# A Fifth-Order-Accurate Finite Difference Scheme for a Natural Coordinate System with Non-Uniform Grid 

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#### Abstract

A fifth-order accurate finite difference scheme for the first derivative in von Mises coordinates is developed in this work. The scheme is tested in the computation of boundary vorticity in the study of twodimensional flow of a viscous fluid in a curvilinear channel. Results obtained show an improvement in the computed solution over fourth-order accurate scheme.


Key-Words: - von Mises natural coordinates, Non-uniform grid, Fifth-order scheme.
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## 1 Introduction

A large amount of research has been devoted to the development and testing of higher order finite difference schemes when a non-uniform grid is employed (c.f. $[1,2,3,4]$ and the references therein). In two-dimensional viscous fluid flow, the NavierStokes equations in vorticity-streamfunction form are approximated using second-order central differencing schemes. On a solid boundary, the streamfunction equation possesses Dirichlet conditions while the vorticity equation possesses Neumann conditions, hence vorticity must be computed on the boundary. A further aspect to handle is when the flow is through a curvilinear domain and the numerical procedure of choice is the finite difference approach. In this case it becomes necessary to transform the physical domain onto a computational domain prior to applying finite
differences. While there are many methods of transforming a curvilinear domain onto a rectangular one, a transformation of interest to the current work is the von Mises transformation, as it presents itself as a natural coordinate transformation with physical significance and connection to the streamlines of the flow, [5-6].

In using the von Mises transformation, the curvilinear physical domain in the XY-plane is transformed onto a rectangular computational domain in the $X \psi$-plane, where $\psi$ is the streamfunction and $\psi=$ constant represent the streamlines of the flow, provided that the boundary is a streamline or part of a streamline of the flow. The governing equations in vorticity-streamfunction form in the physical domain are transformed into a vorticity equation and an equation for $y(x, \psi)$ in the computational domain. Similarly, all physical
boundary conditions are transformed into computational boundary conditions, and the vorticity derivative boundary conditions in the physical domain are transformed into vorticity derivative boundary conditions in von Mises coordinates. Vorticity at the computational domain boundaries remains a quantity to be determined (approximated) using finite differences.

It has been argued that a higher-order scheme for the vorticity on a solid wall may better approximate the vorticity there. Some authors, [7-9], suggested that the accuracy of the solution to the governing equations depends not only on the order of the scheme; rather, other factors such as the stretching parameters, the tolerance used in the solution procedure, and the actual iterative procedure should be taken into consideration. Higher-order schemes have been shown to produce better approximations to boundary vorticity. In fact, in the work of Alharbi and Hamdan, [10], a fourth-order accurate scheme for non-uniform grid was developed for the problem considered in this work and produced better boundary vorticity approximations than lower-order schemes.

This motivates the current work in which we develop a standard, six-point, fifth-order-accurate forward finite difference scheme for the boundary vorticity using non-uniform grids. The scheme is suitable for use when coordinate transformation is employed, and is tested in the computation of corner vorticity in the case of viscous fluid flow through a two-dimensional curvilinear channel that has been mapped onto a rectangular computational domain using von Mises coordinates. Results show the improvement in boundary vorticity approximation.

## 2 Problem Formulation

Consider the viscous fluid flow in the curvilinear (long) channel depicted in Fig. 1, below, described by $\left\{(x, y) \mid a \leq x \leq b ; g_{1}(x) \leq y \leq g_{2}(x)\right\}$, where $g_{1}(x)$ and $g_{2}(x)$ are known smooth functions. The inlet to the channel is $-1 \leq y \leq 1$. Flow through the channel is governed by the Navier-Stokes equations, in vorticity-streamfunction form, with boundary conditions on vorticity $\omega$ and streamfunction $\psi$ as shown in Fig. 1, ( $c f$. [1] for more details).

At the inlet, the tangential velocity profile is parabolic, $u=1-y^{2}$, and the normal velocity $v=$ 0 . The square of the speed of the flow is $q^{2}=u^{2}+$ $v^{2}=\left[1-y^{2}\right]^{2}$. Vorticity at the inlet to the channel is given by $\omega=2 y$. At the point $(x, y)=(a,-1)$, vorticity takes the value $\omega=-2$. The streamfunction at the inlet to the channel is given by $\psi=y-\frac{y^{3}}{3}$ for $y_{\min }=-1 \leq y \leq 1=y_{\max }$. The streamlines thus
range between the minimum and maximum values $\psi=\psi_{\text {min }}=-\frac{2}{3}$ and $\psi=\psi_{\max }=\frac{2}{3}$.

In the absence of an exact solution to the given problem, it is typical to use a numerical technique, such as finite differences. The presence of curvilinear boundaries, however, necessitates mapping the flow domain onto a rectangular computational domain. To accomplish this, we rely on the well-known von Mises transformation, $(x, y) \rightarrow(x, \psi)$, defined by $y=y(x, \psi)$. In the curvilinear net $(x, \psi)$, the curves $\psi=$ constant represent the streamlines of the flow. Jacobian of the von Mises transformation is given by $J=\left|\frac{\partial(x, y)}{\partial(x, \psi)}\right|=y_{\psi}$. If $0<J<\infty$, then the inverse transformation exists and we can relate first partial derivative operators in the two coordinate systems as follows, wherein subscript notation denotes partial differentiation, [6]:
$\partial_{x}=\partial_{x}-\frac{y_{x}}{y_{\psi}} \partial_{\psi}$
$\partial_{y}=\frac{1}{y_{\psi}} \partial_{\psi}$

Velocity components and vorticity take the following forms, respectively, in von Mises coordinates:
$u=\frac{1}{y_{\psi}}$
$v=\frac{y_{x}}{y_{\psi}}=u y_{x}$
$\omega=v_{x}+\left(\frac{v^{2}}{u}-u\right) u_{\psi}-\frac{v}{u} u_{x}-2 v v_{\psi}$
The square of the speed of the flow is given by
$q^{2}=u^{2}+v^{2}=\frac{1+\left(y_{x}\right)^{2}}{\left(y_{\psi}\right)^{2}}$
Vorticity, (6), can thus be written in terms of the square of the speed, $q^{2}=u^{2}+v^{2}$, as
$\omega=v_{x}-\frac{1}{2}\left(q^{2}\right)_{\psi}$

In the problem at hand, $v_{x}=0$ on all boundaries, and equation (7) reduces to:
$\omega=-\frac{1}{2}\left(q^{2}\right)_{\psi}$

The physical domain, Fig. 1, is this transformed onto
the computational domain shown in Fig. 2.

$$
y=g_{2}(x) ; \quad \psi=\frac{2}{3} ; \quad \omega=v_{x}-u_{y} ; \quad u=v=q^{2}=0
$$



$$
\begin{aligned}
& q^{2}=\left(1-y^{2}\right)^{2} \\
& u=1-y^{2} \\
& v=0 \\
& \omega=2 y \\
& \psi=y-\frac{y^{3}}{3}
\end{aligned}
$$

$$
x=a ; y=-1 ; \quad y=g_{1}(x) ; \quad \psi=-\frac{2}{3} ; \quad \omega=v_{x}-u_{y} ; \quad u=v=q^{2}=0 ; \quad x=b
$$

Fig. 1 Physical Flow Configuration

$$
x=c ; y=1 ; \quad y=g_{2}(x) ; \quad \psi=\frac{2}{3} ; \quad \omega=-\frac{1}{2}\left(q^{2}\right)_{\psi} ; \quad x=d
$$

$$
x=a ; y=-1 ; \quad y=g_{1}(x) ; \quad \psi=-\frac{2}{3} ; \quad \omega=-\frac{1}{2}\left(q^{2}\right)_{\psi} ; \quad x=b
$$

Fig. 2 Computational Domain

## 3 Current Objectives

The objective of the current work is to derive a fifth-order-accurate forward difference scheme for $\left(q^{2}\right)_{\psi}$ of equation (8) that uses six grid points, one boundary point and five internal infield points, using Taylor series expansion. The scheme will be used to compute the vorticity at a boundary point where the exact solution is known, namely $\omega(x, \psi)=-2$ at $x=0$ and $\psi=-\frac{2}{3}$. The developed scheme is an upwind, forward differencing scheme that can be used to approximate lower boundary vorticity. A backward differencing scheme can be then deduced and used in approximating vorticity on the upper boundary.

Fitth-order scheme is derived below for nonuniform grid in the computational domain. However, we point out the following caveat. If a uniform grid is used in the physical domain, then the von Mises coordinate system naturally produces a grid that is clustered near the boundary. This effect is desired for more accurate results. However, if a uniform grid is chosen in the computational domain, then the physical domain grid is clustered near the centre of the channel and far away from the boundary. This effects is not desired as it produces less accurate results by not capturing the effects of boundary vorticity on the flow, as would a clustered grid.

## 4 Domain Discretization

In order to accomplish the above objective, the rectangular computational domain of Fig. 2 is discretized using a non-uniform, clustered grid by taking vertical grid lines to range from $i=1$ at channel inlet to $i=\operatorname{Imax}$ at channel exit. Horizontal grid lines are taken to range from $j=1$ at the lower computational boundary, $\left(\psi=-\frac{2}{3}\right)$, to $j=$ Jmax at the upper computational boundary, ( $\psi=\frac{2}{3}$ ), as shown in Fig. 3.

For non-uniform grid, we select a uniform grid in the physical domain with 200 points in the y -direction, resulting in step size $\Delta y=$ $\frac{y_{\text {max }}-y_{\text {min }}}{200}=\frac{[1-(-1)]}{200}=0.01$. Grid spacings $\Delta \psi_{j}$ are then calculated in the computational domain using $y-\frac{y^{3}}{3}=\psi$ for $-\frac{2}{3} \leq \psi \leq \frac{2}{3}$. These are shown in Table 1.


Fig. 3. Grid Lines. $(i, j)=(1,1)$ Corresponds to

$$
(x, y)=(a,-1)
$$

## 5 Derivation of the Scheme

In order to derive forward differencing schemes of local accuracy $n$ for the first derivative along the grid line ( $i, 1$ )using $k_{\max }=6$ grid points, where the scheme will employ one boundary point and five internal grid points, namely grid points $j=1,2,3,4,5$ and 6 , we assume the schemes to be of the form, $[8]$ :
$\left(q_{\psi}^{2}\right)_{i, 1}+\sum_{j=1}^{6} A_{j}\left(q^{2}\right)_{i, j}=E$
where $E$ is the local truncation error.
The weights, $A_{j}$, are calculated using Taylor's series expansion of $\left(q^{2}\right)_{i, m}$ about point $(i, 1)$ for $m=$ $2,3, \ldots k_{\max }=6$, namely
$\left(q^{2}\right)_{i, m}=\left.\sum_{j=1}^{5} \frac{\left(a_{m}\right)^{j-1}}{(j-1)!} \frac{\partial^{j-1} q^{2}}{\partial \psi^{j-1}}\right|_{(i, 1)}+E_{6}$
$E_{6}=\left.\sum_{j=6}^{\infty} \frac{\left(a_{m}\right)^{j-1}}{(j-1)!} \frac{\partial^{j-1} q^{2}}{\partial \psi^{j-1}}\right|_{(i, 1)}$

The coefficients $a_{m}, m=2,3, \ldots, k_{\max }=6$ are defined by

$$
\begin{align*}
& a_{m}=\sum_{j=1}^{m-1} \Delta \psi_{j}  \tag{12}\\
& \Delta \psi_{j}=\psi_{j+1}-\psi_{j} \tag{13}
\end{align*}
$$

| $j$ | $y_{j}^{*}$ | $y_{j}=-y_{j}^{*}$ | $\Delta y_{j}=y_{j+1}-y_{j}$ | $\psi_{j}$ | $\Delta \psi_{j}=\psi_{j+1}-\psi_{j}$ |
| :--- | :--- | :--- | :--- | :---: | :---: |
| 1 | 1 | $y_{1}=-1$ | 0.01 | $\psi_{1}=-0.666666666$ | $\Delta \psi_{1}=0.000099666$ |
| 2 | 0.99 | $y_{2}=-0.99$ | 0.01 | $\psi_{2}=-0.666567000$ | $\Delta \psi_{2}=0.000297667$ |
| 3 | 0.98 | $y_{3}=-0.98$ | 0.01 | $\psi_{3}=-0.666269333$ | $\Delta \psi_{3}=0.000493667$ |
| 4 | 0.97 | $y_{4}=-0.97$ | 0.01 | $\psi_{4}=-0.665775666$ | $\Delta \psi_{4}=0.000687666$ |
| 5 | 0.96 | $y_{5}=-0.96$ | 0.01 | $\psi_{5}=-0.665088000$ | $\Delta \psi_{5}=0.000879667$ |
| 6 | 0.95 | $y_{6}=-0.95$ |  | $\psi_{6}=-0.664208333$ |  |

Table 1: Grid in the Physical Domain

$$
y_{j}=-y_{j}^{*} \text { for } y_{j}^{*}=1,0.99,0.98,0.97,0.96,0.95
$$

Values of $\Delta \psi_{j}$ were provided in Table 1, and the square of the speed at channel inlet is tabulated in Table 2. The corresponding values of $a_{m}$ are calculated using (12) and (13), and are given in Table 3.

| $j$ | $y_{j}$ | $q_{j}^{2}=\left(1-y_{j}^{2}\right)^{2}$ |
| :--- | :---: | :---: |
| 1 | $y_{1}=-1$ | 0 |
| 2 | $y_{2}=-0.99$ | 0.00039601 |
| 3 | $y_{3}=-0.98$ | 0.00156816 |
| 4 | $y_{4}=-0.97$ | 0.00349281 |
| 5 | $y_{5}=-0.96$ | 0.00614656 |
| 6 | $y_{6}=-0.95$ | 0.00950625 |

Table 2: Square of the Speed at Inlet

| $\boldsymbol{a}_{\boldsymbol{m}}$ | Value |
| :--- | :--- |
| $a_{2}=\Delta \psi_{1}$ | 0.000099666 |
| $a_{3}=\Delta \psi_{1}+\Delta \psi_{2}$ | 0.000397333 |
| $a_{4}=\Delta \psi_{1}+\Delta \psi_{2}+\Delta \psi_{3}$ | 0.000891 |
| $a_{5}=\Delta \psi_{1}+\Delta \psi_{2}+$ <br> $\Delta \psi_{3}+\Delta \psi_{4}$ | 0.001578666 |
| $a_{6}=\Delta \psi_{1}+\Delta \psi_{2}+$ <br> $\Delta \psi_{3}+\Delta \psi_{4}+\Delta \psi_{5}$ | 0.002458333 |

Table 3. Values of $a_{m}$ for Non-Uniform Grid
Using (10) in (9) and equating to zero the coefficients of the first $n$ partial derivatives (including the zero'th derivative) of $q^{2}$ with respect to $\psi$ leads to the following six conditions on $A_{j}, j=1,2, \ldots, k_{\max }=$ 6:

$$
\begin{equation*}
\sum_{j=1}^{k_{\max }=6} A_{j}=0 \tag{14}
\end{equation*}
$$

$\sum_{j=2}^{k_{\max }=6} a_{j} A_{j}=-1$
$\sum_{j=2}^{k_{\max }=6} \frac{\left(a_{j}\right)^{m}}{m!} A_{j}=0 ; \quad m=2,3,4, \ldots$
Equations (14)-(16) translate into the following six equations in the six coefficients $A_{1}, A_{2}, A_{3}, A_{4}, A_{5}, A_{6}$ :
$A_{1}+A_{2}+A_{3}+A_{4}+A_{5}+A_{6}=0$
$a_{2} A_{2}+a_{3} A_{3}+a_{4} A_{4}+a_{5} A_{5}+a_{6} A_{6}=-1$
$\frac{a_{2}^{2}}{2} A_{2}+\frac{a_{3}^{2}}{2} A_{3}+\frac{a_{4}^{2}}{2} A_{4}+\frac{a_{5}^{2}}{2} A_{5}+\frac{a_{6}^{2}}{2} A_{6}=0$
$\frac{a_{2}^{3}}{6} A_{2}+\frac{a_{3}^{3}}{6} A_{3}+\frac{a_{4}^{3}}{6} A_{4}+\frac{a_{5}^{3}}{6} A_{5}+\frac{a_{6}^{3}}{6} A_{6}=0$
$\frac{a_{2}^{4}}{24} A_{2}+\frac{a_{3}^{4}}{24} A_{3}+\frac{a_{4}^{4}}{24} A_{4}+\frac{a_{5}^{4}}{24} A_{5}+\frac{a_{6}^{4}}{24} A_{6}=0$
$\frac{a_{2}^{5}}{120} A_{2}+\frac{a_{3}^{5}}{120} A_{3}+\frac{a_{4}^{5}}{120} A_{4}+\frac{a_{5}^{5}}{120} A_{5}+\frac{a_{6}^{5}}{120} A_{6}=0$
Solution to (17)-(22) takes the following forms in terms of $a_{m}$, obtained using MATLAB Symbolic Software:
$A_{1}=\frac{1}{a_{6}}+\frac{1}{a_{5}}+\frac{1}{a_{4}}+\frac{1}{a_{3}}+\frac{1}{a_{2}}$
$A_{2}=-\frac{a_{3} a_{4} a_{5} a_{6}}{a_{2}\left(a_{2}-a_{3}\right)\left(a_{2}-a_{4}\right)\left(a_{2}-a_{5}\right)\left(a_{2}-a_{6}\right)}$
$A_{3}=\frac{a_{2} a_{4} a_{5} a_{6}}{a_{3}\left(a_{2}-a_{3}\right)\left(a_{3}-a_{4}\right)\left(a_{3}-a_{5}\right)\left(a_{3}-a_{6}\right)}$
$A_{4}=-\frac{a_{2} a_{3} a_{5} a_{6}}{a_{4}\left(a_{2}-a_{4}\right)\left(a_{3}-a_{4}\right)\left(a_{4}-a_{5}\right)\left(a_{4}-a_{6}\right)}$
$A_{5}=\frac{a_{2} a_{3} a_{4} a_{6}}{a_{5}\left(a_{2}-a_{5}\right)\left(a_{3}-a_{5}\right)\left(a_{4}-a_{5}\right)\left(a_{5}-a_{6}\right)}$
$A_{6}=-\frac{a_{2} a_{3} a_{4} a_{5}}{a_{6}\left(a_{2}-a_{6}\right)\left(a_{3}-a_{6}\right)\left(a_{4}-a_{6}\right)\left(a_{5}-a_{6}\right)}$
Using (12), we can write (23)-(28) in terms of $\Delta \psi_{j}$ as:
$A_{1}=\sum_{i=1}^{5} \frac{1}{\sum_{j=1}^{i} \Delta \psi_{j}}$
$A_{2}=-\frac{1}{\Delta \psi_{1}} \frac{\prod_{i=1}^{4} \sum_{j=1}^{i+1} \Delta \psi_{j}}{\prod_{i=1}^{4} \sum_{j=2}^{i+1} \Delta \psi_{j}}$

$$
\begin{align*}
& A_{3}=\frac{\Delta \psi_{1} \prod_{i=3}^{5} \sum_{j=1}^{i} \Delta \psi_{j}}{\left(\Delta \psi_{1}+\Delta \psi_{2}\right)\left(\Delta \psi_{2}\right) \prod_{i=3}^{5} \sum_{j=3}^{i} \Delta \psi_{j}}  \tag{31}\\
& A_{4}=-\frac{\prod_{i=0}^{4} \sum_{j=1}^{i+1} \Delta \psi_{j}}{\left(\sum_{j=1}^{3} \Delta \psi_{j}\right)\left(\prod_{i=1}^{3} \Sigma_{j=i}^{3} \Delta \psi_{j}\right)\left(\prod_{i=4}^{5} \Sigma_{j=4}^{i} \Delta \psi_{j}\right)}  \tag{32}\\
& A_{5}=\frac{\Delta \psi_{5} \prod_{i=0}^{2} \sum_{j=1}^{i+1} \Delta \psi_{j}+\prod_{i=0}^{3} \Sigma_{j=1}^{i+1} \Delta \psi_{j}}{\Delta \psi_{5} \prod_{i=1}^{4} \Sigma_{j=i}^{4} \Delta \psi_{j}}  \tag{33}\\
& A_{6}=-\frac{\prod_{i=0}^{3} \sum_{j=1}^{i+1} \Delta \psi_{j}}{\prod_{i=1}^{5} \Sigma_{j=i}^{5} \Delta \psi_{j}} \tag{34}
\end{align*}
$$

## 6 Results and Discussion

Values of the six coefficients $A_{1}, A_{2}, A_{3}, A_{4}, A_{5}, A_{6}$ are listed in Table 4, below. They correspond to nonuniform grid data of Tables 1 and 3.

| $\boldsymbol{A}_{\boldsymbol{j}}$ | Value |
| :---: | :---: |
| $A_{1}$ | $14,712.853$ |
| $A_{2}$ | $-16,776.0981$ |
| $A_{3}$ | $2,424.29769$ |
| $A_{4}$ | -409.658693 |
| $A_{5}$ | 51.986845 |
| $A_{6}$ | -3.380685 |

Table 4. Values of Coefficients

$$
A_{1}, A_{2}, A_{3}, A_{4}, A_{5}, A_{6}
$$

The fifth order accurate finite differences scheme for the first derivative $\left(q_{\psi}^{2}\right)_{i, 1}$ is provided by equation (9), written as:

$$
\begin{align*}
& \left(q_{\psi}^{2}\right)_{i, 1} \approx-\left\{A_{1}\left(q^{2}\right)_{i, 1}+A_{2}\left(q^{2}\right)_{i, 2}+A_{3}\left(q^{2}\right)_{i, 3}+\right. \\
& \left.A_{4}\left(q^{2}\right)_{i, 4}+A_{5}\left(q^{2}\right)_{i, 5}+A_{6}\left(q^{2}\right)_{i, 6}\right\} \tag{35}
\end{align*}
$$

where the coefficients $A_{1}, A_{2}, A_{3}, A_{4}, A_{5}, A_{6}$ are given by (29)-(34) for non-uniform grid.

Using the data of Tables 2 and 4, expression (36) renders the following value for $\left(q_{\psi}^{2}\right)_{1,1}$ :

$$
\left(q_{\psi}^{2}\right)_{1,1} \approx 3.98527329923628279
$$

Vorticity at the point $(x, y)=(a,-1)$ is obtained by substituting $\left(q_{\psi}^{2}\right)_{1,1}$ in equation (8), as:

$$
\omega_{1,1}=-1.992636649618141395 .
$$

Since the true value is $\omega_{1,1}=-2$, the percentage relative error (P.R.E.), defined as

$$
\begin{equation*}
\text { P.R.E. }=\left|\frac{\text { True quantity-Computed quantity }}{\text { True quantity }}\right| \% \tag{36}
\end{equation*}
$$

yields P.R.E. $\approx 0.368 \%$.
By comparison with results obtained from firstorder accurate to fourth-order accurate schemes, [7], [8], [10], Table 5 shows that the fifth-order scheme renders the lowest P.R.E.

|  | $\omega_{1,1}$ | P.R.E. |
| :---: | :---: | :---: |
| $1^{\text {st }}$ order scheme | -1.9867357 | 0.666\% |
| $2^{\text {nd }}$ order <br> scheme | -1.9911322 | 0.443\% |
| $3^{\text {rd }}$ order <br> scheme | -1.9920387 | 0.398\% |
| $4^{\text {th }}$ order <br> scheme | -1.9924314 | 0.378\% |
| $5^{\text {th }}$ order <br> scheme | -1.9926366 | 0.368\% |

Table 5. Comparison of Computed Corner Vorticity

The fifth-order scheme developed in this work is expected to work well with both uniform and clustered grids. Typically, uniform grid in the physical domain is chosen such that $y_{j}=-y_{j}{ }^{*}$ for uniformly varying values of $y_{j}{ }^{*}$. Non-uniform grid in the physical domain can be accomplished in various ways, including the use of elementary functions such
as $y_{j}=-\sqrt{y_{j}{ }^{*}}, y_{j}=-\sqrt[3]{y_{j}^{*}}, \quad$ and $y_{j}=-\left(y_{j}{ }^{*}\right)^{2}$, for uniformly varying values of $y_{j}{ }^{*}$. These functions produce different clustering near the flow domain boundaries, as discussed in [1]. In using these functions, Hamdan, [1], showed that in a fourth-order accurate scheme, they produce results closer to the actual solutions. Similar conclusions are expected in using the current fifth order scheme.

## 7 Conclusion

A fifth-order accurate finite difference scheme was developed in this work for use with transformed curvilinear coordinates. Non-uniform grid was used as it produced clustering near the boundaries in order to capture effects of the boundary. Scheme was used in computing corner vorticity. The fifth order accurate scheme developed I this work produced the most accurate results so far. In future work, focus will be on developing arbitrary order schemes for nonuniform grid.

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## Contribution of individual authors

Both authors conducted literature survey.
M.H. formulated the problem and provided analysis. Simulation and MATLAB work was conducted by I.G.

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