e^{m_2 y} + \gamma Da_1 e^{\beta y}; \quad 0 < y \leq \varepsilon \quad (20)$$

$$u_2 = d_1 e^{r_1 y} + d_2 e^{r_2 y} + \gamma Da_2 e^{\beta y}; \quad \varepsilon \leq y < 1 \quad (21)$$

where  $c_1, c_2, d_1$  and  $d_2$  are arbitrary constants and

$$m_1 = \frac{\beta + \sqrt{\beta^2 + \frac{4}{Da_1}}}{2}, \quad m_2 = \frac{\beta - \sqrt{\beta^2 + \frac{4}{Da_1}}}{2}, \quad r_1 = \frac{\beta + \sqrt{\beta^2 + \frac{4}{Da_2}}}{2}, \quad r_2 = \frac{\beta - \sqrt{\beta^2 + \frac{4}{Da_2}}}{2} \quad (22)$$

Velocity at the interface is given by either (20) or (21), evaluated at  $y = \varepsilon$ , namely

$$u_1(\varepsilon) = c_1 e^{m_1 \varepsilon} + c_2 e^{m_2 \varepsilon} + \gamma Da_1 e^{\beta \varepsilon} \quad (23)$$

$$u_2(\varepsilon) = d_1 e^{r_1 \varepsilon} + d_2 e^{r_2 \varepsilon} + \gamma Da_2 e^{\beta \varepsilon}. \quad (24)$$

Now, to find the values of arbitrary constants  $c_1, c_2, d_1$  and  $d_2$  appearing in (20) and (21), we apply equation (6), (7), (9) and (10) to obtain the following system of linear equations:

$$c_1 + c_2 + \gamma Da_1 = 0 \quad (25)$$

$$d_1 e^{r_1} + d_2 e^{r_2} + \gamma Da_2 e^{\beta} = 0 \quad (26)$$

$$c_1 e^{m_1 \varepsilon} + c_2 e^{m_2 \varepsilon} = d_1 e^{r_1 \varepsilon} + d_2 e^{r_2 \varepsilon} + \gamma e^{\beta \varepsilon} (Da_2 - Da_1) \quad (27)$$

$$c_1 m_1 e^{m_1 \varepsilon} + c_2 m_2 e^{m_2 \varepsilon} = d_1 r_1 e^{r_1 \varepsilon} + d_2 r_2 e^{r_2 \varepsilon} + \gamma \beta e^{\beta \varepsilon} (Da_2 - Da_1) \quad (28)$$

Equations (25)-(28) are written in the matrix form  $A\vec{X} = \vec{B}$ , which can be solved numerically using *Maple*, where

$$A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & e^{r_1} & e^{r_2} \\ e^{m_1 \varepsilon} & e^{m_2 \varepsilon} & -e^{r_1 \varepsilon} & -e^{r_2 \varepsilon} \\ m_1 e^{m_1 \varepsilon} & m_2 e^{m_2 \varepsilon} & -r_1 e^{r_1 \varepsilon} & -r_2 e^{r_2 \varepsilon} \end{pmatrix},$$

$$\vec{X} = \begin{pmatrix} c_1 \\ c_2 \\ d_1 \\ d_2 \end{pmatrix}, \vec{B} = \begin{pmatrix} -\gamma Da_1 \\ -\gamma Da_2 e^{\beta} \\ \gamma e^{\beta \varepsilon} (Da_1 - Da_2) \\ \gamma \beta e^{\beta \varepsilon} (Da_1 - Da_2) \end{pmatrix} \quad (29)$$

### 3.2. Vorticity and Shear Stress

Vorticities,  $\omega_1$  in the lower layer and  $\omega_2$  in the upper layer, take the following forms with the help of (20) and (21), respectively:

$$\omega_1 = -\frac{du_1}{dy} = -[c_1 m_1 e^{m_1 y} + c_2 m_2 e^{m_2 y} + \gamma \beta Da_1 e^{\beta y}] \quad (30)$$

$$\omega_2 = -\frac{du_2}{dy} = -[d_1 r_1 e^{r_1 y} + d_2 r_2 e^{r_2 y} + \gamma \beta Da_2 e^{\beta y}] \quad (31)$$

with values at the interface given by

$$\omega_1(\varepsilon) = -[c_1 m_1 e^{m_1 \varepsilon} + c_2 m_2 e^{m_2 \varepsilon} + \gamma \beta Da_1 e^{\beta \varepsilon}] \quad (32)$$

$$\omega_2(\varepsilon) = -[d_1 r_1 e^{r_1 \varepsilon} + d_2 r_2 e^{r_2 \varepsilon} + \gamma \beta Da_2 e^{\beta \varepsilon}]. \quad (33)$$

We note that  $\omega_1(\varepsilon) = \omega_2(\varepsilon)$  as a consequence of conditions (10) and (11).

The shear stresses,  $\tau_1$  in the lower layer  $\tau_2$  in the upper layer, are written as follows with the help of (20) and (21), respectively:

$$\tau_1 = \mu_1 \frac{du_1}{dy} = \mu_1 [c_1 m_1 e^{m_1 y} + c_2 m_2 e^{m_2 y} + \gamma \beta Da_1 e^{\beta y}] \quad (34)$$

$$\tau_2 = \mu_2 \frac{du_2}{dy} = \mu_2 [d_1 r_1 e^{r_1 y} + d_2 r_2 e^{r_2 y} + \gamma \beta Da_2 e^{\beta y}] \quad (35)$$

The shear stress at the interface ( $y = \varepsilon$ ) is given by:

$$\tau_1(\varepsilon) = \mu_1(\varepsilon) [c_1 m_1 e^{m_1 \varepsilon} + c_2 m_2 e^{m_2 \varepsilon} + \gamma \beta Da_1 e^{\beta \varepsilon}] \quad (36)$$

$$\tau_2(\varepsilon) = \mu_2(\varepsilon) [d_1 r_1 e^{r_1 \varepsilon} + d_2 r_2 e^{r_2 \varepsilon} + \gamma \beta Da_2 e^{\beta \varepsilon}] \quad (37)$$

We note that  $\tau_1(\varepsilon) = \tau_2(\varepsilon)$  due to (10).

## 4. Results and Discussion

Results have been obtained for the following ranges that are representative of the media and flow parameters:

Ranges of Darcy Numbers:  $Da_1 = 1, 0.1, 0.01, 0.001$  and  $0.00001$ , and  $Da_2 = 1$  and  $0.01$ . We point out that when  $Da_1 = Da_2$  then the two layers behave like one layer.

Range of inclination angle  $\vartheta$ :  $30, 60,$  and  $75$  degrees.

Range of  $p_0$ :  $2, 3,$  and  $5$ .

Range of  $\varepsilon$ :  $0.25, 0.5$  and  $0.75$ .

Range of  $\alpha$ :  $0.01, 0.1$  and  $1$ .

We can take  $\rho g = 1$  and  $h = 1$  as is Kannan and Rajagopal [13]. We also take  $A=U=I$  as representative values.

### 4.1. Velocity Profiles

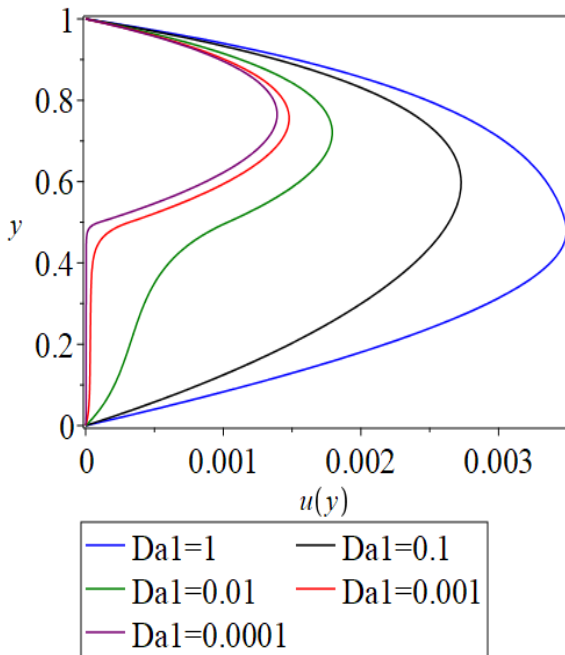
Velocities in the porous layers are given by equations (20) and (21), respectively. Effects of the various

flow and medium parameters on the velocity profiles are discussed in what follows.

#### 4.1.1. Effects of Darcy Numbers

**Fig. 2** illustrates the effects of Darcy numbers on the velocity profiles across the two layers, when they are of the same thickness. As is well known, velocity increases with increasing Darcy number. When  $Da_1 = Da_2$ , permeabilities are the same and the two layers behave like a single layer. The velocity profile shown for the case of  $Da_1 = Da_2 = 0.1$  is parabolic and symmetric about  $y=0.5$ .

In the lower layer,  $y < 0.5$ , **Fig. 2** shows the increase in velocity with increasing  $Da_1$ . By keeping  $Da_2$  fixed at 0.1, **Fig. 2** shows a greater influence on the upper layer by the lower layer with increasing  $Da_1$ . This influence results in distorting the parabolic shape of the velocity profile in the upper layer.



**Fig. 2** Velocity across the two layers for various values of  $Da_1$ .  
 $\epsilon = 0.5, \alpha = 1, UA = 1, p_0 = 2, \vartheta = 30, Da_2 = 0.1$ .

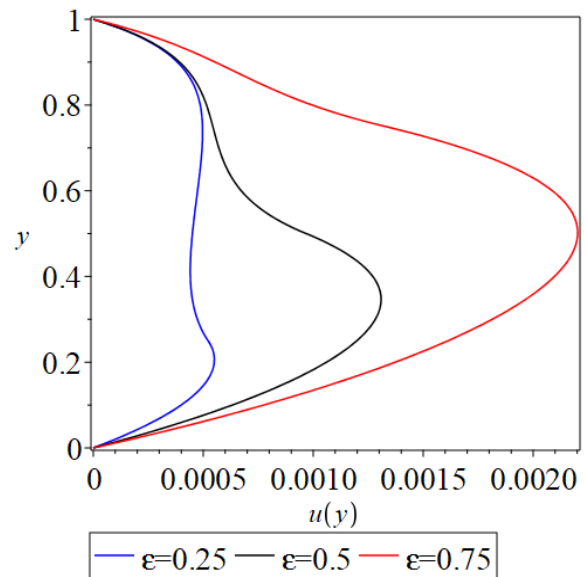
#### 4.1.2. Effects of $\epsilon$

The value of  $\epsilon$  represents the fraction of the total thickness of the flow domain that the lower layer occupies. When  $\epsilon = 0.5$ , both layers are of the same thickness.

In **Fig. 3**, we illustrate the effects of  $\epsilon$  when the lower layer has a higher Darcy number than the upper layer. This translates into the lower layer having a higher influence on the upper layer by virtue of the higher velocity associated with higher  $Da$ . With increasing  $\epsilon$ , velocity at the interface increases, as per equations (23) and (24).

#### 4.1.3. Effects of $p_0$

**Fig. 4** illustrates the effects of  $p_0$  on the velocity profile. It shows that with decreasing  $p_0$  velocity increases due to the decrease in viscosity that is associated with decreasing  $p_0$ . Decreasing viscosity translates into a lesser resistance to the flow, hence a greater velocity.



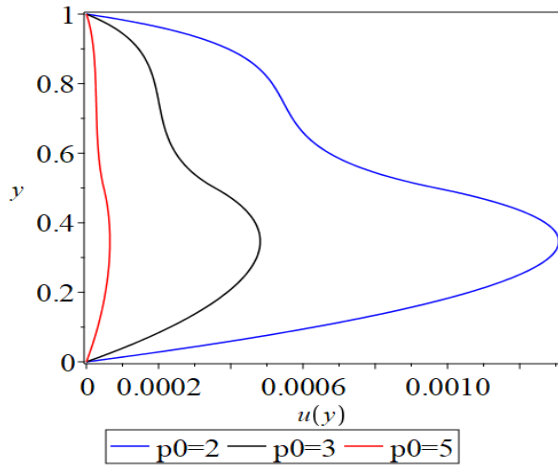
**Fig. 3** Velocity across the two layers various values of  $\epsilon$ .  
 $\alpha = 1, p_0 = 2, AU = 1, \vartheta = 30, Da_2 = 0.01, Da_1 = 0.1$ .

#### 4.1.4. Effects of $\vartheta$

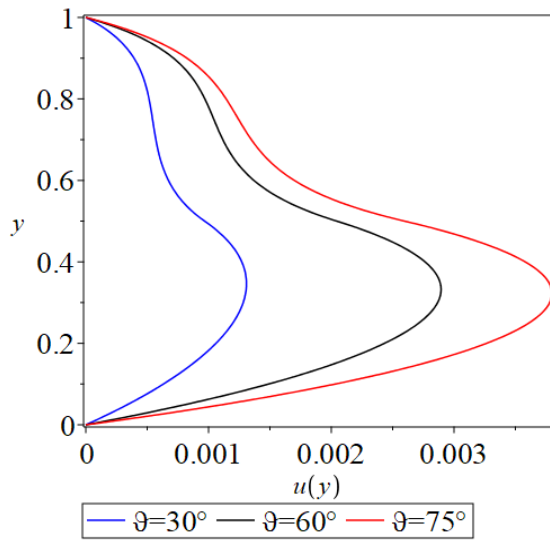
Associated with increasing angle of inclination is a decrease in the pressure distribution, hence a decrease in viscosity, hence an increase in velocity. In addition, with increasing inclination angle there is a greater gravitational force driving the flow. The net effect across the configuration is a velocity increases with increasing angle of inclination, as shown in **Fig. 5**.

#### 4.1.5. Effects of $\alpha$

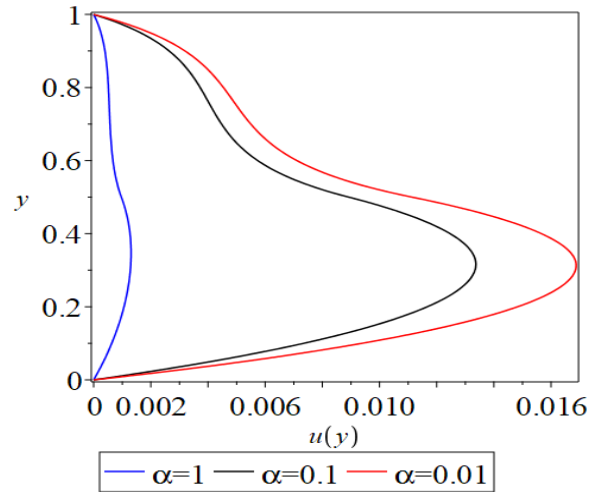
For a given pressure distribution, when  $\alpha$  increases then viscosity increases, which results in a decrease in velocity across the layers. This is illustrated in **Fig. 6** which shows the slowing down of the flow as  $\alpha$  increases.



**Fig. 4** Velocity across the two layers for various values of  $p_0$ .  
 $\varepsilon = 0.5, \alpha = 1, AU = 1, \vartheta = 30, Da_2 = 0.01,$  and  $Da_1 = 0.1$ .



**Figure 5** Velocity across the two layers for various values of  $\vartheta$ .  
 $\varepsilon = 0.5, \alpha = 1, AU = 1, p_0 = 2, Da_2 = 0.01,$  and  $Da_1 = 0.1$ .



**Fig. 6** Velocity across the two layers for various values of  $\alpha$ .  
 $\varepsilon = 0.5, p_0 = 2, AU = 1, \vartheta = 30, Da_2 = 0.01,$  and  $Da_1 = 0.1$ .

#### 4.2. Velocity, Vorticity and Shear Stress at the Interface

Velocity, vorticity and shear stress at the interface  $y = \varepsilon$  are tabulated, **Tables 1** through **5**, below for different parameters using expressions (23), (24), (32), (33), (36) and (37).

**Table 1** illustrates the effects of Darcy number on interfacial quantities and shows the expected increase of velocity at the interface with increasing  $Da_1$  for a fixed value of  $Da_2$ . This behaviour is in agreement with the effects of Darcy number  $Da_1$  on the velocity profile, shown in **Fig. 2**. Vorticity decreases, numerically, with decreasing  $Da_1$ , and shear stress at the interface increases, numerically with decreasing  $Da_1$ . This is also in line with the velocity profiles depicted in **Fig. 2** if one considers the behaviour of slopes of the velocity curves at the interface  $y = \varepsilon$ .

Also in line with the velocity profile figures, **Fig. 2** to **Fig. 6**, are the effects of the parameters  $\varepsilon, \alpha, \vartheta$  and  $p_0$  on the velocity at the interface, illustrated in **Tables 2** to **5** in which we document the values of vorticity and shear stress at the interface. We summarize their effects as follows. Increasing  $\alpha$  results in a decrease in the interfacial velocity and a decrease in the vorticity, and a numerical increase in shear stress, as shown in **Table 2**.

Increasing  $\varepsilon$ , results in an increase in the interfacial velocity, and a corresponding increase in

the vorticity, and a numerical decrease in the shear stress at the interface, as shown in **Table 3**.

Increasing  $p_0$  results in a decrease in the interfacial velocity, and a decrease in the vorticity. The shear stress at the interface remains unaffected by changes in  $p_0$ , as shown in **Table 4**.

Increasing the angle of inclination,  $\vartheta$ , results in an increase in the interfacial velocity, as per **Fig. 5**, and a corresponding increase in the vorticity, while the shear stress at the interface decreases with increasing inclination angle, as shown in **Table 5**.

**Table 1** Velocity at the interface for various  $Da_1$ .  $\varepsilon = 0.5, \alpha = 1, UA = 1, p_0 = 2, \vartheta = 30, Da_2 = 0.1$

$Da_1$	$u_1(\varepsilon) = u_2(\varepsilon)$	$\omega_1(\varepsilon) = \omega_2(\varepsilon)$	$\tau_1(\varepsilon) = \tau_2(\varepsilon)$
1	0.0034873	0.00976403	-0.08958714
0.1	0.0026393	0.00401309	-0.03682098
0.01	0.0009683	-0.0031813	0.0292059
0.001	0.000283	-0.0056960	0.0522625
0.0001	0.000086	-0.0064038	0.0587570

**Table 2** Velocity, Vorticity and Shear stress at the interface for different  $\alpha$ .  $p_0 = 2, AU = 1, \vartheta = 30, Da_2 = 0.01, \text{ and } Da_1 = 0.1, \varepsilon = 0.5$

$\alpha$	$u_1(\varepsilon) = u_2(\varepsilon)$	$\omega_1(\varepsilon) = \omega_2(\varepsilon)$	$\tau_1(\varepsilon) = \tau_2(\varepsilon)$
1	0.00096826	0.00476337	-0.05426985
0.1	0.00892301	0.05001707	-0.06379441
0.01	0.01113969	0.06319418	-0.06475056

**Table 3** Velocity, Vorticity and Shear stress at the interface for different  $\varepsilon$ .

$\alpha = 1, p_0 = 2, AU = 1, \vartheta = 30, Da_2 = 0.01, \text{ and } Da_1 = 0.1.$

$\varepsilon$	$u_1(\varepsilon) = u_2(\varepsilon)$	$\omega_1(\varepsilon) = \omega_2(\varepsilon)$	$\tau_1(\varepsilon) = \tau_2(\varepsilon)$
0.25	0.00052199	0.00131358	-0.01858354
0.5	0.00096826	0.00476337	-0.05426985
0.75	0.00132741	0.00812923	-0.07458747

**Table 4** Velocity, Vorticity and Shear stress at the interface for different  $p_0$ .

$\varepsilon = 0.5, \alpha = 1, AU = 1, \vartheta = 30, Da_2 = 0.01, \text{ and } Da_1 = 0.1.$

$p_0$	$u_1(\varepsilon) = u_2(\varepsilon)$	$\omega_1(\varepsilon) = \omega_2(\varepsilon)$	$\tau_1(\varepsilon) = \tau_2(\varepsilon)$
2	0.00096826	0.00476337	-0.05426985
3	0.00035620	0.00175235	-0.05426985
5	0.00004821	0.00023715	-0.05426985

**Table 5** Velocity, Vorticity and Shear stress at the interface for different  $\vartheta$ .  $\varepsilon = 0.5, \alpha = 1, AU = 1,$

$p_0 = 2, Da_2 = 0.01, \text{ and } Da_1 = 0.1.$

$\vartheta$	$u_1(\varepsilon) = u_2(\varepsilon)$	$\omega_1(\varepsilon) = \omega_2(\varepsilon)$	$\tau_1(\varepsilon) = \tau_2(\varepsilon)$
30	0.00096826	0.00476337	-0.05426985
60	0.00204452	0.01072180	-0.10172564
75	0.00259720	0.01416932	-0.11916257

## 5 Conclusion

In this work, we modelled, and provided a solution to, parallel flow of a fluid with pressure-dependent viscosity through a composite of two inclined porous

layers. It was assumed that permeabilities are constant and the flow in each layer is governed by Brinkman's equation for flow of fluids with variable viscosity. The layers were saturated by the same fluid. Pressure variations through the flow domain were described by a continuous linear function. Viscosity was then expressed as a continuous, exponential function of pressure. These choices of viscosity and pressure distributions helped maintain the continuity conditions at the interface between layers. Model equations were solved subject to continuity of velocity, pressure, viscosity and shear stress at the interface, and the no-slip condition on solid boundaries. Results obtained support the following conclusions:

- 1) Parameters that influence the flow are the angle of inclination,  $\vartheta$ , pressure condition  $p_0$  at the upper channel wall, thickness  $\varepsilon$  of the lower porous layer, viscosity adjustment parameter,  $\alpha$ , and the Darcy number of each layer.
- 2) For a given pressure distribution, viscosity distribution is the most sensitive parameter as it controls the behaviour and values of viscosity. High and low values of  $\alpha$  could result in unrealistic viscosity values. [8]
- 3) Effects of the parameters on velocity at the interface are as follows:
  - i) Increasing  $\vartheta$ , all other parameters fixed, increases the velocity and vorticity, but decreases shear stress at the interface.
  - ii) Increasing  $p_0$  results in a decrease in the interfacial velocity, and a decrease in the vorticity. The shear stress at the interface remains unaffected by changes in  $p_0$ .
  - iii) Increasing  $\varepsilon$ , results in an increase in the interfacial velocity, and a corresponding increase in the vorticity, and a numerical decrease in the shear stress at the interface.
  - iv) Increasing  $\alpha$  results in a decrease in the interfacial velocity and a decrease in the vorticity, and a numerical increase in shear stress.
  - v) Velocity at the interface increases with increasing  $Da_1$  for a fixed value of  $Da_2$ . Vorticity decreases, numerically, with decreasing  $Da_1$ , and shear stress at the interface increases, numerically with decreasing  $Da_1$ .

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#### Contribution of individual authors

Both authors participated in pertinent literature review.

Both authors independently obtained the solutions to governing equations.

M.S. outlined the steps to take in conducting this research.

M.S. provided calculations and graphing of results using *Maple*, and provided initial analysis of results.

M.H. identified what quantities to calculate and values of parameters to be used.

M.H. analysed the results wrote the manuscript.

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